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Sammendrag, innholdsfortegnelse eller innholdsbeskrivelse ApendixB Reports on GPS survey Vakkerlien ApendixC Logistic Report 2005 UTEM survey Vakkerlien ApendixD In House UTEM Maxwell Modelling Vakkerlien

2 stk CDer ligger vedlagt: Vakkerlien GPS 2005 og 2005 UTEM Survey 0531 Data and Logistic Report

# 2005 Fall Ground Geophysical Program Vakkerlien Project

Hedemark County, Norway

P. Tirschmann Falconbridge Limited

On behalf of Sulfidmalm A/S

February 27, 2006

### SUMMARY AND CONCLUSIONS

This report gives the details and results of a ground geophysical program carried out on the Vakkerlien project in the fall of 2005. The project is located approximately 300km north of Oslo and 90km south of Trondheim in central Norway and is an option and joint venture between Sulfidmalm A/S (Norway), a wholly-owned subsidiary of Falconbridge Limited, and Blackstone Ventures Inc. (Canada). Exploration programs are carried out by Falconbridge Limited on behalf of Sulfidmalm.

The Vakkerlien project area is underlain by Gula group supracrustal and intrusive rocks within the central Norwegian Caledonides. This region host the Vakkerlien nickel deposit (400,000 tonnes grading 1.0% Ni & 0.4% Cu) as well as the Olkar and Kaltberget nickel occurrences.

In order to evaluate nickel sulphide potential in the Vakkerlien area, a 3,750 line km helicopterborne magnetic and frequency domain electromagnetic survey was contracted out to the NGU and flown in June of 2004. A ground follow-up and prospecting program was carried out during June and July of the same year. The airborne survey and ground follow-up identified areas of interest east and south of the Vakkerlien deposit and a ground geophysical program was subsequently planned.

The 2005 fall ground geophysical program was carried out during the period October 3<sup>rd</sup> to November 26<sup>th</sup>, 2005 and consisted of 50.45 line km of gridding and UTEM surveying. A bamboo picket grid was established by McKeown Exploration Services (Canada) using a differential global positioning system (DGPS), base station and repeater. Grids lines were spaced 100-200m apart. The UTEM surveying was carried out by Lamontagne Geophysics Limited (Canada). Measurements were taken at station intervals of either 25m or 50m depending on survey logistics and noise levels.

The UTEM survey identified a two-line UTEM response flanking the west side of the hook-shaped magnetic feature which is situated immediately east of the Vakkerlien deposit. In-house modeling by A. Watts outlined a UTEM plate with a conductance of 2000 siemens, a strike extent of 300m, a dip extent of 400m and a 53° east dip. This anomaly represents a viable drill target and drill testing is planned for 2006.

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## 1.0 Location, Topography and General Access

The Vakkerlien project area is located 300 km north of Oslo and 90km south of Trondheim in central Norway. The project is situated within Tynset kommune, Hedemark fylke and is easily accessible by car via the E6 and #3 highways north from Oslo or south from Trondheim (Figure 1).

The Orkla River transects the center of the project area and represents a prominent topographic low (440-700m) in the region. The ground rises steeply to the east and west of the Orkla River with local mountain peaks up to 1400m in elevation. Much of the project area has either open deciduous forest cover or is above the tree line. The Vakkerlien deposit is situated on a broad, relatively flat plateau just at the tree line with an average elevation of 900m. Elevation in the work area ranges from 750-1,000m.

Access to the field area is good via highway #3 and a well-developed system of secondary gravel roads and hiking trails. Tolls must be paid for access along many of the local gravel roads. The following two secondary roads were used to access the work area:

- road located approx. 6.5 km south of Kvikne extending west off of highway #3 past the Vakkerlien deposit (toll required)
- road located approx. 13.5km south of Kvikne extending west off of highway #3 and running along the north side of the Orkla river.

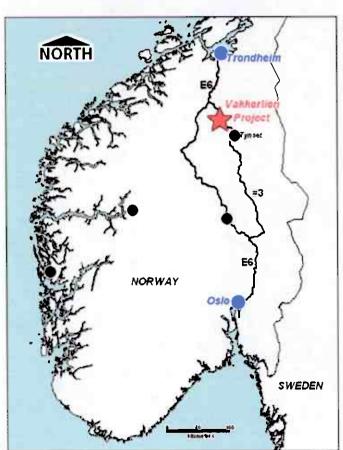


Figure 1 Vakkerlien Project – Location

#### 2.0 Land Access Issues

Land in the work area is held by private landowners as well as collective groups ("sameie"). Permission for the off-road use of snowmobiles was required from both the local kommune and the landowners. In addition, approximately half of the planned geophysical grid was situated within the Knutshø Landskapsvernområde or "landscape protected area" as shown in Figure 2. Although permission for the use of snowmobiles was received from Tynset kommune, use was restricted to pre-authorized access routes external to the Knutshø Landskapsvernområde. This significantly complicated the logistics of the ground work and added to the time and cost of surveying. In extreme cases, the survey equipment had to be moved manually by wheelbarrow or sled.

Kvikne Work Area Knutshø **Landskapsvernområde** Asf e let kilometre UTM WGS84 Zone 32N

Figure 2
Location of Knutshø Landskapsvernområde in Relation to Work Area

## 3.0 Property and Ownership

The Vakkerlien property, at the time the work reported herein was performed, consisted of 173 pre-claims or "mutinger" in three separate blocks collectively covering a total area of 50.1 sq km (Figure 3). (The claim block has since been reduced to 126 pre-claims totalling 36 sq km). The pre-claims are registered to Sulfidmalm A/S (Norway), a wholly owned subsidiary of Falconbridge Nikkleverk (Norway) which is owned by Falconbridge Limited (Canada). Exploration on the project is carried out under an option and joint venture agreement between Sulfidmalm A/S and Blackstone Ventures Inc. (Canada). Work programs are carried out by Falconbridge Limited on behalf of Sulfidmalm.

NOTE: Pre-claims owned by a third party over part of the Vakkerlien deposit were allowed to lapse in 2005 and, therefore, pre-claims registered to Sulfidmalm A/S now take precedence.

**Kvikne** NORTH Pre-claims **Outline of Pre-claims** 6937500 mN 6935000 mN 6932500 mN 6930000 mN 6927500 mN kilometers

Figure 3
Vakkerlien Project - Pre-claims

UTM WGS84 Zone 32N

### 4.0 Geological Setting

The Vakkerlien project is underlain by Gula group lithologies of the central Norwegian Caledonides. The Gula group forms the oldest part of the Trondheim nappe and is thought to be Proterozoic in age. Main lithologies include metasediments in the form of psammitic, pelitic, calcareous and graphitic schists as well as iron formations, metavolcanics (amphibolites), trondjemitic intrusions and occasional gabbroic to ultramafic intrusions. The metamorphic grade is middle to upper amphibolite facies.

A number of deposits are hosted in the Gula group including the Vakkerlien nickel sulphide deposit (400,000 tonnes grading 1.0% Ni & 0.4% Cu) discovered by Sulfidmalm A/S in 1974. The deposit is hosted in the core of a differentiated gabbroic to ultramafic intrusion and forms a plunging rod-shaped (10m x 40m) zone which can be traced laterally for 1,250m.

Other nickel occurrences in the area include the Kaltberget showing and the Olkar mine.

### 5.0 Previous Work

Past copper-zinc focused mining and exploration activity in the Kvikne-Tynset area is voluminous and a detailed summary is beyond the scope of this report. Abundance evidence of surface prospecting can be seen in the form of old pits and trenches.

Several older vintage airborne geophysical surveys flown at 200m line spacing covered portions of the current exploration area and include the following:

- 1974 helicopter-borne Sander EM-3 and mag survey
- 1979 helicopter-borne Sander EM-3, mag, radiometric and VLF survey
- 1981 helicopter-borne EM, mag and VLF survey

Sulfidmalm A/S initiated exploration in the area for Besshi-type VMS deposits in the early 1970's. This program included regional stream sediment sampling as well as prospecting and lithogeochemical sampling, the latter of which led to the discovery of the Vakkerlien deposit in 1974. During the course of sampling pits at the historical Vakkerlien showing for copper and zinc mineralization, Sulfidmalm obtained grab samples assaying up to 3.02% Ni. Subsequent work by Sulfidmalm concentrated on delineation of the Vakkerlien deposit and on exploration in the immediate vicinity as summarized in Table 1.A small amount of nickel-related exploration was also carried out concurrently at several other sites in the Kvikne area as summarized in Table 2.

Table 1
Summary of Work Completed over the Vakkerlien Deposit and Immediate Area

Period	Company	Description of Work
1975-1977	Sulfidmalm A/S	• 109 holes drilled and a resource of 400,000 tonnes grading 1.0% Ni & 0.4% Cu delineated using a 0.4% Ni cut-off
		<ul> <li>Metallurgical testing yielding a concentrate grading 15.5% Ni @ 80% recovery and 7.0% Cu @ 92% recovery</li> </ul>
1975	Sulfidmalm A/S	<ul> <li>Surface geophysical surveys including magnetics, VLF, Slingram, Mise-la-Masse, resistivity sounding and Turam to try and trace deposit along strike and down plunge to SE</li> </ul>
1979	Sulfidmalm A/S	Max-Min and Crone PEM test surveys
1991-1992	Folldall Verk A/S & Outokumpu (Norsulfid A/S) Joint Venture	<ul> <li>100 holes drilled on deposit on sections between Sulfidmalm holes to confirm resource</li> <li>Resource estimated to be 104,516 tonnes grading 1.73% Ni, &amp;0.55% Cu using a 0.5% Ni cut-off or 52,132 tonnes grading 2.55% Ni &amp; 0.80% Cu using a 1.0% Ni cut-off</li> </ul>

Table 2
Summary of Work Completed by Sulfidmalm A/S at Selected Locations in the Kvikne Area Prior to 2002

Period Area		Description of Work/Results		
1975-1976	Olkar	<ul> <li>Grab samples from dump pile taken; best sample assayed 1.5% Ni, 1.6% Cu &amp; 23.6% S</li> <li>VLF and magnetic survey</li> <li>Geological mapping and prospecting</li> <li>6 drillholes totaling 269.9m; best result of 1.78% Ni, 1.18% Cu and 22.5% S over 1.5m in DDH2</li> </ul>		
1976-1977	Kaltberget	<ul> <li>Geological mapping, ground mag &amp; VLF survey</li> <li>Discovered Grötberget showing with grab samples up to 2.1% Ni &amp; 1.12% Cu</li> <li>1976: 13 drillholes totaling 609.95m; best result of 1.60% Ni, 0.30% Cu &amp; 7.5% S over 5.5m in DDH12</li> <li>Surface and downhole charge potential surveys</li> <li>1977: 4 drillholes totaling 324.1m; best result of 1.55% Ni, 0.48% Cu &amp; 11.2% S over 0.5m in DDH 17</li> </ul>		
1977	Kletten	chip sampling (no significant values) and VLF survey		
1979	Regional	<ul> <li>helicopter survey; magnetic and single frequency</li> <li>(1000Hz) Sander EM data collected on 200m spaced lines</li> </ul>		

### 6.0 Recent Work by Sulfidmalm A/S

Falconbridge geologists made a reconnaissance visit to the Vakkerlien area in late 2002. In early 2003, Sulfidmalm acquired new pre-claims in the area and initiated nickel sulphide exploration, signing an option and joint venture arrangement with Blackstone Ventures Inc. in August 2003.

In June 2004, Sulfidmalm commissioned the Geological Survey of Norway (NGU) to fly a 3,750 line km regional helicopter-borne magnetics and electromagnetic (EM) survey. Data was acquired on east-west oriented flight lines spaced 150m apart with a nominal flying height of 60m above ground level. The EM system used was the 5-frequency Geotech Ltd. Hummingbird system. A ground EM follow-up and prospecting program was carried out during June and July 2004. The preceding work is described in Tirschmann (2005).

The airborne survey identified a number of strong, laterally continuous EM conductors typically associated with strong magnetic highs and occurring in the central and eastern portions of the survey block. Field checking of a number of these anomalies found them to be associated with sulphidic and/or graphitic metasediments.

The northwestern portion of the airborne survey block was characterized by subtle EM conductors and more discrete NW-SE and N-S striking magnetic highs superimposed on a rather featureless low to moderately magnetic background. All of the well-known nickel occurrences (Vakkerlien, Olkar & Kaltberget) were observed to be situated within this geophysical domain. Ground follow-up and prospecting on one 300m long EM anomaly in the immediate area of the old Olkar mine found the anomaly to correlate with apparent sulphidic sediments assaying 0.62% Ni, 0.53% Cu, 0.13% Co, 0.02 g/t Pt, 0.08 g/t Pd & 19.1% S. The new airborne data also showed the presence of weak EM conductors correlated with a subtle 1km long magnetic trend in the Kalberget area.

In the vicinity of the Vakkerlien deposit, the new airborne survey detected only weak EM anomalies. However, several interesting magnetic anomalies were identified including the following:

- a NW trending hook-shaped magnetic anomaly situated immediately east of the Vakkerlien deposit, possibly representing a folded extension of the host intrusion
- a large (1.5km x 2km) magnetic high located 1km south of Vakkerlien
- 2<sup>nd</sup> large (0.7km x 1km) magnetic high with a coincident subtle EM response located 3km SE of Vakkerlien

Field-checking of these magnetic features was hampered by thick overburden. However, boulders and float of altered ultramafic rocks were found at the anomaly situated 1km south of Vakkerlien. The two large magnetic features were postulated to represent ultramafic intrusions, potentially related to the same magnatic system which formed the Vakkerlien deposit. A ground UTEM (University of Toronto Electromagnetic System) survey was subsequently planned to test all three magnetic features.

Ground follow-up in the Olkar and Kalberget areas, though merited, was deferred due to complicated logistics, challenging topography and limited in-house resources.

## 7.0 2005 Fall Ground Geophysics Program

During the period October 3<sup>rd</sup> to November 26<sup>th</sup> 2005, a fall work program consisting of 50.45km line km of gridding and UTEM geophysical surveying was carried out (Figure 4). A list of field personnel involved in the program can be found in Appendix A.

### **Grid Preparation**

The grid was established by McKeown Exploration Services, with the help of Falconbridge and Sulfidmalm personnel, between October  $3^{rd}$  and October  $16^{th}$ . The gridding team consisted of one operator and two helpers. Gridding was accomplished using a real-time differential global positioning system (DGPS) and local base station  $\pm$  repeater. DGPS control was used on both the grid and the geophysical loops in order to provide the location and elevation (x, y & z) accuracy required for detailed geophysical modelling.

The grid variably consisted of N-S and E-W oriented lines spaced 100-200m apart with stations set at 25m intervals along each line and marked by thin bamboo pickets (Figure 5). The grid reference system used was UTM WGS84 (zone 32N). For ease of labelling both in the field and with respect to data handling, the first two and three digits, respectively, were dropped from the eastings and northings of grid locations (e.g. 566750E & 6931700N would be referred to as "6750E & 1700N").

All gridding was carried out on foot due to a lack of snow. Bamboo pickets were collected in November upon completion of the UTEM surveying in order to return the survey area to its original state.

Appendix B consists of a detailed report by McKeown Exploration Services on the fall 2005 DGPS surveying and grid work. Documentation and data are also given in digital form on an accompanying CD.

### UTEM Geophysical Surveying

Lamontagne Geophysics Limited carried out 50.45 line km of UTEM survey between November 3<sup>rd</sup> and November 26<sup>th</sup> (Figure 6). The UTEM crew consisted of two Lamontagne operators, one Lamontagne helper and two Falconbridge/Sulfidmalm helpers. Surveying was carried out on foot but snowmobiles were selectively used to help move people and equipment as needed. The inability to use snowmobiles within the Knutshø Landskapsvernområde resulted in more time-consuming "manual" forms of haulage (Figure 7).

Surveying was conducted using five large transmitter loops consisting of narrow gauge copper wire. Data was collected in both "off-loop" and in-loop configurations on 100-200m spaced lines at station intervals of either 25m or 50m depending on survey logistics and noise levels. Loop 2a was only used to survey the northern extensions of L670E and 671E where additional data was required.

Appendix C contains a detailed logistical report by Lamontagne Geophysics on the fall 2005 UTEM surveying. Included are a description of the survey logistics and methodology and a full listing of the UTEM profiles. Documentation and data are also given in digital form on an accompanying CD.

## 8.0 Results of 2005 UTEM Survey

UTEM responses were obtained at several locations throughout the grid, one of which merited more detailed modeling. Results are summarized as follows:

### Loop #1:

- UTEM responses on L336N and L337N @ approximately 5950-5975E, flanking the west side of hook-shaped magnetic feature east of Vakkerlien deposit. Data from L336N was modeled in-house by A. Watts and outlined a UTEM plate with a conductance of 2000 siemens, a strike extent of 300m, a dip extent of 400m and a 53° east dip (see Figure 8 & Appendix D). The ability to extend UTEM coverage to the north is limited by the presence of a NE-SW trending power line.
- UTEM responses on L334N (@ ~5730E), L335N (@ ~5635E) and L336N (@ ~5540E) which can be correlated with the Vakkerlien deposit. Coupling was probably not optimum for "seeing" the deposit as the position of Loop #1 was optimized for surveying over the hook-shaped magnetic feature to the east rather than for the well explored deposit area. It should also be noted that the data was relatively noisy on the west end of the loop #1 lines due to the power line which transects the extreme NW corner of the grid.

### Loop #2:

• Early channel, low conductance response on L669E and L670E @ approximately 2600N.

### Loop #3:

No UTEM responses

### Loop #4:

• Early channel, low conductance response on L292N @ approximately 7950E.

The UTEM anomaly modeled on L336N represents a viable drill target and should be drill-tested. No further work is recommended elsewhere on the grid at this time.

Figure 4
Vakkerlien Project – 2005 UTEM Grids and Loops

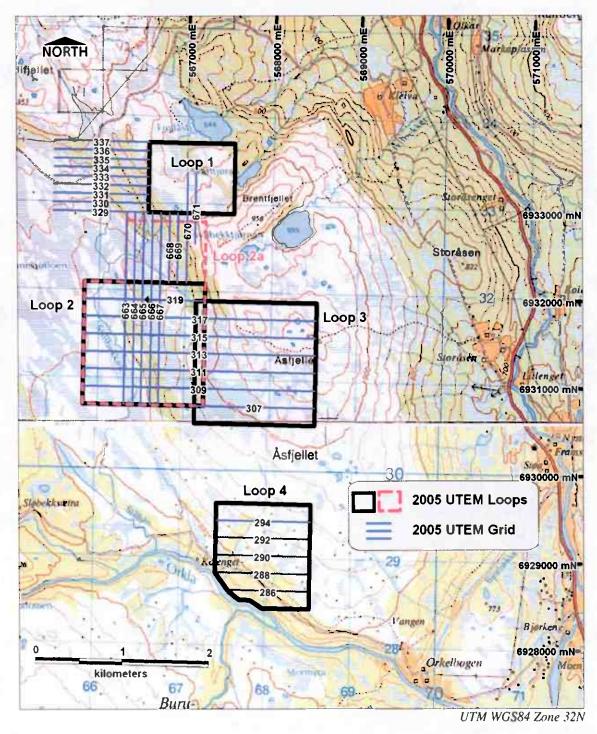


Figure 5: Establishment of DGPS-controlled Grid

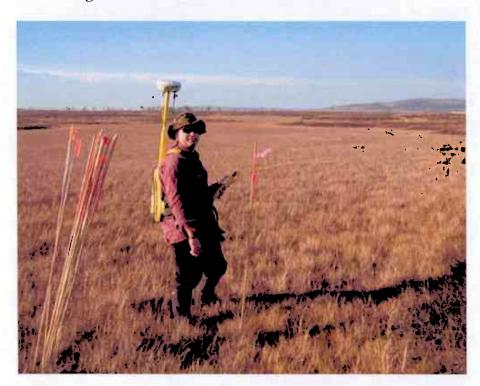


Figure 6: UTEM Surveying



Figure 7
Manual Transport of UTEM Survey Equipment





MACION Project (Multiple Plates) : 1 Preferences Model Project Model Save / Load Draw Process View "李宝女父女 脸里 好心众才回回回回回 "古四只千只只 不不不 益命 Aves / Grids Disp. Chans. Lighting Drill Planner Plates Add Delete 35 Flip Copy Colour Calc Auto Calc
Thick Ft. ✓ Use In Auto Scale 40030000 Smidale Oserburden No DB Simulation 400 Lithology None Reference Point 20070 Centre Top of Plate Ancore £ 565965 31 ✓ 5.0 N 6933650 50 P932'90'04F ₹ 50 Z 23.069 Grientation 0 126 763 25 -200 00 270 25 25 Rot 0 () mension SL 300 DE 412 906 Electrical CT 2000 Ri 10 Sk 1 Invession Channels End 5 Plate Boxdes Th Style 0.2 Solid Ribbons Th Style 0.1 Dash Plate Infersection w 666076 35

View Azimuth | 161.0, Inclination | 29.0, Render Time | 45ms

Figure 8
Maxwell Model for Loop 1, Line 336N UTEM Plate

# 9.0 References

Tirschmann, P.A., 2005

Vakkerlien Project Report on 2004 Work Program: Airborne Geophysics & Ground Follow-up, Hedemark County, Norway, Falconbridge Limited for Sulfidmalm A/S, April 10, 2005.

### APPENDIX A LIST OF FIELD PERSONNEL

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McKeown Exploration

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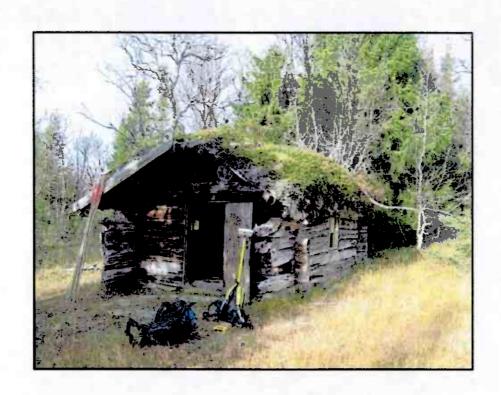
REPORT ON GPS SURVEY

FOR FALCONBRIDGE LTD.

VAKKERLIEN PROECT

TYNSET KOMMUNE, NORWAY

OCTOBER 2005



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### 1 Introduction

On 04 October, 2005, a crew was mobilised from Oshawa, Ontario to Falconbridge's Vakkerlien Project in the Tynset province of Norway, 175km south of Trondheim, to fix the position of an exploration grid in three dimensions using Global Positioning System (GPS) satellite receivers. The work was carried out by McKeown Exploration Services of Oshawa, Ontario.

## 2 Background

## 2.1 GPS General Theory

The Global Positioning System (GPS) is a network of twenty four earth orbiting NAVSTAR satellites (SVs) operated by the United States Department of Defense. The satellites orbit the earth every twelve hours at an altitude of approximately 20,200km. Four SVs orbit in each of six different planes inclined at 55deg to the equator, they provide constant positioning and time information by means of radio signals broadcast from each satellite.

Each GPS satellite broadcasts two radio signals known as L1 and L2 (1575.42 MHz, 1227.6 MHz). The L1 signal is modulated with two pseudorandom noise (PRN) ranging codes; P-code, and C/A code. The precision or P-code can be encrypted for military use, while the C/A code is not encrypted. The L2 signal is modulated with the P-code only. Most GPS receivers make use of the L1 signal only, while some survey grade GPS receivers take advantage of both

The US Department of Defense tracks each of the satellites continuously, constantly monitoring and calculating the exact path of the satellite. The exact path of the satellite, as well as atomic clock correction coefficients (each satellite contains several very precise atomic clocks) are broadcast to the satellite daily, this information (called the Broadcast Ephemeris and Almanac) is rebroadcast by each SV and used by the GPS receiver on the ground.

The GPS receiver is capable of receiving signals from several different satellites at once. The incoming code from the satellite contains information regarding the identity of each SV. The receiver calculates the distance that it is from the satellite by looking at the incoming code from the satellite, and then looks at how long ago it (the receiver) generated the same code. The difference in time is multiplied by the speed of light to give the distance, and through the use of triangulation, an exact position of the receiver antenna can be calculated.

### 2.2 Errors in the GPS Position

The calculated GPS position assumes that light travels at a constant speed, unfortunately this is only true of light travelling in a vacuum. When the GPS signal enters the Earth's atmosphere, the signal is slowed down by both the ionosphere and the troposphere, which may result in incorrect distance calculations. This effect is minimized by calculated correction factors that are broadcast with the Broadcast Ephemeris.

Multipath can be another significant source of error in the calculated GPS position. If the satellite signal is reflected off of objects in close proximity to the GPS receiver, it can interfere with the straight-line signal coming from the satellite, slowing the signal down and "confusing" the GPS receiver. This type of error is more common in areas with man-made cultural influence, such as large buildings, and generally is not a factor in the wilderness setting.

Until recently, the largest single source of error was known as "Selective Availability", or the intentional degradation of the GPS signal by the US Department of Defense, it may cause an error in the horizontal positions of the receiver of more than 100m. In the Spring of 2000 the US government removed Selective Availability, as a result, a standard off-the-shelf single frequency GPS may now yield a horizontal position with a +/- 5m precision.

### 2.3 Real Time Differential Correction and WAAS

The technique of Real Time Differential Correction (RTC) greatly increases the accuracy of the GPS position and helps minimize the effects of atmosphere, multipath, and selective availability. It employs two GPS receivers, one placed at a known location (the base) and one at an unknown position (the rover). The data collected at the base are used to determine the error in the GPS position, this error is in turn broadcast, through the use of an FM/UHF band radio-modem, to the rover unit and used to remove the errors in the position at the unknown location in real-time.

Using a single frequency GPS receiver (L1 only), with a base-rover separation (base-line length) of less than 10km can yield real-time sub-meter accuracy in both horizontal and vertical position, while use of a survey grade dual frequency L1/L2 GPS receiver can yield real-time 2cm-5cm accuracy in both horizontal and vertical positions.

WAAS, or Wide Area Augmentation System, is a real-time differential correction system implemented and operated by the American FAA (Federal Aviation Authority) for use in GPS aided navigational approaches for aircraft. The system employs a broad network of GPS base stations over the continental United States, the data from which is broadcast by satellite. This differential correction is broadcast on the same frequency as the Navstar signal. Specially equipped GPS

receivers are able to apply this correction in real-time to yield a real time position with <2 metre accuracy.

EGNOS is the European equivalent to WAAS.

## 2.4 Postprocessed Differential Corrections

Similar to the RTC method described above, data can be corrected after-the-fact by collecting data at a base station, and simultaneously collecting data at the rover unit. The data can then be downloaded from the GPS receiver to a computer and "post-processed" to give a differentially corrected position. This is useful in "fixing" base station positions from known geodetic control points where base-rover separation is in excess of 10km (the range of the FM radio modem). The amount of data collected (i.e. the time spent "occupying" a station) to produce a precise position is proportional to the base-rover separation. A general rule of thumb for rover occupation time is fifteen minutes plus one minute for every kilometer over ten kilometers base-rover separation, i.e. a base-rover separation of 100km should be occupied for 15min + (100km- 10km) \* 1min / km = 15min + 90 min = 105 minutes.

Post-processed single frequency data can yield 10-15cm precision, while survey grade dual frequency receivers can yield up to part-per-million precision.

## 2.5 Dilution of Precision (DOP) and Elevation Mask

The DOP is a measure of the geometry of the satellites relative to each other. The best possible position fix, or most accurate, will be possible when the geometry of the satellites is such that the satellites are within range, but as far apart from each other as possible. A low PDOP (position DOP) indicates that the geometry of the satellites, relative to each other, is good for a triangulation fix. If the SVs are close to each other, or are lined up, then the geometry will be poor for triangulation, and the PDOP will be higher. A PDOP less than 4 gives the best position fix, 5-8 is marginally acceptable, and 9 or over is poor. Generally a PDOP mask (or filter) is applied so that if the PDOP is over a certain level (6 is the maximum for this particular survey), then a reading is not possible.

A minimum of four satellites are generally required to give an accurate position fix. The GPS system used for this particular survey uses a proprietary algorithm called "Over-Determined 3D", which requires at least five common base/rover SVs to compute a position fix.

The elevation mask is a user entered angle filter which will tell the GPS to ignore all SVs within the zero degree above horizon to elevation mask range. When satellites are low on the horizon, the signal is forced to travel farther through the atmosphere, and the low angle of incidence means signals reflect off of objects

more readily and the multipath error is increased. The elevation mask for this survey is 13°.

## 3 Mobilization and Equipment

### 3.1 Mobilization

On 04 October, 2005, a crew was mobilised from Oshawa, Ontario to Falconbridge's Vakkerlien Project in the Tynset province of Norway, 175km south of Trondheim

The crew, which included the author, and two representatives from Falconbridge Ltd stayed in the Hogstad Campground ten kilometers north of the survey areas just off of highway 3. Access to the Vakkerlien project was by pick-up truck via two farm access roads just south of Vikne. The grid was accessed on foot



Figure 3.1.1 - Location Map



Figure 3.1.2 - Location Map

# 3.2 Equipment

All GPS equipment was rented by the author on behalf of Falconbridge. Two Trimble dual frequency geodetic grade GPS receivers were employed, one Trimble model 5700 and one model 5800 receiver, along with a Trimble 25 watt base station radio modem, and a similar 25 watt Trimble radio acting as a modem repeater (see Appendix D for specifications).

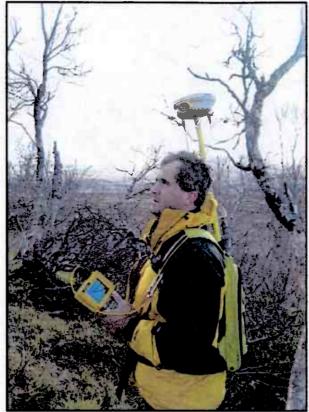


Figure 3.2.1 - Author with Trimble 5800 GPS system

## 4 Survey Procedure

### 4.1 The Local Grid

The local grid was originally designed and oriented to produce lines perpendicular to the geological trend or strike. Grids followed universal transverse mercator (UTM) projection gridlines, lines were running either north-south, or east west. Magnetic declination in the survey area is zero, so magnetic north and grid north are essentially the same.

The World Geodetic System 1984 (WGS84) UTM reference system was chosen by Falconbridge as the default coordinate system. The Survey area was located in UTM zone 32V.

Lines were placed at either 100 metre or 200 metre intervals, with a station spacing of 25 metres.

## 4.2 GPS Base Station and Repeater

On 06 October 2005, the real-time GPS base station was erected at government geodetic control point known as G27T0222 "Storinnsjoen" which was chosen due to it's central location to the grid and easy walk-in access.

GPS occupations were observed at two other government control points, "Vakkerlifjell" and "Slobekksetera" for comparison, readings were within +/- 2 cm of the published coordinates.

Point V999 was established relative to G27T0222 by static occupation of site for 15 minutes. Over the course of the survey, G27T0222, V999, and G27T0223 were used as GPS base stations.



Figure 4.2.1 - GPS Basestation SLOBEKKSETERA

ID	Name	UTM_N	UTM_E	Elev.
G27T0065	Asfjell	6931463.775	568571.041	970.249
G27T0136	Vakkerlifjell	6935786.254	565601.417	989.559
G27T0222	Storinnsjoen	6933997.854	564379.512	879.776
G27T0023	Slobekksetera	6929262.312	565619.475	809.177

Figure 4.1.1 - Coordinates of published government control points, ETRS89.

ID	UTM_N	UTM_E	Elev.
V999	6933842.725	566311.650	900.489

Figure 4.1.2 - GPS Base derived from static occupation of G27T0222

The published geodetic control point coordinates are in the ETRF89 (or EUREF89) coordinate system, or European Terrestrial Reference Frame. The Norweigan government agency "Statenskart" which is responsible for geodetic control points in Norway responded to an inquiry on the definition with the following: "...EUREF89 is apparently very close to WGS84, the difference is in the order of 20-30cm".

This statement, combined with the evidence from the comparison of the coordinates obtained from the test, provided enough support for keeping WGS84 without any detrimental effects.

WGS84 elevations and coordinates were used for the duration of the survey.

A GPS repeater was used on various days when signal propagation was RTK signal was obstructed

## 4.3 The Survey

The Trimble 5800 RTK GPS was used to navigate from one ideal station to the next, Falconbridge personnel then placed a labeled bamboo picket at the station. Periodically it was not possible to place the real station at the ideal station location due to trees or topographic obstruction, in such instances the station was moved away from the ideal by up to 5 metres. The station was then staked out, i.e. the real location and elevation observed and recorded in the GPS data controller.

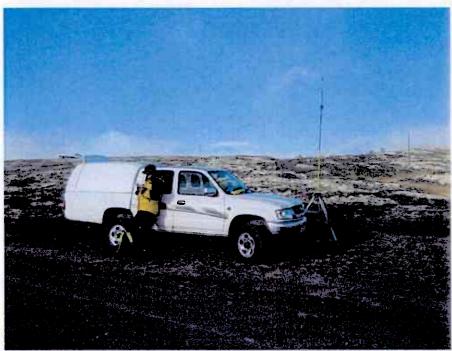


Figure 4.3.1 GPS Repeater set up next to road

The GPS antenna was placed on the GPS backpack, which was 2.04m above ground level (see figure 4.3.1).

The GPS fix, depending on the Dilution of Precision (DOP) value was usually obtained with 3 readings (one per second) taken over the course of at least 5 seconds. If DOPs were low, (<6.0) then a shorter reading was possible, if high (>6.0), then generally a longer observation was necessary to obtain the desired precision, normally less than one minute.

Initially, the desired precision was set to 5cm. This was later changed to 20cm metre L1/L2 fine initialisations due to time limitations and the fact that tree cover was causing lengthy L2 or "Fine initialization". The initialization type is displayed in the attached data file in column 9, a "F" indicates fine or L1/L2 high precision observation (+/- 5cm), and a "C" indicates course or L1 only float observation (+/- 1m).

All observations were "F" or fine high-precision initializations on this survey

Readings were stored in the hand-held GPS computer and downloaded nightly to a laptop computer. Trimble Geomatics Office Version 1.6 (TGO) software was used to transfer and decode binary data. Data were exported from TGO into ASCII format, which was then imported in Excel. An master Excel spreadsheet was created and contained all merged data (see Appendix A).

The production GPS survey was started 07 October 2005, and completed 17 Oct 2005 (see Appendix C for details on daily progress).

The GPS was also used to fix the positions of all UTEM Loop wires to be used by Lamontagne Geophysics. Four loops were surveyed (1-4) with position fixes taken every 100m, or at any line or elevation break (see Map 7.1).

## 5.0 Quality Control

To maintain a quality data set, and to test the manufacturer's claim of error/precision, as many random repeats were taken as time would allow. The results of the repeats are outlined below (see Chart 5.0.1).

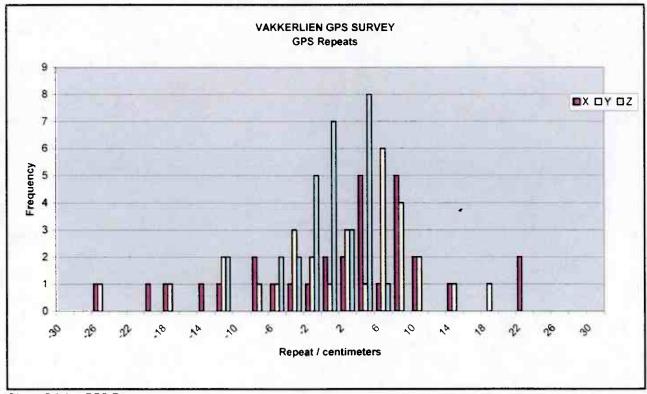


Chart 5.0.1 - GPS Repeats

Chart 5.0.1 illustrates that the precision is as expected (sub-metre). The average of the absolute Z repeat value is 3.4cm, with the standard deviation (single population) of 3cm. This implies that if the number of repeats is statistically significant, and approximates a normal distribution, 68% of the readings should have an error in elevation of 3cm or less (one standard deviation), and 95% should have an error less than 6cm (two standard deviations)

As the error is random as far as being positive or negative in value, the absolute value is considered when calculating averages.

Only 30 repeats were considered for approximately 1825 stations, or 1.6%. Ideally 5-10% should be randomly repeated for a survey of this size.

### 6 Comments

## 6.1 Comments on Satellite Geometry

During the course of a survey day, three significant time periods were observed where satellite geometry was less than ideal; around 8:00-8:45, 10:30 to 11:30, 13:15-14:00. During these times it became apparent early in the survey that readings taken in the trees would be difficult to obtain as satellites were either very low on the horizon, or all available satellites were grouped directly overhead and geometry was not favorable for triangulation. With proper planning, usually a survey crew can plan to be working in the clear open areas during these times.

Appendix E contains plots of sample satellite geometry for 05 October 2005 and again for 17 October 2005. Bad times can be seen to shift back in time approximately 30 minutes over this period.

The charts in Appendix E shows number of satellites and PDOP plotted against time. Periods of 5 satellites or less, or a PDOP greater than 4 can be difficult times to survey. Obstructions such as mountains or trees can significantly block satellites from the view of the antenna.

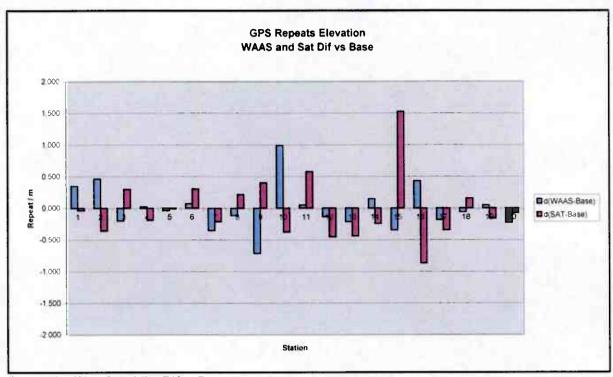


Chart 6.2 - WAAS and Sat Dif vs Base

On the final day of surveying, a test was done to compare observations made using two different types of differential correction.

A section of line was chosen that was previously read using the high-precision geodetic grade GPS system using a base station, these values for the sake of the test were assumed to be the "most correct" coordinates for each station. The stations were re-read using both Falconbridge's Trimble Pathfinder PRO XRS which uses the Fugro Omnistar satellite differential correction system (paid subscription service), and the Trimble 5800 system configured in WAAS/EGNOS mode (free aviation-approach service).

The relative change from one station to the next was compared to the change observed with the geodetic system and plotted above. The chart above indicates that both systems are providing typically submeter precision. The Omnistar system appears to have one repeat in excess of 1m.

The WAAS/EGNOS system was significantly slower in the trees owing to the fact that the differential correction satellite was low on the horizon during the test and lost easily while walking in the trees.

It is doubtful that enabling the WAAS/EGNOS option on Falconbridge's GPS would offer a significant advantage, and could possibly slow down production while working in the trees.

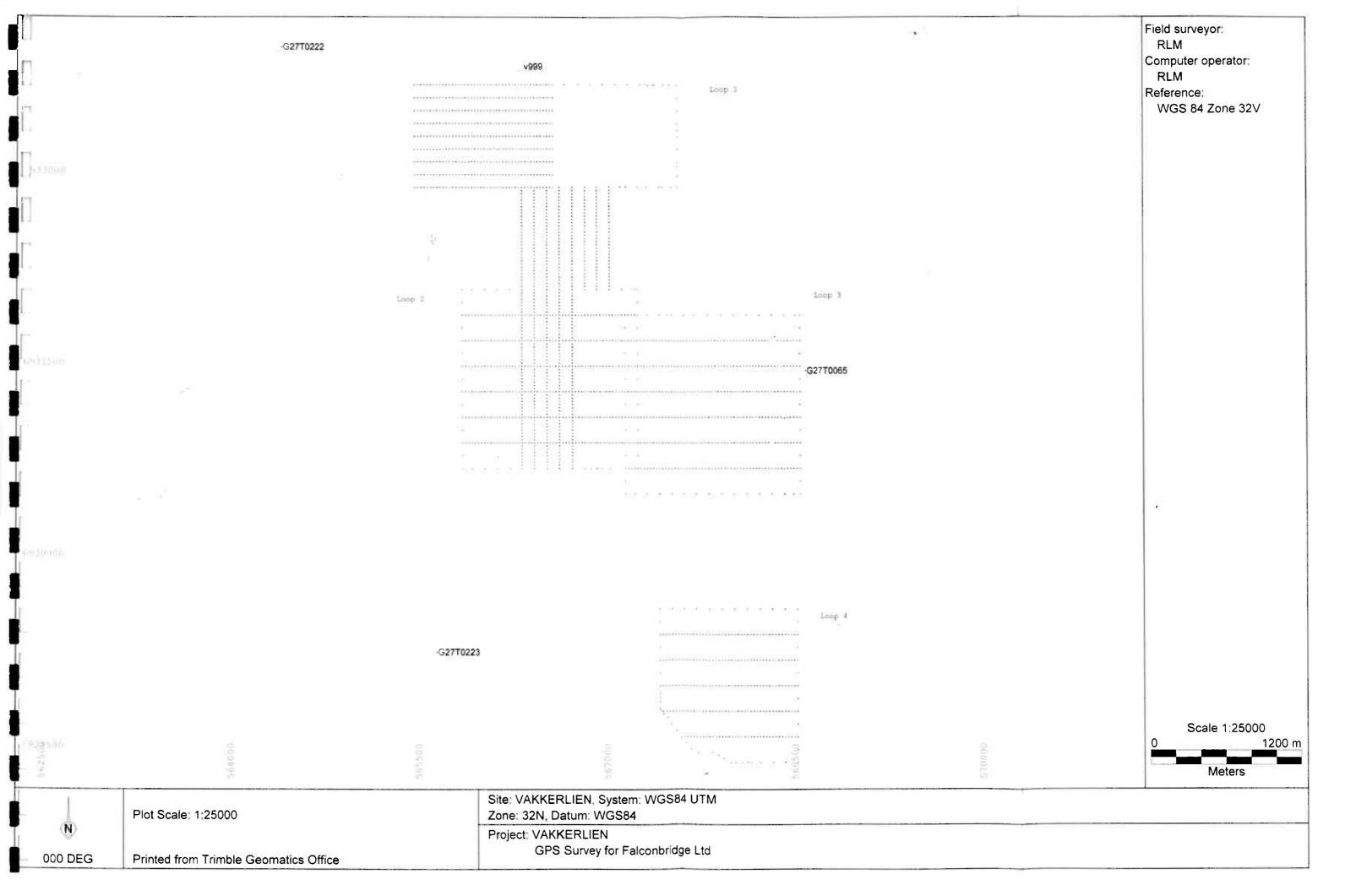
The most robust method of improving Falconbridge's Pathfinder system would be to use it in conjunction with a local RTK GPS base station

#### 6.3 Elevation

It was noted that the Falconbridge GPS was collecting data with elevations significantly different than those indicated on the topo maps and geodetic control points, this is probably owing to the difference in ellipsoid vs geoid height. The data presented in this report is in agreement with the local topo maps and geodetic control. Over such a small survey area the lateral variation is quite small (~20cm) and heights could be adjusted by a simple addition/subtraction of 42.320m, this is the average separation as indicated in the datasheet supplied by the government of Norway (see Appendix)

Respectfully Submitted

Robert L. McKeown, B.Sc. 2005-10-28



#### Appendix A Data CD Information

The attached data CD contains all raw and processed data collected. Raw Trimble binary files are located in the directory:

#### \GPS\RAWDATA

and are only readable with Trimble Geomatics Office. All binary files were decoded and exported as ASCII text files, then imported into the excel spreadsheet vakkerlien.xls Geosoft space delimited xyz data was exported from excel and saved in the folder:

#### \GPS\XYZ

UTEM loops' GPS data are located in the directories:

#### \GPS\LOOPS

The figure below is a sample of the final data format (Geosoft XYZ) located in the master spreadsheet:

#### \GPS\XYZ\vakkerlien.xls

NGPS/XYZ/Vakkerilen.xis										
/GPS Survey for Falcon birdge Ltd										
Wakkerlien Project, Norway										
/UTM_E UTM_N	ID Elevicat Lor	ng Precision	Date GMT	Time Line Sta	ition	П				
/WGS84 Zone 3									1	
1										
Line	286,000									
567599.975	<b>6</b> 928800 <b>02</b> 1	28658 <b>7600</b>	759.205	62.48232784	10.31147977	F	051016	1409	286	567600
567624.234	6928800.455	286587625	764.034	62.48232731	10.31195043					
567650.022	<b>6</b> 928500 050	286567650	764.991	62.48231898	10.31245042	F	051016	1402	286	567650
567674.961	6928500 019	286567675	771.257	62.48231416	10.31293409	F	051016	1400	286	567675
567699.951	<b>69</b> 28599 961	286567700	772.645	62.48230908	10.31341873	F	051016	1359	286	567700
567724.983	6925559 987	286567725	775.069	62.48230474	10.31390423					
567749.534	6928599 988	286567750	776.886	62.48230027	10.31438038	F	051016	1356	286	567750
567774.927	6928600 009	286567775	779.730	62.48229581	10.31487287	F	051016	1354	286	567775
567799.431	6928600.032	285567800	780.979	62.48229155	10.31534813	F	051016	1353	286	567800
567824,148	6928599 458	286567825	775.109	62.48228188	10.31582728	F	051016	1349	286	567825
567850.019	6928600.047	286557850	781.172	62.48228243	10.31632926	F	051016	1345	286	567850
567875.007	<b>6</b> 928600 021	288567875	786.176	62.48227763	10.31681388	F	051016	1344	286	567875
<b>56</b> 7899.866	<b>6</b> 926600.010	286567900	787.469	62.48227298	10.31729601	F	051016	1342	286	567900
567924,854	6928800 065	288567925	785.412	62.48226891	10.31778065	F	051016	1341	286	567925
567950.134	6928600 011	288597950	790.578	62.48226379	10.31827093	F	051016	1340	286	567950
567975.050	6928599 931	286567975	792.451	62.48225851	10.31875413	F	051016	1339	286	567975
567999.908	6928600 <b>09</b> 1		793.272	62.48225539	10.3192363	F	051016	1336	286	568000
<b>56</b> 8024.935	<b>6</b> 928600 <b>016</b>	288568025	795.606	62.48225013	10.31972164	F	051016	1334	286	568025
568050.014	6928800.111	288588050	795.772	62.48224638	10.32020807	F	051016	1333	286	568050
568075.625	<b>6</b> 928500.1 <b>27</b>	286568075	797.436	62.48224182	10.32070481	F	051016	1331	286	568075
568100.048	6928599.931	286568100	799.618	62.48223559	10.3211784	F	051016	1327	286	568100
568124.963	6928599 994	286568125	801.052	62.48223158	10.32166163	F	051016	1327	286	568125
568149.974	6928589 967	288568150	802.079	62.48222674	10.32214669	F	051016	1326	286	568150
568175.051	6928599 964	286568175	803.915	62.48222211	10.32263304	F	051016	1325	286	568175
568200.113	6925500 027	285568200	805.575	62.48221806	10.32311913	F	051016	1324	286	568200
568225.024	<b>6</b> 928593 <b>980</b>	286568225	806.417	62.48221307	10.32360223	F	051016	1323	286	568225
568249.921	6928599 970	286568250	808.130	62.4822084	10.3240851	F	051016	1322	286	568250

Figure A.1 – Sample Data

## GPS Survey for Falconbridge Ltd. Vakkerlien Project - GPS Repeats

Reading 1				Reading 2				Repeat					
X1	Y1	STAT1	<b>Z</b> 1	X2	Y2	STAT2	Z2	dX	dY	dΖ	+dX	+dY	+dZ
566300,065	6930899.949	663930900	802.834	566300.087	6930900.141	309566300	802.813	-2.2	-19.2	2.1	2.2	19.2	
566300 025	6931099.949	663931100	803,011	566299,952	6931099,898	311566300	802.972	7.3	5.1	3.9	7.3	5.1	3.9
566300.024	6931300.024	663931300	802 526	566300.065	6931299.983	313566300	802.519	-4.1	4.1	0.7	4.1	4.1	0.7
566599.862	6931299.549	666931300	829.679	566599.822	6931299.558	313566600	829.668				4	0.9	
566700.116	6931300 056	667931300	828 332	566700.079	6931300,113	313566700	828,309	3.7	-5.7	2.3	3.7	5.7	
566300.098	6931499.937	663931500	812.567	566300,116	6931499.868	315566300	812.543	-1.8	6.9	2.4	1.8	6.9	
566600.033	6931500.091	666931500	820.519	566600.021	6931500.068	315566600	820.486	1.2	2.3	3.3			
566700.025	6931499.988	667931500	828.582	566699.969	6931499.986	315566700	828.556	5.6	0.2	2.6	5.6	0.2	
566299.976	6931700.022	663931700	817.247	566300.102	6931700.060	317566300	817.245	12.6	-3.8	0.2	12,6	3.8	
566399.994	6931700.054	664931700	815.725	566399,966	6931699.988	317566400	815.671	2.8	6.6	5.4	2,8	6.6	
566600.014	6931699 962	666931700	820.751	566599.936	6931699.830	317566600	820,719	7.8	13.2	3 2	7.8	13.2	3.2
566599 969	6931902.068	666931900	827.192	566600.066	6931902.059	319566600	827.153	-9.7	0.9	3.9	9.7	0.9	
566 <b>3</b> 00 <b>0</b> 38	6931900 006	663931900	812,882	566300.102	6931900.137	319566300	812.916	-6.4	13.1	-3.4	6.4	13.1	
566399 973	6930900.002	664930900	802 193	566399 948	6930900.098	309566400	802.197	2.5	-9.6	-0.4	2.5	9.6	0.4
566400.070	6931100.038	664931100	802,011	566399.858	6931099.981	311566400	802.072	21.2	5.7	-6.1	21.2	5.7	6.1
566399 956	6931300.032	664931300	816.086	566399.895	6931300.077	313566400	816.096	6.1			5.1	4.5	
566400 044	6931500.340	664931500	824.785	566399 827	6931500.268	315566400	824.823	21.7	7.2	-3.8	21.7		
566400,040	6931897.578	664931900	814.282	566400.057	6931897.522	319566400	814.402					5.€	
566500.102	6930899.659	665930900	804.215	566500.367	6930899.616	309566500	804.286	-26.5	4.3	-6.8			
566500 054	6931100,089	665931100	811,990	566500.243	6931100,048	311566500	812,004	-18.9	4.1	-1.2	18.9	4.1	
566500.045	6931299.933	665931300	824.691	566500,039	6931300.072	313566500	824.722	0,6	-13.9	-3.1			3.1
566500.005	6931499,930	665931500	823.116	566500.220	6931499.972	315566500	823.118	-21.5	-4.2			4.2	
566500.012	6931699.999	665931700	815.524	566499.942	6931699.985	317566500	815.539	7	1.4	-1.5	7	1,4	1,5
566499.979	6931899.850	665931900	826,155	566500.078	6931899.925	319566500	826.166	9.9	-7.5	-1,1			
566600.078	6930900.017	666930900	820.170	566600.046	6930899.936	309566600	820.298	3.2	8.1	-12.8	3.2	8.1	
566600.001	6931100.038	666931100	828 084	566599.925	6931099.869	311566600	828.106	7.0	16.9	-2.2	7.6	16.9	2.2
566699.954	6930899.816	667930900	840.363	566700.107	6930900,079	309566700	840.407	-15.3	3 26.3	-4.4	15.3		
566699 933	6931099,928	667931100	839.471	566699.797	6931099.866	311566700	839.512	13.6			13.€	6.2	
566700 094	6931700.120	667931700	830.126	566700.003	6931700.028	317566700	830.144	9.	9.2				
566699 997	6931899.926	667931900	830.072	566699.911	6931899.954	319566700	830.110	8.6	2.8	-3.8	8.6	2.6	3.8

Fred	Liency	Distribution

interval cm	X	y	Z
-30		0	- 0
-28	0	0	
-26	1	1	- 6
-24	0	0	0
-22	0		0
-20 -18	1	0	
-18	- 1	1	- 0
-16	0	0	0
-14	1	0	- 0
-14 -12 -10	1	2	- 2
-10	0		- 0
-8	2	1	- 0
-6	-1		2
-4	1	3	- 2
-2	1		5
2	) 2		
- 2	2 5	3	3
4	. 5		
		6	1
	5	4	
10	2	2	
12	0		
14	1	1	
16		0	
14 16 18	0		
20	0		
22	2 2	0	
24		0	0
24 26	6		
28	3	0	
30	0	0	1

count	30	3 3				
min	-26.5	-26.3	12.8	0.6	0.2	0.0
max	21.7	16.9	5.4	26.5	26.3	12.8
mean	0.1	-0.1	-1.3	8.8	7.3	3.4
stdev	11.4	9.5	4.3	7.1	5.9	3.0

## **GPS Survey for Falconbridge Ltd.**

## Vakkerlien, Norway October 2005 **Production Summary**

Date	Prod	S/B	M/D	Line	Station	Station	Length	Notes
05/10/04	Н		1	155%	From	То	255106.000	-p.m. RLM Departs Toronto for Norway
05/10/05			1					-p.m. RLM arrives Ir Vakkerlien
05/10/06		1						-a.m. setup base station at geodetic point G27T0222
								-checked against G27T0136 and G27T0223, aggrees with publised coordinates +/- 2cm x,y,z -base V999 established realative to G27T0222 at north end of survey area
								-base G27T0223 to be used for southern grid
05/10/07	1			66933700 66933600	5654 <b>50</b> 5654 <b>50</b>	56 <b>6550</b> 56 <b>6550</b>		-surveyed in norther grid -switched base battery at 3pm
				66933500 66933400	565450 565450	566000 566000		-bad PDOP/RMS for half hour at 11:00-11:30am
				66933300 66933200	565450 565450	565 <b>9</b> 75 566 <b>000</b>	525 550	
				66933100 66933000	565450 565450	566000	550 550	
TOTAL				66932900	5654 <b>50</b>		550 6025	
05/10/08	0.5	0,5		6933500 6933400	566025 566025	566550 566550		-worked a.mp.m. Rob Jones to Trandheim, not possible to work in field while driving him to airport
				6933300 6933200	56 <b>6000</b> 56 <b>6025</b>	566550 566550	550 525	
				6933100 6933000	566025 566025	566550 566550	525 525	친
TOTAL							3175	
05/10/09	7			6933000	566025			-rain and sleet all day
No.CO.				566300 5664 <b>00</b>	6930700 6930700	120 At 24 CT ALCOHOL: 14	2000	-survey controller locked up in afternoon at 4pm -radio link lost at south end of lines on south side of ridge, will move base station tomorrow
TOTAL							4725	-slow day!
05/10/10	1		$\neg$	566400	6932725			-moved base station to point G27T0222, to northwest to try to get better radio coverage to south
TOTAL	- 1			566500 566000	6930700 6930700	6932900 6932900	2200	-problem with radio coverage at north end of grid after moving base -returned to cabin to get repeater, installed on road near north grid centre
TOTAL							43/3	-no more problems with radio link for entire length of north south linesslow going in trees, satellites low on horizon
05/10/11	- 1	_	_	567000	6932900	6932100	800	- sunny day, no problems
				6931900 6931700	565825 565825	567225 568525	1400 2700	
TOTAL				6931500	565825	568525	2700 7600	A control of the cont
							C.0000	
05/10/12	1			566900 566800	6932900 6932900		800	-slow day today, all lines in trees -GPSed in south, west, north loop edge of Loop 2005-02
TOTAL				566700	6932900	6930700	2200 3800	CONTROL OF THE CONTROL OF THE STATE OF THE S
05/10/13	1	$\dashv$	$\dashv$	566900	6932900	6932100	800	
****		- 1		566 <b>80</b> 0 566700	6932900 6932900	6932100 6930900	2000	
TOTAL							3600	
05/10/14	_	_	_	6930900	566850	568525	1075	-GPSed in part of loop 2005-02
03/10/14	1	- 1		6931100 6930700	568375 567125	568525 568525	150 1400	-Groed III part of cop 2000-02
TOTAL		- 1		0000700	307120	300023	3225	
05/10/15	1	コ						-GPSed Loop 2005-03, 2005-04
				1				
05/10/16	-1	$\dashv$	$\dashv$	6929400	568500	567400		-all grids and loops complete today
				692 <b>9</b> 200 6929000	56 <b>8</b> 500 56 <b>850</b> 0	567400 567400	1100 1100	
0.000	- 1			6928800 6928600	5685 <b>0</b> 0 5685 <b>0</b> 0	567450 567600	1050 900	
TOTAL							5250	
05/10/17	1	$\dashv$						-carried out test/repeats using Pathfinder PRO XRS GPS with satellite differential correction and
								Trimble 5800 using WAAS
	- 1							-p m. demobed, travel Vakkerlien to Espadelen
05/10/18	_	4	4					-RM and LW to Oslo
our rui FQ								
TOTAL	10.5						41975	
LITTING	14.0						41313	H

## **TSCe Controller**

## The flexible data collector of choice

The TSCe™ controller is a rugged and adaptable handheld data collector. Running powerful Trimble field software on a Microsoft® Windows® operating system, TSCe provides exceptional control of Trimble GPS and optical sensors, whatever your surveying or construction application.

## Exceptional in the field even in extreme temperatures

The TSCe controller is the rugged data-collection solution that fits comfortably in your hand and in your field processes. And because it's designed to take the knocks and drops of the surveying and construction environment, the TSCe controller's ruggedness makes it a reliable and dependable member of your field crew. When you're out working long days, TSCe will keep on working right there with you.

In extremely cold temperatures, TSCe is more robust than ever before. With its new color touch screen, TSCe will easily operate in temperatures as low as -25 °C without the addition of an internal heater.

#### Full keyboard and touch screen

On the TSCe controller you can choose to drive your data collection software using the full alphanumeric keyboard, or via the easy-to-use color touch screen—TSCe enables you to use the method or method combination that provides you with the most efficient data control.

The instant results of the touch screen offer complete control over data and make light work of navigation, data selection, positioning, and stakeout.

#### Color graphic display

The color graphic display of the TSCe controller is clearly readable in a wide range of field conditions. The display's reflective LCD technology makes it easy to read in bright



sunlight, and it is front lit for when light levels are low, such as on dark winter days.

The color display makes not only simple text easier to read, but also complex maps and technical drawings. Having these graphics in colour right at your fingertips makes navigating and positioning much easier, and speeds up stakeout and data selection. Data management and quality assurance are also greatly improved. Because you can thoroughly check your data in the field, errors and omissions are minimized.

## în extreme temperatures

Exceptional in the field even

- Full keyboard and touch screen
- Color graphic display
- Large memory capacity
- Adaptable

#### Large memory capacity

The TSCe controller comes with 512 MB of CompactFlash memory as standard. This large storage capacity means that you can work with larger data files and background maps, and that you can work for longer in the field without backup storage.

Adaptable

The TSCe controller is designed to operate with all your Trimble sensors, including the Trimble® R7 and R8 GPS receivers with R-track technology, the 5700 and 5800 GPS receivers, and the 3600 and 5600 total stations. It also supports many major third-party total

stations. In addition, when the Trimble BlueCap module is used, Bluetooth® wireless technology provides cable-free communication with the Trimble R8 and 5800 GPS systems.



## **TSCe Controller**

#### The flexible data collector of choice

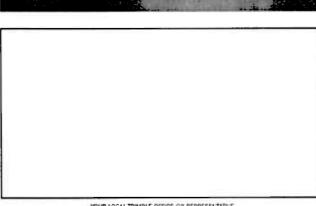
#### **Specifications**

Power	Internal 3800 mAh NiMH rechargeable battery pack ittery life of 30 hours under normal operating conditions Complete recharge in under three hours
Size	25.8 cm (10.2 in) × 13 cm (5.1 in) × 5.2 cm (2.1 in)
	7.4 cm (2.9 in) at handgrip
Weight	990 gm (2.2 lb) including battery
Certification	FCC class B, CE Mark, CSA, and C-tick approval
	9-pin serial port-RS232 (115 kB/s),
	COM1 with 5 V (250 mA) on pin 9
MultiPort 1/0	26-pin MultiPort-RS232, COM2, Ethernet 10BaseT,
WIN (************************************	USB client, power in/out and audio in/out
	0-Shell Lemo
	RS-232 (115 kB/s)
Processor	Intel StrongARM SA-1110 @ 206 MHz
	512 MB non-volatile flash disk; 64 MB SDRAM
	320 × 240 pixels (¼ VGA) reflective color TFT,
COTEL 4 SCOTLODGO	frontlight fluminated display
Touch Screen	Passive touch screen, works with stylus or finger
	57-key tactile action with separate navigation,
,	alpha and numeric keypads
Audio	Integrated speaker and microphone

#### **Environmental**

Temperature:	
Operating	25 °C to 60 °C (-13 °F to 140 °F)
	30 °C to 60 °C (-22 °F to 140 °F)
Water	ICE 529, IP 67, sealed against temporary immersion
Drop	1.22 m (4 ft) to concrete on all faces, edges and corners
Sand and Dust	ICE 529, IP 6X and MIL-STD-810E, Method 510.3
Vibration	MIL-STD-810E, I-3.4.9 category 10, Fig 16 and 17
	MIL-STD-810E, Method 500.3





YOUR LOCAL TRIMBLE OFFICE OR REPRESENTATIVE

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**Trimble** 

# **Trimble 5700 GPS System**

# One receiver, many configurations, for greater flexibility and choice

The Trimble® 5700 GPS receiver is an advanced, but easy-to-use, surveying instrument that is rugged and versatile enough for any job.

Combine your 5700 with the antenna and radio that best suit your needs, and then add the Trimble controller and software of your choice for a total surveying solution. The powerful 5700 GPS system will provide all the advanced technological power and unparalleled flexibility you need to increase your efficiency and productivity in any surveying environment.

#### Advanced GPS receiver technology

The 5700 is a 24-channel dual-frequency RTK GPS receiver featuring the advanced Trimble Maxwell™ technology for superior tracking of GPS satellites, increased measuring speed, longer battery life through less power use, and optimal precision in tough environments. WAAS and EGNOS capability lets you perform real-time differential surveys to GIS grade without a base station.

#### Modular design for versatility

For topographic, boundary, or engineering surveying, clip the receiver to your belt, carry it in a comfortable backpack, or configure it with all components on a lightweight range pole. With the receiver attached to your site vehicle, you can survey a surface as fast as you can drive! For control applications, attach the receiver to a tripod...it's designed to work the way your job requires.

#### Full metal jacket...and lightweight

The 5700 GPS receiver boasts the toughest mechanical and waterproofing specs in the business. Its magnesium alloy case is stronger than aluminum,



but also 30% lighter—the 5700 weighs just 1.4 kg (3 lb) with batteries. Whether you're collecting control points on a tripod, or scrambling down a scree slope collecting real-time kinematic data, the receiver is light enough and tough enough to carry on performing.

## Fast and efficient data storage and communications

Use the receiver's CompactFlash memory to store more than 3,400 hours of continuous L1/L2 data collection at an average of 15-second intervals. Transfer data to a PC at speeds of more than 1 megabit per second through the super-fast USB port. Your choice of UHF radio modem is built in to the receiver to provide RTK communications receiving without the need for cables or extra power!

#### Your choice of Trimble antenna

Choose the high-accuracy Trimble GPS antenna that best suits your needs: the lightweight and portable Zephyr™ antenna for RTK roving, or the Zephyr Geodetic™ antenna for geodetic surveying.

The Zephyr Geodetic antenna offers submillimeter phase center repeatability and excellent low-elevation tracking, while the innovative design of its

- Industry-leading technology provides superior performance
- Flexible configurations put you in total control
- Rugged, high-performance hardware is built to last
- With the Trimble controller and software of your choice, enjoy seamless integrated surveying

Trimble Stealth™ ground plane literally burns up multipath energy using technology similar to that used by stealth aircraft to hide from radar. The Zephyr Geodetic antenna thus provides unsurpassed accuracy from a portable antenna.



## Trimble 5700 GPS System

#### General Front panel for on/off, one-button-push data logging, CompactFlash card formatting, ephemeris and application file deletion, and restoring default controls · LED indicators for satellite tracking, radio-link, data logging, and power monitoring · Tripod clip or integrated base case Performance specifications Measurements Advanced Timble Maxwell technology High-precision multiple correlator L1 and L2 pseudorange measurements Unfiltered, unsmoothed pseudorange measurement data for low noise, low multipath error, low time domain correlation, and high dynamic response Very low noise L1 and L2 carrier phase measurements with <1 mm precision in a</li> 1 Hz bandwidth . L1 and L2 Signal-to-Noise ratios reported in dB-Hz . Proven Trimble low-elevation tracking technology 24 Channels L1 C/A Code, L1/L2 Full Cycle Carrier, WAAS/EGNOS. Code differential GPS positioning1 Vertical ±(0.5 m + 1 ppm) RMS WAAS differential positioning accuracy typically <5 m 3DRMS<sup>2</sup> Static and FastStatic GPS surveying<sup>1</sup> Kinematic surveying<sup>1</sup> Real-time and postprocessed kinematic surveys Vertical ±(20 mm + 1 ppm) RMS Initialization time. Single/Multi-base minimum 10 sec + 0.5 times baseline length in km, up to 30 km Scalable GPS infrastructure initialization time . . . . . . <30 seconds typical anywhere within coverage area 5700 GPS receiver Physical:

Casing	Tough, lightweight, fully seafed magnesium alloy
Waterproof	Tested to IPX7 standards
Shock and vibration Tested ar Shock	id meets the following environmental standards: OF to survive a 1 m (3.28 ft) drop onto concrete MIL-STD-810-F on each axis
Weight	batteries, internal radio, internal battery charger, standard UHF antenna: 1.4 kg (3 lb)
As entire RTK rover with batteries	for greater than 7 hours, less than 4 kg (8.8 lb)
Dimensions (W×H×L) 13.5	cm × 8.5 cm × 24 cm (5.3 in × 3.4 in × 9.5 in)
Electrical:	
Power	input 11 to 28 V DC with over voltage protection
Power consumption 2.5	W receiver only, 3.75 W including internal radio
Battery Greater than 1 RTK open	O hours data logging, or greater than 7 hours of ation on two internal 2.0 Ah lithium-ion batteries
Battery weight	0.1 kg (3.5 oz)
Battery charger	Internal with external AC power adapter;

Certification.	
Storage temp	it: nperature440 °C to 65 °C (-40 °F to 149 °F) erature40 °C to 80 °C (-40 °F to 176 °F)
Communicati 2 external Integrated External GF CompactFli 64 MB or 1	ons and data storage: power ports, 2 internal battery ports, 3 RS232 serial ports USB for data download speeds in excess of 1 Mb per second 'S antenna connector ash advanced lightweight and compact removable data storage, Options of 128 MB from Trimble
More than	3.400 hours continuous 1.1+1.2 logging at 15 seconds with 6 satellites

- typical with 128 MB card · Fully integrated, fully sealed internal UHF radio modern option
- · GSM, celiphone, and CDPD modern support
- · Dual event marker input capability
- 1 Hz, 2 Hz, 5 Hz, and 10 Hz positioning and data logging
- · 1 pulse per second output capability
- CMRII, CMR+, RTCM 2x and 3x input and output standard
- 14 NMEA outputs

Zepnyr amtenna			
Dimensions	cm (6.38	in) diamete	r × 6.2 cm (2.44 in) height
Weight			0.55 kg (1.20 lb)
Operating temperature		40 °C to	70 °C (-40 °F to 158 °F)
Humidity		100%	humidity proof, fully sealed

Shock and vibration ..... Tested and meets the following environmental standards: Shock . . . . . . MiL-STD-810-F to survive a 2 m (6.56 ft) drop onto concrete 

- · 4-point antenna feed for submillimeter phase center repeatability
- · Integral low noise amplifier
- 50 dB antenna gain

#### Zenhyr Geodetic antenna

Dimensions	34.3 cm (13.5 in) diameter × 7.6 cm (3 in) height
Weight	1.31 kg (2.88 lb)
Operating temperature	40 °C to 70 °C (-40 °F to 158 °F)
Humidity	
Shock and vibration Te	sted and meets the following environmental standards:
Shock MIL-S	TD-810-F to survive a 2 m (6.56 ft) drop onto concrete
Vibration	MIL-STD 810-F on each axis

- · 4-point antenna feed for submillimeter phase center repeatability
- · Integral low noise amplifier
- 50 dB antenna gain
- · Trimble Stealth ground plane for reduced multipath
- 1. Accuracy may be subject to conditions such as multipath, obstructions, satellite geometry, and atmospheric parameters. Always follow recommended survey practices.
- 2 Depends on WAAS/EGNOS system performance.
- 3 May be affected by atmospheric conditions, signal multipath, and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality.

  4 Receiver operates normally to -40 °C (-40 °F) but some office based functions such as USB download.
- or internal battery charging are not recommended at temperatures below freezing. Specifications subject to change without notice.

## NORTH AMERICA

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YOUR LOCAL TRIMBLE OFFICE OR REPRESENTATIVE





no requirement for external charger



#### **KEY FEATURES**

Versatile: Use as base, repeater or rover

Flexible: 2 W, 10 W, or 25 W power output

Channel spacing programmable at 12.5 kHz or 25 kHz

Easy to use and configure

Built-in channel selector and monitor

Rugged and weatherproof



## RUGGED AND VERSATILE MULTICHANNEL RADIO MODEM

The TRIMMARK<sup>TM</sup> 3 radio modem provides a convenient, versatile means of establishing a robust wireless data broadcast network for real-time, high-precision GPS survey and telemetry applications.

The rugged, compact TRIMMARK 3 radio modem is designed for use in tough environments and in a variety of situations. The single unit is usable as a base station, repeater station, or rover receiver for maximum versatility. However you use it, you'll appreciate its simplicity and famous Trimble reliability and quality.

#### **SELECT THE POWER YOU NEED**

The TRIMMARK 3 radio modem provides selectable power outputs of 2 W, 10 W, or 25 W to support both short and long-range operations, conserve battery life and minimize risk of interference with other systems.

A 25 W base unit broadcasts up to 15 km (8 miles) line-of-sight, under optimal conditions. Path obstructions and terrain can reduce the typical effective range to 10 km to 12 km (6 miles to 7 miles). One or two additional units can be networked as repeater stations to extend range, minimize base station moves, and provide seamless coverage around local obstacles such as large buildings or hills. The typical range of a 2 W repeater is 5 km to 8 km (3 miles to 5 miles).

A TRIMMARK 3 radio modem broadcasts or repeats data to Trimble survey-grade GPS receivers, such as the Trimble R8, 5800, Trimble R7, and 5700, that either contain an internal radio modem or are being used with an external rover radio. The TRIMMARK 3 is fully backward compatible with the TRIMMARK Ile radio modem, so it can be used in both new and existing systems.

#### **CONFIGURE IT TO YOUR NEEDS**

The TRIMMARK 3 radio modem can be configured completely and easily in the office by using the supplied WinFLASH utility on your computer. Many functions also can be configured in the field from the front panel or from the Trimble Survey Controller™ software used with your GPS survey receivers. The serial port communication settings are easily set to match the default settings on the GPS receiver.

You can configure each broadcast network to operate on one of up to 20 programmed channels via a built-in channel selector.

Channel spacing of either 12.5 kHz or 25 kHz is programmable at the factory or by a service provider.

To reduce the risk of interference in a congested RF environment, you can use the built-in audio speaker to monitor activity on the selected channel. The unit also can automatically monitor the channel using its software selectable carrier detect function to detect other users on the channel before transmitting.

The TRIMMARK 3 radio modem is available as a stand-alone product as well as in convenient base and repeater equipment sets. Available in three frequency bands, the TRIMMARK 3 radio modem is designed to meet the licensing requirements of many countries around the world.



## TRIMMARK 3 RADIO MODEM

#### STANDARD FEATURES

- Selectable 20-channel capacity
- · Rugged weatherproof construction
- · Configurable from front panel, survey controller, or from supplied WinFLASH utility on your computer
- . Up to 15 km line-of-sight range
- · Same unit can function as base station, repeater station, or rover receiver
- Selectable power outputs of 2 W, 10 W, or 25 W
- Programmable channel spacing of 12.5 kHz or 25 kHz
- · Built-in channel selector
- · Supports up to two repeaters in a network
- · 4800, 9600 and 19200 baud rate over the air
- · Retrievable/storable radio diagnostic information

#### TRIMMARK 3 RASE/REPEATER

Physical	
Size	12.5 cm W x 22.9 cm D x 7.9 cm H
	(4.9° W x 9.0° D x 3.1° H)
Weight	1.59 kg (3.5 lb)
Electrical	
Downer	

#### Environmental

remperature.	
Operating	40 °C to +65 °C (-40 °F to +149 °F)
Storage	-55 °C to +75 °C (-67 °F to +167 °F)
Humidity	100%, fully sealed, weatherproof

#### **TECHNICAL SPECIFICATIONS**

TEGUMENT SI EGIMENTON	
Transmit Power <sup>1</sup>	2 W, 10 W, 25 W
	4800 bps, 9600 bps, 19200 bps
Frequency Bands	. 410-420 MHz, 430-450 MHz, or 450-470 MHz
S	(Only one band per radio modem)
Channel Spacing	12.5 kHz or 25 kHz
The state of the s	(Only one spacing per radio modem)
Number of Channels <sup>2</sup>	Can be ordered with up to 20 programmed
	frequencies, internally stored
RF Modulation Format	Gaussian Minimum Shift Keying (GMSK)

#### Range (typical)3

25 W Base	. 10 km to 12 km (6 miles to 7 miles)
2 W Repeater	5 km to 8 km (3 miles to 5 miles)

Power Consumption <sup>4</sup>	Voltage Current		Nominal Load	
2 W mode	12.6 V	0.8 A	~10 W	
10 W mode	12.6 V	3.6 A	-45 W	
25 W mode	12.6 V	8.0 A	~75 W	

Serial Port..... One set of RS-232 signals available. Data is 8 bits with selectable parity and 1 stop bit. Supported data rates are 9600 bps, 19200 bps, and 38400 bps<sup>5</sup>

ANTENNA PHYSICAL	LENGTH (TYPICAL)	WEIGHT
Standard antenna	Value of the second	
0 dB UHF omni whip	47 cm (18.5 in)	0.5 kg (1.1 lb)
5 dB UHF omni whip	99 cm (39 in)	0.5 kg (1.1 lb)

1. Radios are configured as 25-W units at the factory.
2. Use the same frequency for all radio modems in the same wireless data network.
3. Varies with terrain and operational conditions. Up to 2 repeaters can be used to extend range.
4 Power consumption and battery life depend on the broadcast information content and wireless data rate (e.g., CMR versus RTCM SC-104 Ver 2x packets at 1-Hz epoch rates).
5. Communications rate between the radio and GPS receiver, not wireless rate.

Specifications subject to change without notice

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# DATA SHEET



#### **KEY FEATURES**

Purpose-built integrated GPS receiver for improved productivity

Can be used as a rover or base for unrivaled versatility

Extremely lightweight—to reduce fatigue on all-day operations

Cable-free rover for more flexibility and ease-of-use in the field

Accurate and reliable for confidence in your results



## FULLY INTEGRATED, EXTREMELY LIGHTWEIGHT, CABLE-FREE GPS SYSTEM

The Trimble® 5800 GPS system makes cables a thing of the past. The receiver itself combines a dual-frequency GPS receiver, Trimble GPS antenna, UHF (receive only) radio and batteries in one compact unit.

#### INTEGRATED SYSTEM

Because the Trimble 5800 GPS system's components are completely integrated, as a rover the system is lightweight and ergonomic—and completely cable-free.

2 MB of internal memory makes collecting data for postprocessing extremely easy and efficient, whether for static or kinematic (stop-and-go) surveying.

The Trimble 5800 can also be used as a base station, so it is versatile to meet the changing needs of your business.

#### **ADVANCED TECHNOLOGY**

The Trimble 5800 GPS system offers advanced Trimble GPS technology. It is a 24-channel dual-frequency GPS/WAAS/EGNOS receiver, containing Trimble's proven Maxwell' technology for robust tracking in difficult GPS environments.

Its WAAS and EGNOS capability provides real-time differential positioning without a base station.

The dual-frequency Trimble antenna enhances the tracking capabilities of the Trimble 5800—the patented four-point antenna feed provides submillimeter phase center stability for precise results. The position of the UHF radio antenna mounting further increases accuracy by being out of the GPS line-of-sight, reducing multipath and avoiding interference with the GPS antenna.

For rover communications use the built-in 450 or 900 MHz radio, or use an external radio, cell phone or wireless packet data modem.

For base communications, select a radio from Trimble's range of powerful communication products. Just the kind of flexibility you need!

For extended coverage and comprehensive error checking when roving, the Trimble 5800 works with signals from multiple base stations transmitting on the same radio channel. For even larger area coverage, at highest accuracies, the Trimble 5800 works with Trimble VRS<sup>14</sup> networks.

Integrated Bluetooth wireless technology enables cable-free communication between the receiver and your Trimble controller.

#### **BUILT FOR THE FIELD**

The Trimble 5800 as a rover is not only lightweight and cable-free; it also consumes minimal power. Two miniature batteries will power the receiver for up to 11 hours – at least enough for a full working day.

Environmentally rated to IPX7, and submersible to a depth of 1 m, the Trimble 5800 is rugged enough for any job. It can withstand a drop of up to 2 m on to a hard surface.

#### WIDE RANGE OF APPLICATIONS

The 5800 GPS system is ideal for a wide range of positioning applications, including:

- Survey
- Construction
- Asset management

It offers you the accuracy, flexibility, and ease of use you need for all your survey-grade GPS applications.

 Bluetooth type approvals are country specific, Contact your Trimble representative for more information.



#### PERFORMANCE SPECIFICATIONS

#### Measurements

- Advanced Trimble Maxwell Custom Survey GPS Chip
- High precision multiple correlator for L1 and L2 pseudorange
- · Unfiltered, unsmoothed pseudorange measurements data for low noise, low multipath error, low time domain correlation and high dynamic response
- Very low noise L1 and L2 carrier phase measurements with <1 mm precision in a 1 Hz bandwidth
- L1 and L2 Signal-to-Noise ratios reported in dB-Hz
- · Proven Trimble low elevation tracking technology
- 24 Channels L1 C/A Code, L1/L2 Full Cycle Carrier, WAAS/EGNOS

#### Code differential GPS positioning<sup>1</sup>

Horizontal	±0.25 m +1 ppm RMS
Vertical	±0.50 m +1 ppm RMS
WAAS differential positioning accuracy <sup>2</sup>	Typically <5 m 3DRMS

#### Static and FastStatic GPS surveying<sup>1</sup>

Horizontal	±5 mm +0.5 ppm RMS
Vertical	±5 mm +1 ppm RMS

#### Kinematic surveying

Horizontal	±10 mm +1 ppm RMS
Vertical	±20 mm +1 ppm RMS
Initialization timeSingle/Mu	Iti-base minimum 10 sec +0.5 times
	baseline length in km, up to 30 km
Initialization reliability3	Typically >99.9%

#### HARDWARE

#### **Physical**

Dimensions (WxH) . 19 cm (7.5 in) × 10 cm (3.9 in), including connectors Weight . . . . . . . . . . . . 1.31 kg (2.89 lb) with internal battery. internal radio, standard UHF antenna. 3.67 kg (8.09 lb) entire RTK rover including batteries, range pole, ACU controller and bracket

Temperature*	
Operating	40 °C to +65 °C (-40 °F to +149 °F)
Storage	_40 °C to +75 °C (_40 °E to +167 °E)

Waterproof..... IPX7 for submersion to depth of 1 m (3.28 ft) Shock and vibration . . . . . . . . . . Tested and meets the following environmental standards:

Shock . . . . Non-operating: Designed to survive a 2 m (6.6 ft) pole drop onto concrete. Operating: to 40 G, 10 msec, sawtooth 

#### Electrical

- Power 11 to 28 V DC external power input with over-voltage protection on Port 1 (7-pin Lemo)
- · Rechargeable, removable 7.4 V, 2.0 Ah Lithium-Ion battery in internal battery compartment. Power consumption is <2.5 W, in RTK mode with internal radio.
- · Operating times on internal battery: 450 MHz or 900 MHz receive only 5.5 hours, varies with temperature
- Certification Class B Part 15, 22, 24 FCC certification, Canadian FCC, CE Mark approval, and C-tick approval

#### Communications and Data Storage

- 3-wire serial (7-pin Lemo) on Port 1. Full RS-232 serial on Port 2 (Dsub 9 pin)
- Fully Integrated, fully sealed internal 450 MHz receiver
- Fully Integrated, fully sealed internal 900 MHz receiver
- Fully integrated, fully sealed 2.4 GHz communications port (Bluetooth)5
- External GSM, Cellphone and CDPD modem support for RTK and VRS operations
- Data storage on 2 MB internal memory: 55 hours of raw observables. based on recording data from 6 satellites at 15 second intervals
- Data storage on controller with 128 MB memory: Over 3400 hours of raw observables based on recording data from 6 satellites at 15 second intervals
- . 1 Hz, 2 Hz, 5 Hz, and 10 Hz positioning
- CMRII, CMR+, RTCM 2.1, RTCM 2.3, RTCM 3.0 Input and Output
- 14 NMEA outputs, GSOF and RT17 outputs
- Supports BINEX and smoothed carrier

I Accuracy and reliability may be subject to anomalies such as multipath, obstructions, satellite geometry,

1 Accuracy and reliability may be subject to anomalies such as multipath, obstructions, satellite geometry and atmospheric conditions. Always follow recommended survey practices.

2 Depends on WAAS/EGNOS system performance.

3 May be affected by atmospheric conditions, signal multipath, and satellite geometry, initialization reliability is continuously monitored to ensure highest quality.

4 Receiver will operate normally to -40 °C, Bluetoath module and internal batteries are rated to -20 °C.

5 Bluetooth type approvals are country specific. Contact your local frimble office or representative for more

Specifications subject to change without notice.

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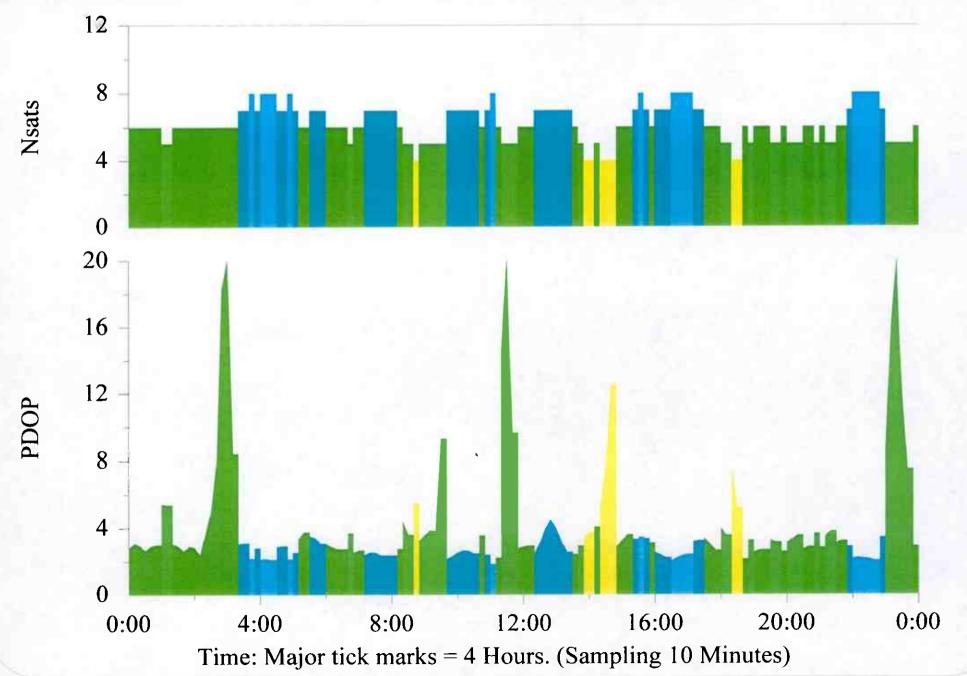


# Number 5 Vs anu PbOF

Point: Vakkerlien
Date: 2005/October/05

Lat 62:32:0 N Lon 10:17:0 E Threshold Elevation 20 (deg) Almanac: ALMANAC.EPH 05/10/06 Time Zone 'Central European Day' 2:00

28 Satellites considered: 1 2 3 4 5 6 7 8 9 10 11 13 14 15 16 18 19 20 21 22 23 24 25 26 27 28 29 30

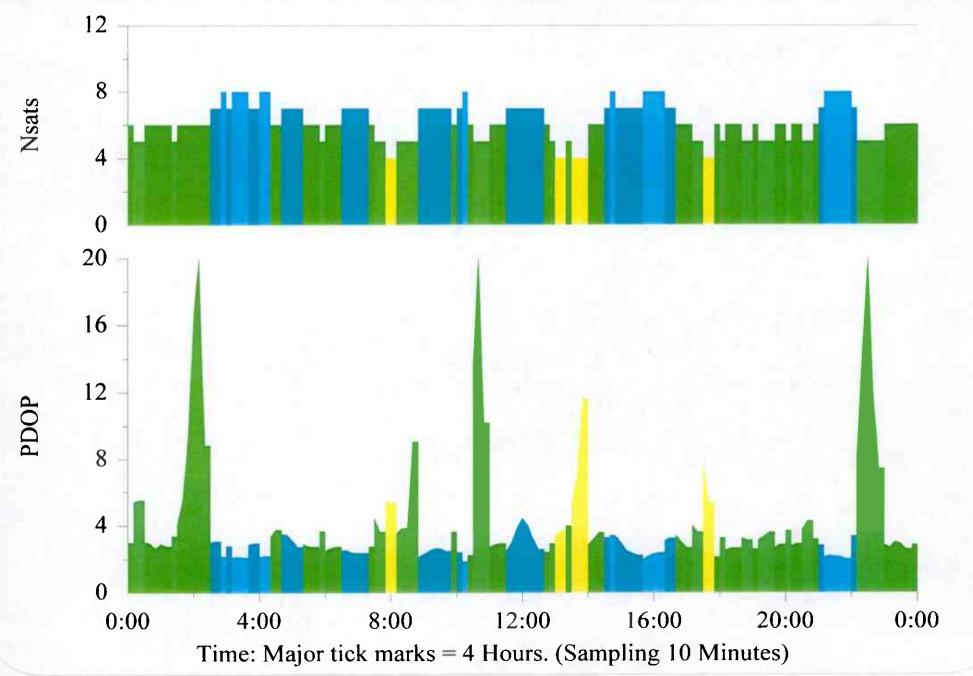


# Number 5 Vs and PbOF

Point: Vakkerlien Date: 2005/October/17

Lat 62:32:0 N Lon 10:17:0 E Threshold Elevation 20 (deg) Almanac: ALMANAC.EPH 05/10/06 Time Zone 'Central European Day' 2:00

28 Satellites considered: 1 2 3 4 5 6 7 8 9 10 11 13 14 15 16 18 19 20 21 22 23 24 25 26 27 28 29 30



#### APPENDIX F - LINE STATISTICS REPORT

XYZSTAT version 1.50.02 Copyright GEOSOFT Inc. 1994

Statistics report for file: VAKK.XYZ

Z column number: 2

type	line#	#pts	X-min	X-max	Y-min	Y-max	Z-min	Z-max
line	286	37	567600	568500	6928600	6928601	759.205	815.422
line	288	43	567452.1	568500.1	6928799	6928801	765.184	827.209
line	290	45	567400.1	568500	6929000	6929000	783.443	835.697
line	292	45	567400	568500	6929200	6929200	796.88	847.407
line	294	4.5	567399.9	568500.1	6929400	6929400	811.317	857.527
line	307	57	567125.1	568525	6930700	6930700	872.161	934.362
line	309	109	565825	568525	6930900	6930900	801.653	945.488
line	311	110	565825	568525.1	6931093	6931100	802 072	951.317
line	313	109	565825	568525.5	6931299	6931301	802.519	962.49
line	315	109	565825	568525.1	6931500	6931501	803.055	969.197
line	317	109	565825	568524.9	6931699	6931730	803.08	961.781
line	319		565825	567225 1	6931898	6931902	804.794	877.292
line	329	46	565450	566550.3	6932899	6932900	823.568	848.081
line	330	45	565450	566550	6933000	6933001	830.665	855.017
line	331	46	565450.1	566550	6933100	6933100	835.083	858.869
line	332	45	565449.8	566550 1	6933195	6933203	840.146	864.598
line	333	45	565449.9	566550	6933300	6933301	846.675	875.823
line	334	46	565449.9	566549.7	6933400	6933400	853.333	882.359
line	335	45	565450	566549.9	6933499	6933500	860 853	887.847
line	336	45	565449.9	566550	6933598	6933601	866 741	893.797
line	337	45	565449.9	566550.1	6933700	6933702	875.204	903.316
line	663	88	566299.8	566300.5	6930700	6932875	802.128	838.43
line	664	89	566399.9	566400.3	6930700	6932875	801.433	844.807
line	665	88	566499.9	566500.1	6930700	6932875	802.416	846.91
line	666		566599.8	566601.9	6930700	6932900	813.705	850.332
line	667	89	566699.9	566701.2	6930700	6932900	824.446	862.219
line	668		566799.8	566800.1	6932100	6932900	830.748	867.056
line	669		566899.9	566901.4	6932100	6932903	838.835	870.994
line	670		566999.9	567000.2	6932100	6932901	844.551	878.568

Statistics report for file: ALL.XYZ

Z column number: 2

Number of points: 1825 Number of lines: 29 0 Base lines: 0 Tie lines: Trend lines: 0 Test lines:

X-min: 565449.8 X-max: 568525.5 Y-min: 6928600 Y-max: 6933702 Z-min: 759.205 Z-max: 969.197 Z-mean: 851.8904 Z-dev: 44.18187 SUMMARY

Z-mean: 851.8904 Z-dev: 44.18187

## FOUR (4) GEODETIC POINT's at KVIKNE NORWAY

This info / table is made / based on info from www.startkart.no -> norgesglasset (old version).

FIXED MARK	G27T0065	G27T0136	G27T0222	G27T0223	
NAME	ÅSFJELL	VAKKERLIFJELL	STORINNSJØEN	SLØBEKKSETERA	
NORTH	6931463,775	6935786,254	6933997,854	6929262,312	
EAST	568571,041	565601,417	564379,512	565619,475	
ZONE	32	32	32	32	
HIGHT (orto)	970,249	989,559	879,776	809,177	
POINT / TYPE	T *)	T *)	L **)	L **)	
SURFACE			BEDROCK	BEDROCK	
QUALITY XYm	0,03	0,05	0,03	0,03	
QUALITY Horto	0,030	0,050	0,030	0,030	
HIGHT (ell)	1012,440	1031,880	922,180	851,542	
STATUS					
REF. YEAR					
KOMMUNE	437	437	437	437	
OTHER ID					
DESCIPTION	About 10 Km. S of the church in Kvikne. From Kvikne along the main road towards SE to STORASEN. From here a foot-path to the top.	70 – 80 m. S of the highest point and 4 m. S of the road to the seter.	In the S end of a small hill, 40 m. NE of road and 20 (?) m. ENE of highvoltage mast.	About 4 m. S of road ditch, 10 m. SSE of the highest point of road.	
Height Diff (orto-ell)	42.191	42.321	42.404	42.365	

#### "Fixed point", fastmerke:

Enclosed are four (4) maps showing location of the points as described under description in the table concerning the grids in "The North Area" - Vakkerlien and "The South Area" - Orkla.

Rgds. finn h Rev.: B 2005.10.13

<sup>\*) = &</sup>quot;Triangel point", Trig. Pt. / trekant punkt

<sup>\*\*)= &</sup>quot;Country grid", Lands-nett

## **GPS Survey for Falconbridge Ltd.**

Vakkerlien Project - WAAS/EGNOS and Omnistar Differential Correction versus Geodetic Grade RTK with Basestation

Statiom		1	WAAS			SAT_DIF			BASE					
	×	У	z	running diff	base diff	×	y	z	running diff	base diff	x	у	z	running diff
335565950	565949.885	6933500.795	908:381			565949.751	6933499,969	908.697			565949.833	6933499.823	865.572	
335565925	565925.341	6933501.140	905.862	-2.519	0.348	565925.077	6933500.240	906.563	-2.134	-0.037	565924.938	6933499.935	863,401	
335565900	565899.870	6933501.416	906.362	0.500	0.462	565900.308	6933500.591	907.883	1.320	and the second second second	THE RESERVE OF THE PARTY OF THE	6933500.036		1
335565875	565875.022	6933501.269	906.698	0.336	-0.201	565875.179	6933500.267	907.721	-0.162		The second secon	6933499.988		
335565850	565850.269	6933501.143	907,328	0.630	0.021	565850.315	6933500.261	908,561	0.840			6933500.047	865.149	1
335565825	565825.253	6933501.201	907.108	-0.220	-0.040	56582 <b>5.25</b> 6	6933500.122	908.310	-0.251			6933500.063	864.889	
335565800	565800.168	6933501.153	907.889	0.781	0.070	565800.307	6933499.901	908.858	0.548			6933499.966		
335565775	565774.815	6933500.998	909.210	1.321	-0.353	565775.095	6933500.217	910.038	1.180	-0.212	565774.929	6933499.923	866.708	
335565750	565749.615	6933500.849	910.708	1.498	-0.114	565750.144	6933500.217	911.207	1.169	0.215	565749.862	6933499.902	868.092	
335565725	565724.988	6933501.523	909.135	-1.573	-0.715	565725.564	6933500.486	908.519	-2.688	0.400	565725.011	6933500.116	865.804	
335565700	565700.224	6933500.646	907.273	-1.862	0.989	565700.375	6933500.001	908.023	-0.496	-0.377	565700.017	6933499.679	864.931	
335565675	565675.374	6933501.508	905.159	-2.114	0.048	565675.441	6933500.777	905.382	-2.641	0.575	565675.054	6933500.212	862.865	1
335565650	565650.295	6933501.098	903.428	-1.731	-0.134	565650.209	6933500.661	903.970	-1.412	-0.453	565649.996	6933500.040	861.000	-1.865
335565625	565625.201	6933500.980	903.495	0.067	-0.214	565625.169	6933500.305	904.265	0.295	-0.442	565624.937	6933500.097	860.853	
335565600	565600.112	6933500.903	906.657	3.162	0.148	565600.097	6933500.127	907.818	3.553	-0.243	565599.959	6933500.082	864.163	
335565575	565575.332	6933500.619	911.040	4.383	-0.347	565575.259	6933500.078	910.331	2.513	1.523	565575.079	6933499.868	868.199	
335565550	565550.244	6933500.938	910.170	-0.870	0.428	565550.089	6933500.429	910.756	0.425	-0.867	565549.870	6933499.965	867.757	<u> </u>
335565525	565525.149	6933500.902	905.954	-4.216	-0.182	565525.146	6933500.534	906.706	-4.050	-0.348	565524.896	6933500.014	863.359	
335565500	565500.288	6933500.905	907.167	1.213	-0.062	565500.337	693350 <b>0</b> .334	907.703	0.997	0.154	565500.028	6933500.052	864.510	
335565475	565475.225	6933500.967	909.429	2.262	0.046	565475.215	6933500.397	910.172	2.469	-0.161	56 <b>5</b> 475.095	6933499.985	866.818	
335565450	565450.313	6933500.686	909,441	0.012	-0.230	565450.307	6933500.444	910.030	-0.142	-0.076	565450.008	6933499.993	866.600	-0.218

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## APPENDIX | REFERENCES

Trimble Navigation, 2000.

Mapping Systems Manual

Telford, W.M., Geldhart, L.P., and Sheriff, R.E. 1990. *Applied Geophysics, 2<sup>nd</sup> Edition,* NY: Cambridge University Press

-Logistics Report-2005 UTEM Survey Vakkerlien Norway for A/S Sulfidmalm

## LAMONTAGNE

GEOPHYSICS LTD GEOPHYSIQUE LTEE

December, 2005

Rob Langridge, M.Sc.

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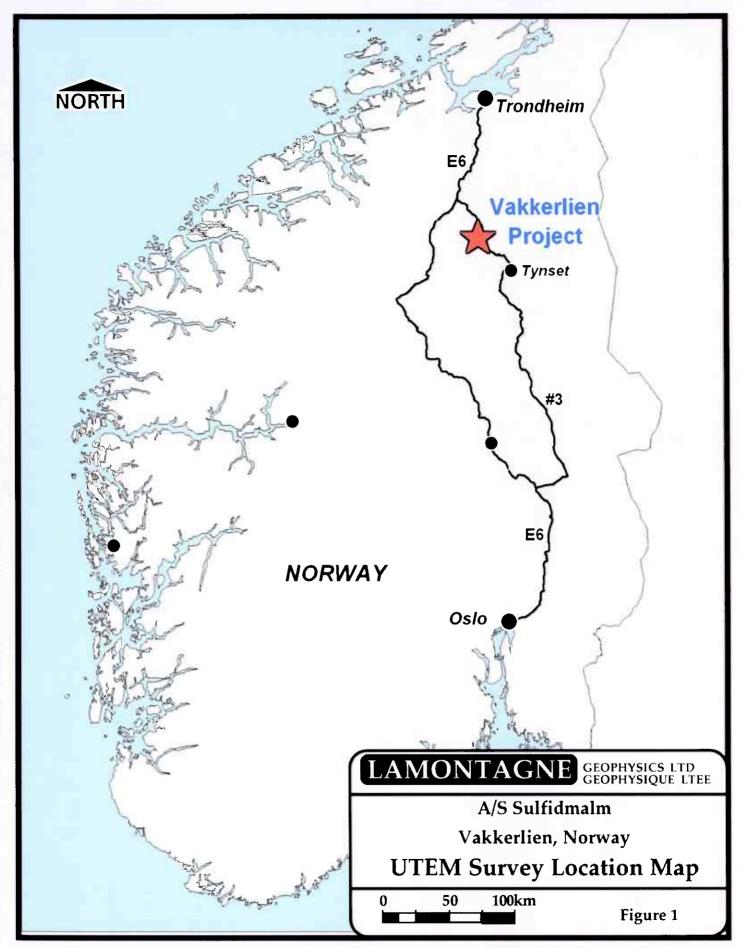
#### INTRODUCTION

During the period of November 3rd 2005 through November 26th 2005 a UTEM survey was carried out by Lamontagne Geophysics Limited personnel for A/S Sulfidmalm in the area of Vakkerlien, Norway (Figure 1). The location of the property is shown in Figures 1 and 2. Areas of interest were identified from the results of an airborne survey and the results of previous work in the area. The survey was carried out to locate conductors in the immediate grid areas with the intention of outlining targets for future work.

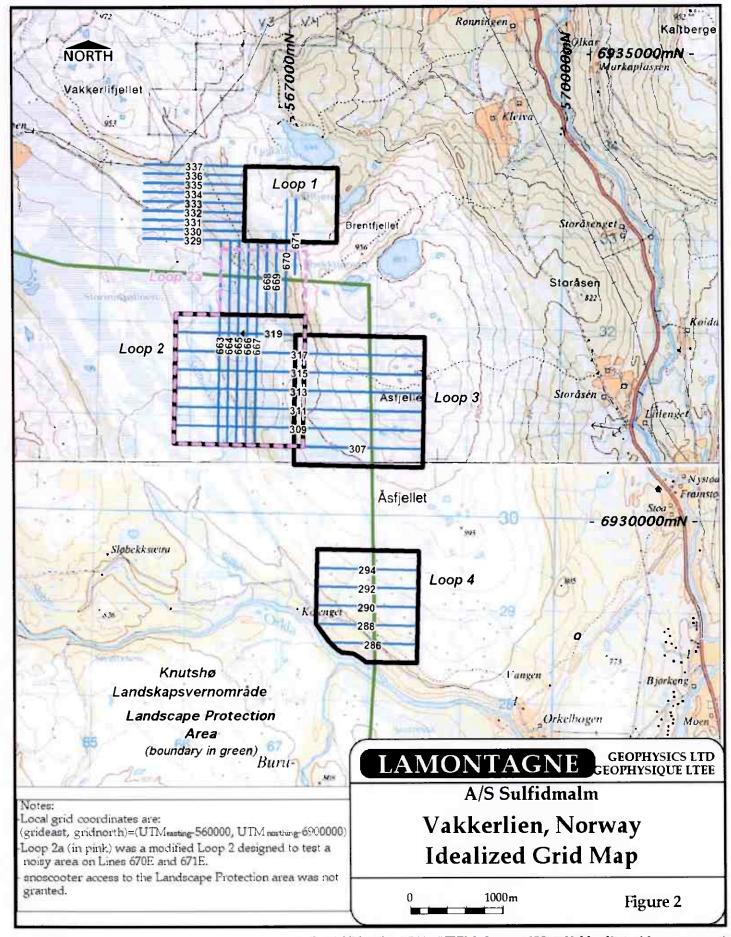
A total of 50.450km of surface UTEM data was collected using 5 transmitter loops (Loops 1, 2, 2a, 3, and 4). All lines were surveyed measuring the vertical component, Hz. A station spacing of 25m or 50m and a line spacing of 200m or 100m was employed. For all loops the receiver operated in 10-channel mode at a transmitter frequency of 3.251Hz.

This report documents the UTEM survey in terms of logistics, survey parameters and field personnel. Appendix A contains the data presented in profile form. Other appendices contain:

-	List of Personnel/Production Diary	(Appendix B)
-	an outline of the UTEM System	(Appendix C)
-	Note on sources of anomalous Ch1	(Appendix D)
4	Note on 4Hz UTEM Data	(Appendix E)



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#### **SURVEY DESIGN**

This UTEM survey is part of a nickel exploration program in the Vakkerlien area. Historically mining of Ni-bearing massive sulfide deposits has been carried out in the area. The UTEM survey was planned and carried out to outline and allow better definition of known conductors, to detect/outline new conductors and to detect/outline deeper features and depth continuations of known features.

The grid and loop layout was designed by A/S Sulfidmalm/Falconbridge Ltd. personnel to allow efficient coverage of the area. Loop size and locations were selected to provide good coupling with the expected targets and to allow efficient coverage of the grid area. The base frequency was lowered from the international standard ~26Hz to 3.251Hz to eliminate the response of many "moderate" conductors - these responses will have decayed away by Ch1 time. Any remaining Ch1 responses are then considered to be representative of conductors of an appreciably higher conductivity.

The survey parameters employed:

- both in-loop and outside-the-loop coverage with 2 receivers
- variable transmitter loop size to fit the area to be covered and the relief
- 1.18mm (~1mm² ~17-gauge copper wire) doubled in places for increased current more signal requires shorter stacking times and/or better quality data
- line spacing of 200m or 100m intervals as required
- station interval of 25m or 50m.
- Hz (vertical component measurements)
- 10-channel data at a frequency of 3.251Hz
- minimum 256 stacking (512 half-cycles) increased where noise levels dictate

In nickel exploration non-decaying Channel 1 (Ch1) conductors are indicative of highly conductive mineralization. Any non-decaying anomalous Ch1 features are therefore of interest. Non-decaying channel UTEM anomalies can reflect:

- i) the presence of conductive mineralization
- ii) the presence of a magnetic anomaly
- iii) poor geometric control either station location or loop location

These are outlined in more detail in Appendix D. From an interpretation standpoint magnetic anomalies and geometric control should be considered and evaluated as a mandatory part of any interpretation. From a field standpoint precise geometric control should be part of any UTEM survey where the target is non-decaying. Poor geometric control has the potential to both mask and invent Ch1 conductors.

For this survey GPS data was collected by the client and made available for use in reducing the UTEM data. GPS data was collected for all survey points and at intervals around all transmitter loops. GPS data collection for UTEM reduction should be most detailed along loop fronts - the most important portion of the loop from a UTEM reduction perspective. The goal along the loop front - and loop sides/back - is to recover the topographic shape of the loop as well as the loop/line intersection points.

#### **SURVEY LOGISTICS**

A Lamontagne Geophysics crew mobilized from Kingston/Calgary to Oslo/Trondheim in early November. The crew consisted of Rob Langridge (crew chief), John Frost (operator) and Tim Pinkerton (looper). John Frost arrived in Oslo on October 31st along with Falconbridge personnel. They and the UTEM equipment were met by client representative Finn Hansen and together they drove to Espedalen. The following morning they continued on to the base of operations for the Vakkerlien survey - at the Hogstad Campground roughly ten kilometers north of the survey areas. Equipment was unpacked and loop laying began. Rob Langridge and Tim Pinkerton were collected from Trondheim on the evening of November 3rd and surveying began the following day - November 4th.

Five transmitter loops were used during the surface UTEM survey for a total survey coverage of 50.450km. Figure 2 shows the loop locations and grid layout. Access to the Vakkerlien project was by pick-up truck via farm access roads. The grid/loop positions had been established by GPS and were demarcated by bamboo wands and flagging. Access to the grid was on foot and later, with the snowfall, in part by snoscooter. Part of the survey area lies in a Landscape Protection Area (outlined on Figure 2) and the snoscooter permit did not allow us access to this area. The only access to the Landscape Protection Area - including all of Loop 2 - was on foot.

There was no snow on the ground for the first part of the survey and as a result surveying began with Loop 4 - the loop most easily accessible by road. The wire for this loop was laid in advance by the client. Loop 1 - the second-most accessible by road - was surveyed next. The generator (Honda 7500W) was moved out to the loop along with the UTEM equipment. The generator is larger than would typically be required (~2500W) and moving it about proved to be difficult under the field conditions. A wheel-barrow was used to transport it to the transmitter sites of Loop 1 and Loop 2/3. It was removed from the survey area by sled - hand towed to the edge of the Landscape Protection Area and then pulled by snoscooter.

Electrical connection to the generator was made through an LGL isolation-transformer/Variac combination rewired to conform with the sockets (standard 2-pin/side-clip ground european) on the generator. For all but a few nights the transmitter was connected to a battery, switched to remote, packed up against the weather and left in the field. This worked well for the duration of the survey. The small-volume gas tank on the generator was the only drawback - it required filling at least 2 times a survey day (every 4.5-5 hours).

In general surface surveying for all loops went well although more slowly than planned. Noise levels proved to be high and in places, along certain geologic structures, extremely high. Higher noise levels in the vertical component are typical of very resistive areas. Locally noisy areas indicate some channeling of telluric currents along features in the very-resistive country rock. For the final two loops - Loop 3 and then Loop 2 - the highest possible pre-whitening level was used and all sides of the loop were doubled as much as possible. Doubling the wire reduces the resistance of the loop and this allows a higher transmitter current to be used. Higher current equals more

signal and an improved signal-to-noise ratio - less stacking is required and surveying proceeds more quickly. In practice it requires a considerable additional effort to lay/retrieve double strands of wire. Because access to these loops was limited to foot access the doubled wire proved a useful resource when repairing loop breaks. Use of a heavier gauge wire could be considered on future surveys.

The northern section of the area surveyed from Loop 1 is cut by a powerline. The powerline crosses the northernmost line surveyed - Line 337N. The powerline meets Line 336N at the westernmost station surveyed. In general surveying in the area of powerlines required additional stacking and the profiles from Loop 1(Appendix A) are noisy in the vicinity of the cultural features. The noise is particularly evident on the earlier channels - Ch10-5 - as the channel width is too narrow to allow the 50Hz powerline transmission to be adequately stacked out (Appendix E). Note that the powerline is not the source of all the noise present on the Loop 1 profiles in Appendix A. The very resistive geological setting is also a contributor as discussed above.

For logistical reasons Tim Pinkerton was demobilized as scheduled on November 24th. The final surface UTEM data was collected November 24th and the survey was declared completed. All remaining wire and pickets were picked up on November 25th and 26th and the equipment was packed for shipping. The crew and equipment, along with the Falconbridge crew and equipment, demobilized. The crew demobilized to Canada on November 28th and the equipment was transported to Gardemoen Airport the same day by Falconbridge personnel. Details of the daily production and personnel are included in the Production Diary (Appendix B) along with a summary of production.

The survey equipment consisted of two UTEM 3 receivers and one UTEM 3 transmitter as well as all necessary accessories, support equipment and backup equipment. Data was reduced on a field computer (Macintosh) and UTEM profiles and digital data were made available/emailed to the client's personnel on a daily basis. Boots and then snowshoes were used during the survey.

Care was taken during the survey not to leave anything on the site. One site which should be checked over after the snow melts is the the Loop 2/3 transmitter site (Line 319N @ 7225E where the loops intersect) which was occupied for over two weeks - from November 11<sup>th</sup> to the 26<sup>th</sup>. The site lies in the Landscape Protection Area and although care was taken with the amount of snow that fell it is possible something was left at the site.

In practice the UTEM operators worked with coilers. Where survey conditions allowed - towards the ends of survey lines where long stacking times were required - the coiler could be freed up to facilitate looping and picket retrieval. The coilers also trekked back to the generator to fill up the gas tank as required. The weather conditions were generally fair-to-good for surveying. Prior to the arrival of snow the days were cool but windy. The snow conditions were generally good although a considerable amount of snow disappeared over the course of a few warmer days.

#### **SURVEY RESULTS**

The results of the survey are summarized and presented as UTEM profiles in Appendix A. The final grid and Loop Locations are presented in Figures 2. Overall the data quality is good - though in places it is noisy. Little evidence of conductors and/or conductive features are evident. Although every effort was taken to shelter the receiver coil minor wind noise may be evident in some profiles.

Surface profiles are listed by Loop number and presented as 3-axis profiles in the following order:

Hz continuous norm Ch1 reduced (blue separator)
Hz point normalized Ch1 reduced (pink separator)

A description of the standard plotting formats used and of the UTEM System is presented in Appendix C.

### Outline of surface profile types

#### Hz continuous norm

Ch1 reduced

(blue separator)

Continuous normalization is useful for detection of the presence of anomalies at any position on a profile. The anomaly shape is distorted by the normalization to the local field. As the field gets very big near the wire the continuously normalized Ch1 tends towards zero.

top axis - Ch5-10 middle axis - Ch2-5 bottom axis - Ch1 bottom axis - topography - no vertical exaggeration

#### Hz point normalized

Ch1 reduced

(pink separator)

normalization point:

all data~300m out from the loop-front centre

Point normalized data is useful for interpretation purposes. Anomaly shape is preserved as is the amplitude if the normalization point is local to the anomaly.

All data has been point normalized to a the field at a point ~300m out from the centre of the loop front. Note that this field value is intermediate and it was chosen because the survey was roughly half inside-the-loop and half off-loop. Normalizing to an intermediate point allows the interpretation of responses along the entire line. The amplitude of responses close to (further from) the loop front will be blown up (muted).

Note: Typically the normalization point for off-loop profiles is 4-500m out from the centre of the loop front and for inside-the-loop profiles it is the loop centre.

The disadvantage of point normalization is that small errors in location near the wire and in current tend to appear as large errors in Ch1. If the loop/station locations and the current are accurately known then point normalized Ch1 (in the absence of a local conductor) will tend to be continuous approaching the

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wire - unlike the continuously normalized Ch1 which, as described above, will dip to zero.

top axis - Ch5-10 middle axis - Ch2-5 bottom axis - Ch1 bottom axis - topography - no vertical exaggeration

#### Discussion of Results

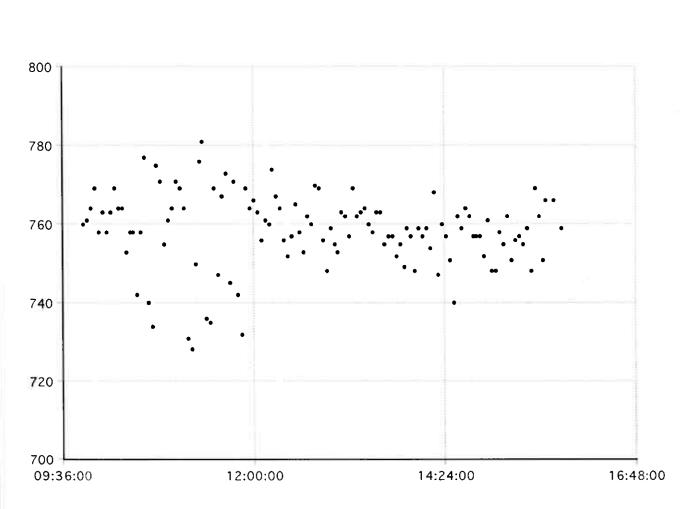
The area surveyed is very resistive - little response is seen at even the earliest time-channels. The off-loop data - Loop 1 and the lines surveyed to the north of Loop 2 - is noisy-to-very-noisy in places once the distance to the loop front exceeds 500-600m.

Noise levels proved to be high and in places, along certain geologic structures, extremely high. Higher noise levels in the vertical component are typical of very resistive areas. Locally noisy areas can indicate some channeling of telluric currents along features in the very-resistive country rock.

As a test of whether the powerline that just comes onto the area surveyed from Loop 1 (NE corner of Figure 2) was responsible for some of the noise seen in the survey data the spare receiver was set up and recorded data during a survey day (November 10). The site selected was reasonably close to the powerline and well-sheltered to reduce wind noise. Staking was deliberately set a little low for the site - 512 full-cycles (1024 half-cycles). A 512 reading takes ~3 minutes to complete and record (2:54) and 124 readings were taken in a 6-hour period.

The results are plotted in Figure 3 and show that noise conditions at the site on the day in question were better after noon than prior to noon. This indicates that the powerline may be having some variable influence on the noise conditions. We were actually testing for ~the opposite influence. As we begin surveying at the loop and as noise levels increased sharply at a given distance - ~a given time in the survey day - from the loop we were testing whether the afternoons were noisier. Had this been the case we would have changed procedure and started surveying at the ends of lines.

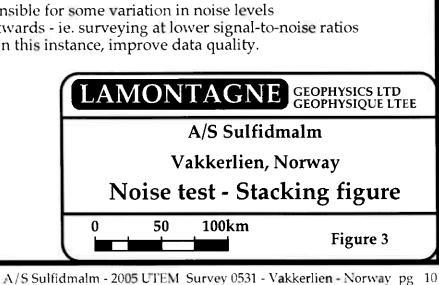
Using the higher pre-whitening level and doubling the loop wire made a difference when surveying the final two loops - Loop 3 and then Loop 2. Even then we needed to "move the loop closer to the area of interest" - extend Loop 2 northward to form Loop 2a - in order to resolve a noise-or-response issue on Lines 670 and 671E. Surveying from Loop 2a brought the area of interest/dispute within 4-600m of the loop front. Reasonably clean data could be efficiently collected and no response was detected. Of note, however, is that stacking times had to be sharply increased (4-8x) over one section of the lines surveyed. Past that section stacking could be reduced again despite the greater distance from the loop.



These are 124 Ch1 readings were taken at Line 137N 5910E 2005.11.10. The site selected was reasonably close (within ~100m) to the powerline and wellsheltered to reduce wind noise. Staking was deliberately set a little low for the site - 512 full-cycles (1024 half-cycles). A 512 reading takes ~3 minutes to complete and record (2:54) and 124 readings were taken in a 6-hour period.

The results are plotted in Figure 3 and show that noise conditions at the site on the day in question were better after noon than prior to noon. This indicates that:

- the powerline may be responsible for some variation in noise levels
- surveying from the loop outwards ie. surveying at lower signal-to-noise ratios in the afternoon may, in this instance, improve data quality.



#### CONCLUSIONS AND RECOMMENDATIONS

The results of the survey are summarized and presented as UTEM profiles in Appendix A. Overall the data quality is good - though in places it is noisy. The final Grid and Loop Locations are presented in Figure 2. The area surveyed is very resistive - little response is seen at even the earliest time-channels.

The profiles presented in Appendix A have been reduced with a grid corrected as well as possible using available information. The location of all survey points and loop locations were collected using a GPS system. For reference GPS collection for UTEM reduction should be more detailed along loop fronts. The goal along the loop front - and loop sides/back - is to recover the topographic shape of the loop as well as the loop/line intersection points.

In terms of logistics the survey ran very smoothly and the crew supplied by Falconbridge was excellent and is thanked for their efforts. Several small points should be noted for future surveys:

- If the same generator is to be used on future surveys it should be rigged with a larger gas tank. The small-volume gas tank currently on the generator required filling 2-3 times a survey day.
- Use of a heavier gauge wire (1.70mm diameter DAMID PE GR 2) on future surveys should be considered.

  As noted above: during this survey a Loops 2 and 3 were doubled. In practice it requires an additional effort to lay/retrieve double strands of wire. The total loop resistance is lowered, however, allowing a higher transmitter current. Signal-tonoise is improved, less stacking is required and surveying proceeds more quickly.

# Appendix A

0531 UTEM Profiles

**UTEM 3 Survey** 

Vakkerlien Norway

for

A/S Sulfidmalm

#### Presentation

The results of the survey are summarized and presented as UTEM profiles in Appendix A. The final grid and Loop Locations are presented in Figures 2. Overall the data quality is good - though in places it is noisy. Few conductive features are evident. A description of the standard plotting formats used and of the UTEM System is presented in Appendix C.

The profiles are listed by Loop number and presented as 3-axis profiles in the order:

Hz continuous norm Ch1 reduced (blue separator)
Hz point normalized Ch1 reduced (pink separator)

#### Outline of surface profile types

Hz continuous norm

Ch1 reduced

(blue separator)

Continuous normalization is useful for detection of the presence anomalies at any position on a profile. The anomaly shape is distorted by the normalization to the local field. As the field gets very big near the wire the continuously normalized Ch1 tends towards zero.

top axis - Ch5-10 middle axis - Ch2-5 bottom axis - Ch1

bottom axis - topography - no vertical exaggeration

Hz point normalized

Ch1 reduced

(pink separator)

normalization point: all data

ta ~300m out from the loop-front centre

Point normalized data is useful for interpretation of responses. Anomaly shape is preserved as is the amplitude if the normalization point is local to the anomaly.

All data has been point normalized to a the field at a point ~300m out from the centre of the loop front. Note that this field value is intermediate and it was chosen because the survey was roughly half inside-the-loop and half off-loop. Normalizing to an intermediate point allows the interpretation of responses along the entire line. The amplitude of responses close to (further from) the loop front will be blown up (muted). Note: Typically the normalization point for off-loop profiles is 4-500m out from the centre of the loop front and for inside-the-loop profiles it is the loop centre.

The disadvantage of point normalization is that small errors in location near the wire and in current tend to appear as large errors in Ch1. If the loop/station locations and the current are accurately known then point normalized Ch1 (in the absence of a local conductor) will tend to be continuous approaching the wire - unlike the continuously normalized Ch1 which, as described above, will dip to zero.

top axis - Ch5-10 middle axis - Ch2-5 bottom axis - Ch1

bottom axis - topography - no vertical exaggeration

UTEM Survey 0531 -A/S Sulfidmalm Vakkerlien, Norway Appendix A pg A1

### **List of Data Collected and Plotted**

### Vakkerlien 2005 Grid

### Surface coverage - @ 3.251 Hertz

	Line	coverage	
Loop 01	Line 329N	5500N - 6550N	1050m
	Line 330N Line 331N	5450N - 6550N 5450N - 6550N	1100m 1100m
	Line 332N	5450N - 6550N	1100m
	Line 333N	5450N - 6550N	1100m
	Line 334N	5450N - 6550N	1100m
	Line 335N	5450N - 6550N	1100m
	Line 336N	5450N - 6550N	1100m
	Line 337N	5450N - 6550N	1100m
	•	Vakkerlien Loop 01 Total	9850m
Loop 02	Line 309N	5825N - 7225N	1400m
(E-W)	Line 311N	5825N - 7225N	1400m
	Line 313N	5825N - 8200N	21 <b>7</b> 5m
	Line 315N	5825N - 7225N	1400m
	Line 317N	5825N - 7225N	1400m
	Line 319N	5825N - 7225N	1400m
(N-S))	Line 663E	700N - 2900N	2200m
	Line 664E	700N - 2900N	2200m
	Line 665E Line 666E	700N - 2900N 700N - 2900N	2200m 2200m
	Line 667E	700N - 2900N 700N - 2900N	2200m
	Line 668E	2100N - 2900N	800m
	Line 669E	2100N - 2900N	800m
	Line 670E	2100N - 3150N	1050m
	Line 6 <b>7</b> 1E	2500N - 3150N	650m
	0.20.1	Vakkerlien Loop 02 Total	23675m
Loop 02a	Line 670E	2800N - 3400N	600m
5004	Line 671E	2800N - 3400N	600m
		Vakkerlien Loop 02a Total	1200m
Loop 03	Line 307N	7125N - 8525N	1400m
Davip ss	Line 309N	7125N - 8525N	1400m
	Line 311N	6125N - 8525N	2400m
	Line 313N	7125N - 8525N	1400m
	Line 315N	7125N - 8525N	1400m
	Line 317N	6100N - 8525N	2425m
		Vakkerlien Loop 03 Total	10425m

#### List of Data Collected and Plotted

### Vakkerlien 2005 Grid

### Surface coverage - @ 3.251 Hertz

	Line	coverage	
Loop 04	Line 286N Line 288N Line 290N Line 292N Line 294N	7600N - 8500N 7400N - 8500N 7400N - 8500N 7400N - 8500N 7400N - 8500N Vakkerlien Loop 04 Total	900m 1100m 1100m 1100m 1100m 5300m
		Vakkerlien 2005 Total	50.450km

Note: The total of 51.750km listed in Appendix B - the Production Diary includes some sections of Loop 1 reread at increased stacking to improve data quality.

## Vakkerlien

# Loop 1

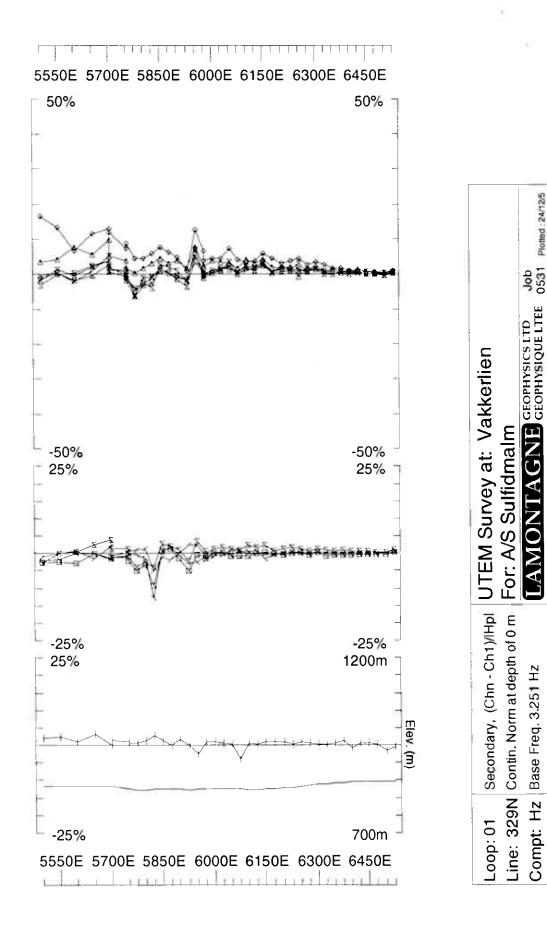
Hz @3.251 Hz frequency

continuous norm

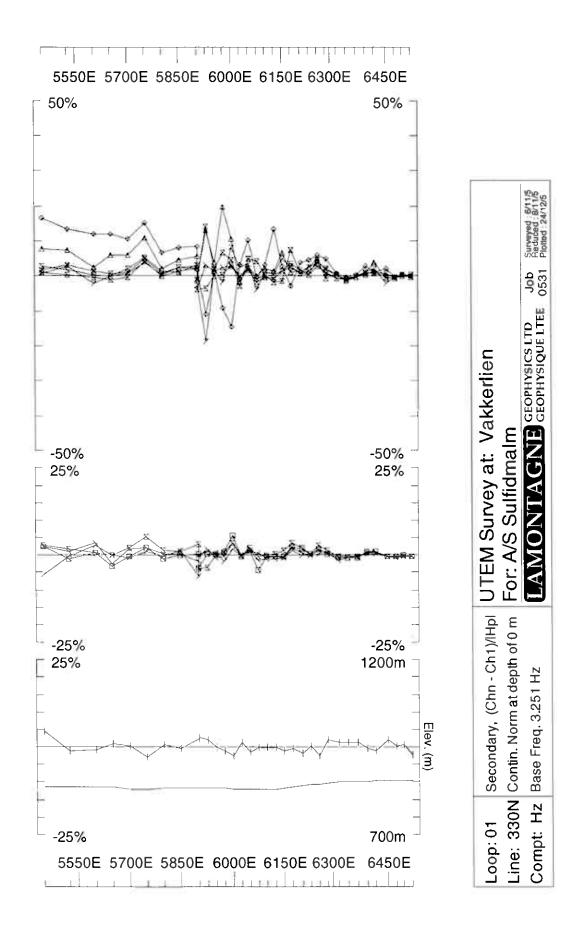
Ch1 reduced

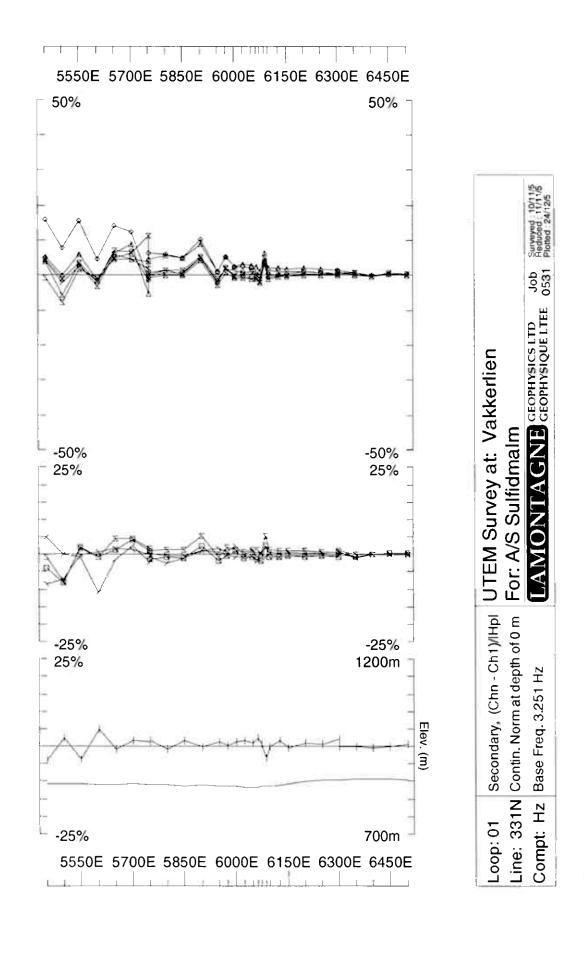
Loop 01	Line 329N	5500N - 6550N	1050m
	Line 330N	5450N - 6550N	1100m
	Line 331N	5450N - 6550N	1100m
	Line 332N	5450N - 6550N	1100m
	Line 333N	5450N - 6550N	1100m
	Line 334N	5450N - 6550N	1100m
	Line 335N	5450N - 6550N	1100m
	Line 336N	5450N - 6550N	1100m
	Line 337N	5450N - 6550N	1100m
	Vakk	erlien Loop 01 Total	9850m

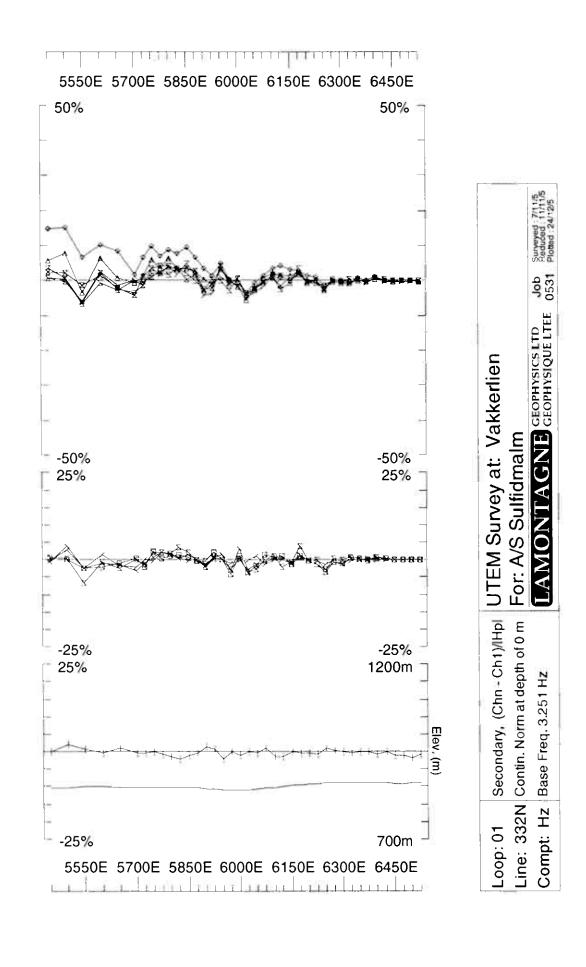
Loop 1 - continuous norm

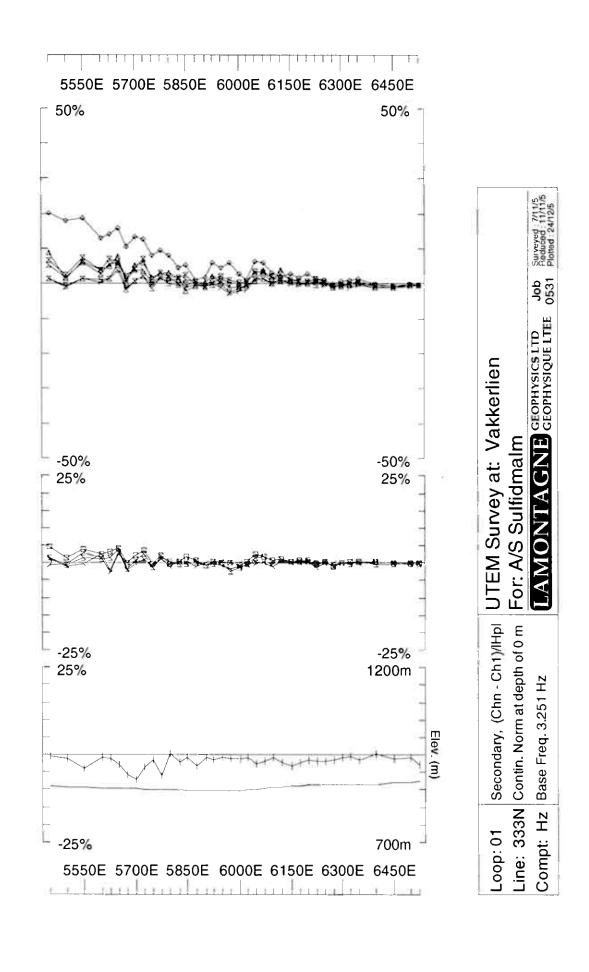


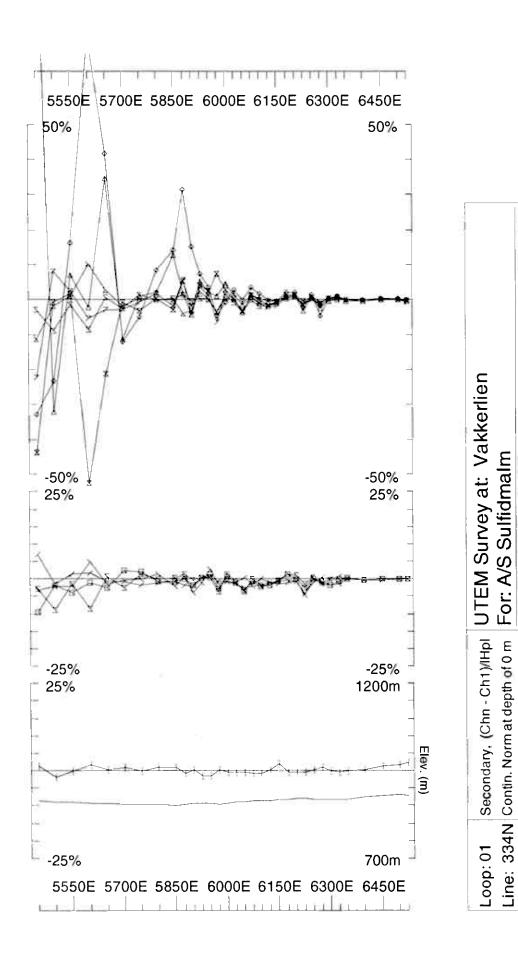
Plotted: 24/12/5









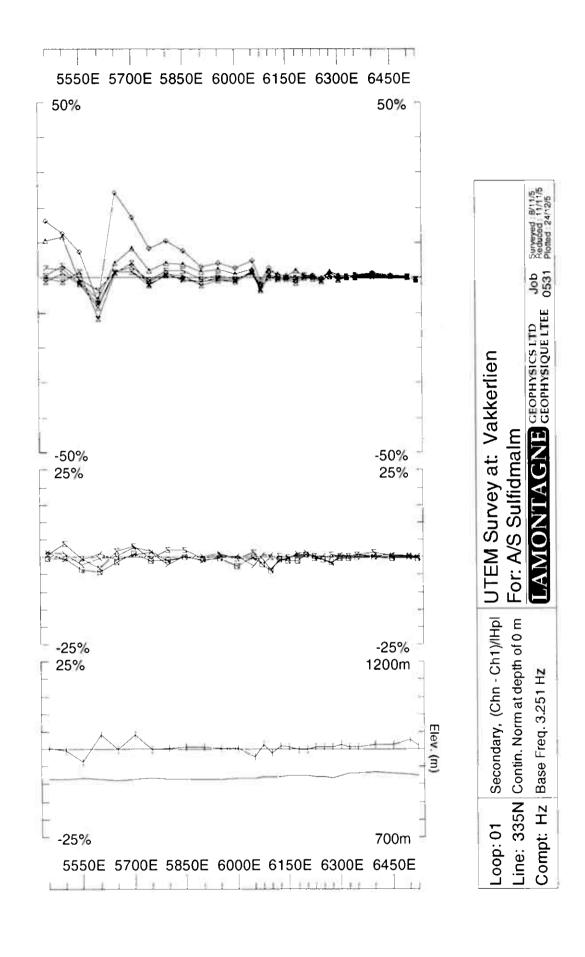


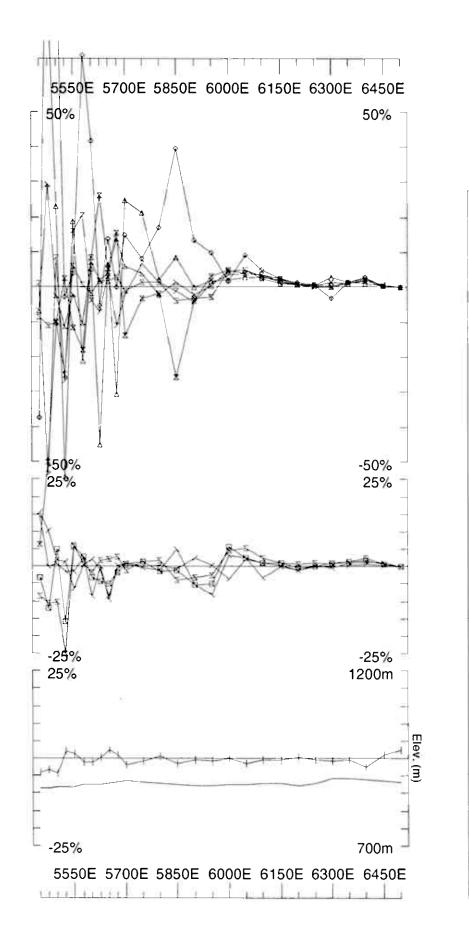
Job Surveyed 8/11/5 0531 Plotted 24/12/5

NE GEOPHYSICS LTD GEOPHYSIQUE LTEE

Base Freq. 3.251 Hz

Compt: Hz



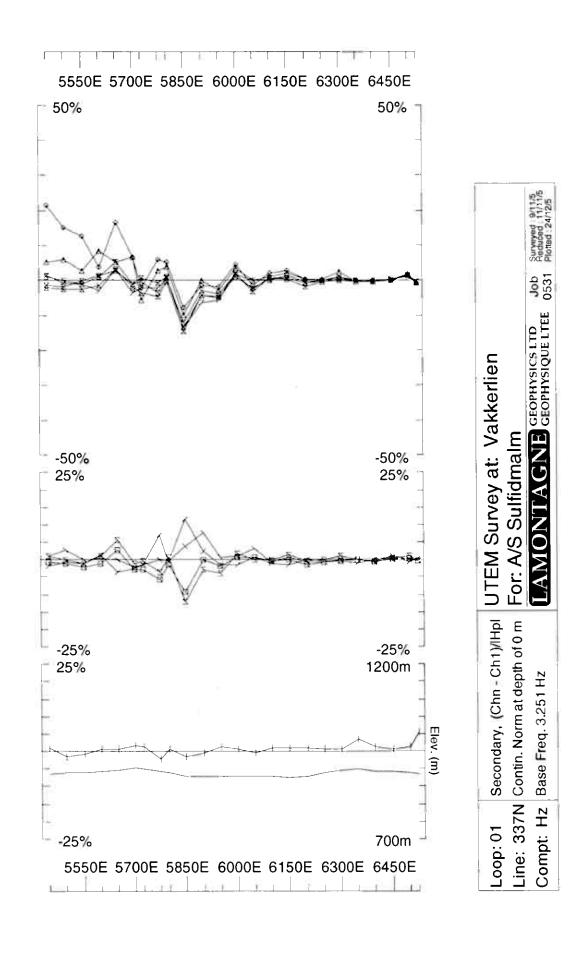


Secondary, (Chn - Ch1)/IHpl Line: 336N Contin. Norm at depth of 0 m Base Freq. 3.251 Hz Compt: Hz

Loop: 01

UTEM Survey at: Vakkerlien For: A/S Sulfidmalm

Job Surveyed 9/11/5 Reduced 11/11/5 0531 Picted 24/12/5 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE



## Vakkerlien

# Loop 1

Hz @3.251 Hz frequency

point norm

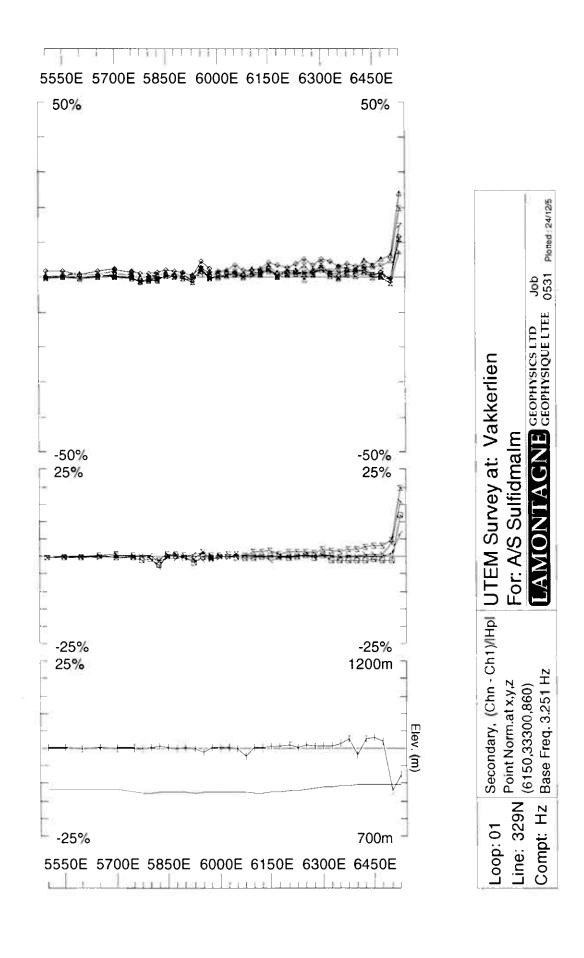
@

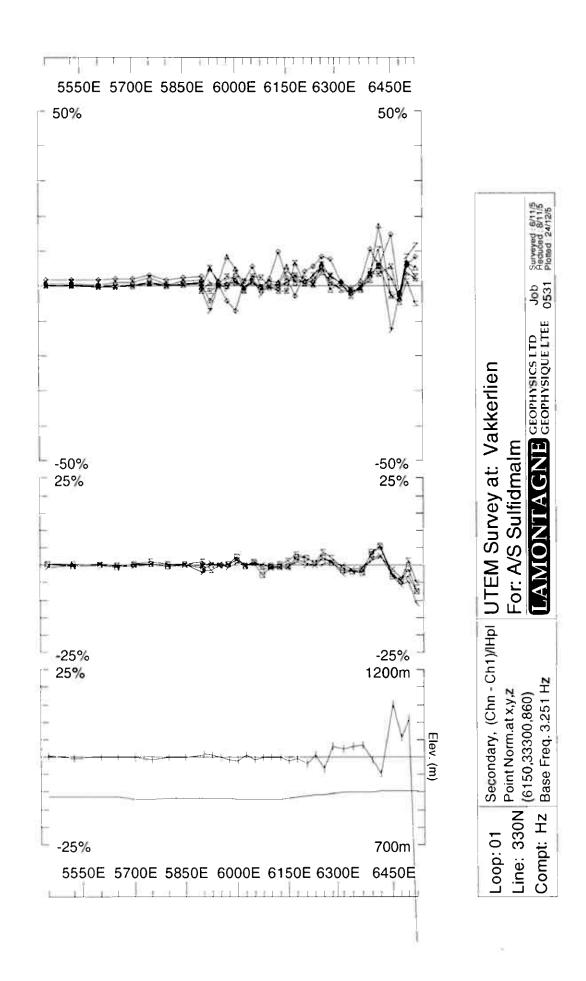
(x,y,z) = (6150E,33300N, 860 m.a.s.l.)

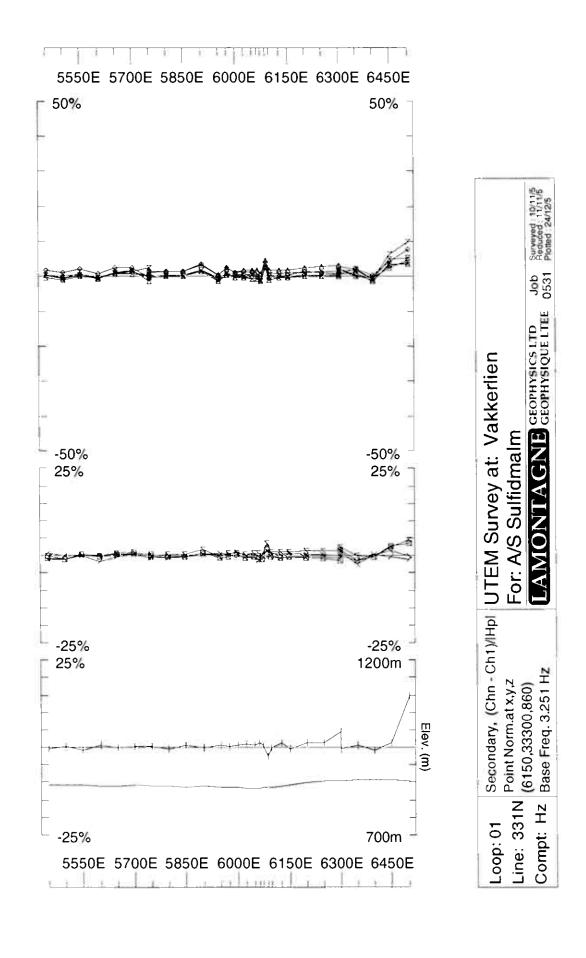
#### Ch1 reduced

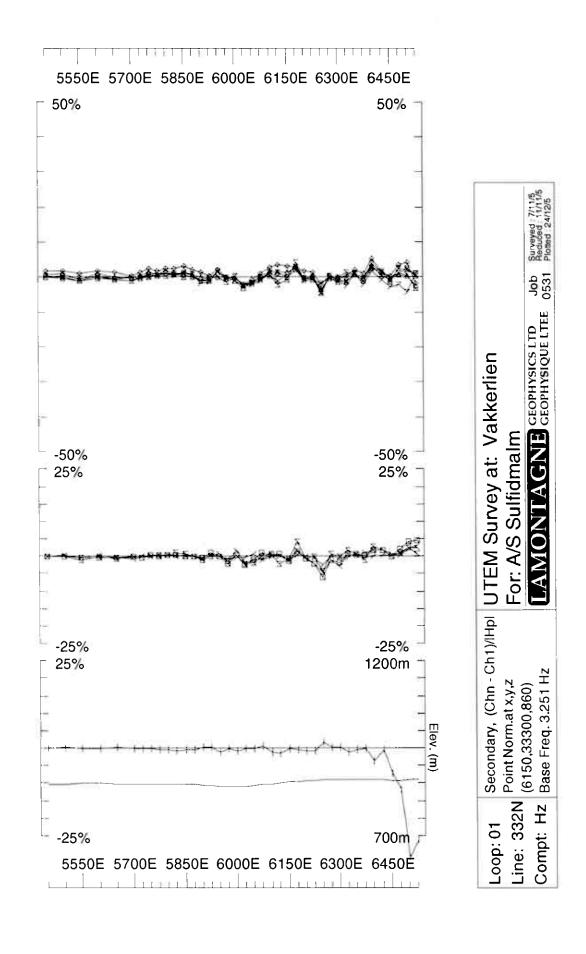
Loop 01	Line 329N	5500N - 6550N	1050m
Double Associate	Line 330N	5450N - 6550N	1100m
	Line 331N	5450N - 6550N	1100m
	Line 332N	5450N - 6550N	1100m
	Line 333N	5450N - 6550N	1100m
	Line 334N	5450N - 6550N	1100m
	Line 335N	5450N - 6550N	1100m
	Line 336N	5450N - 6550N	1100m
	Line 337N	5450N - 6550N	1100m
	Vakk	erlien Loop 01 Total	9850m

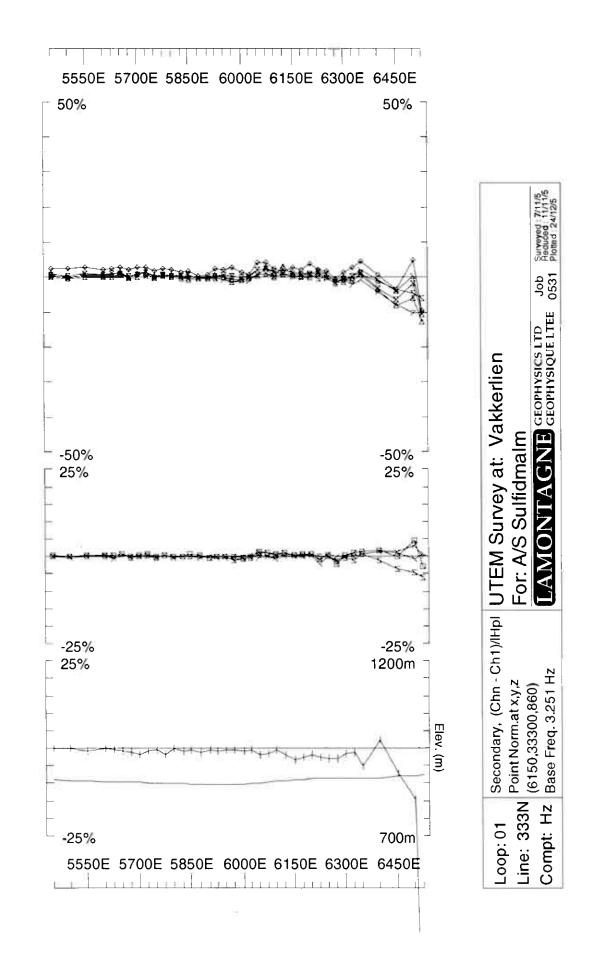
Loop 1 - point norm

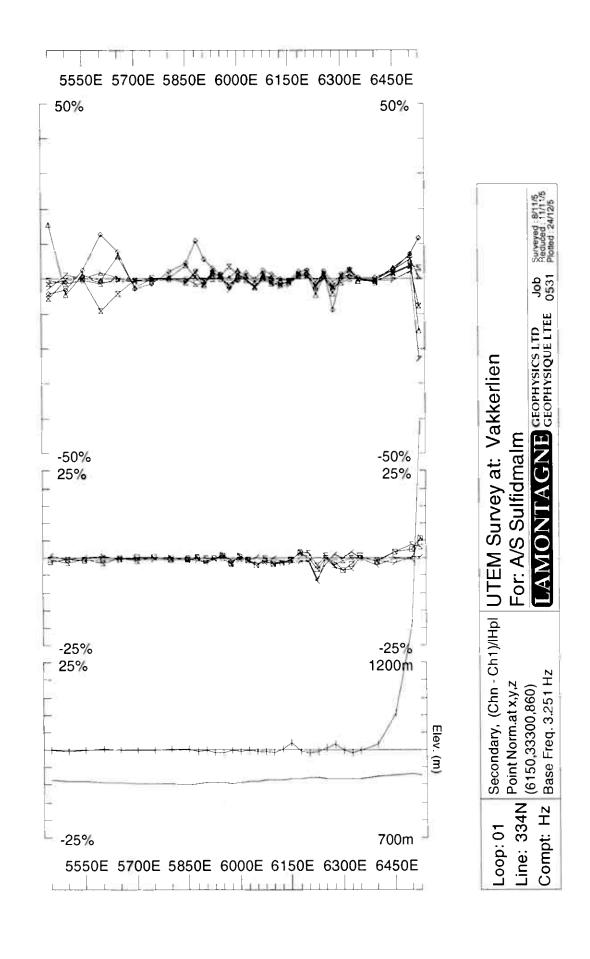


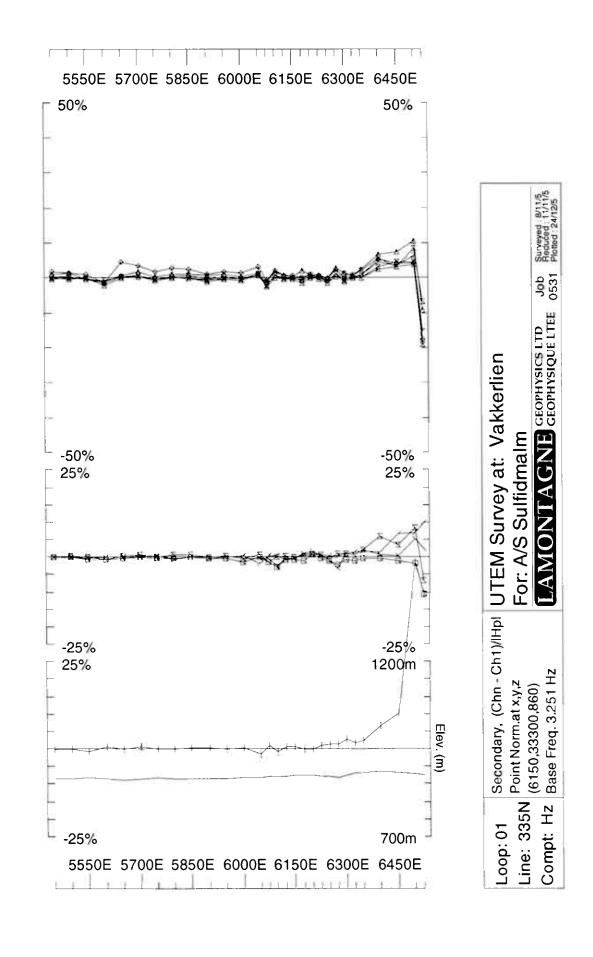


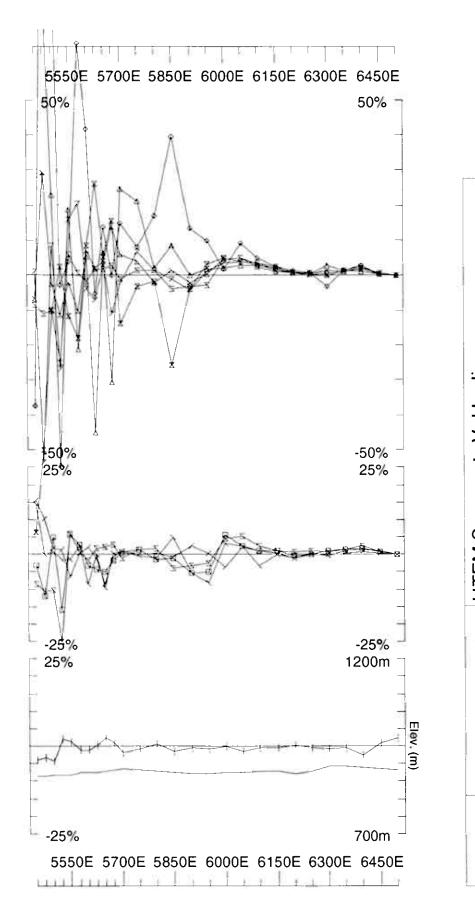








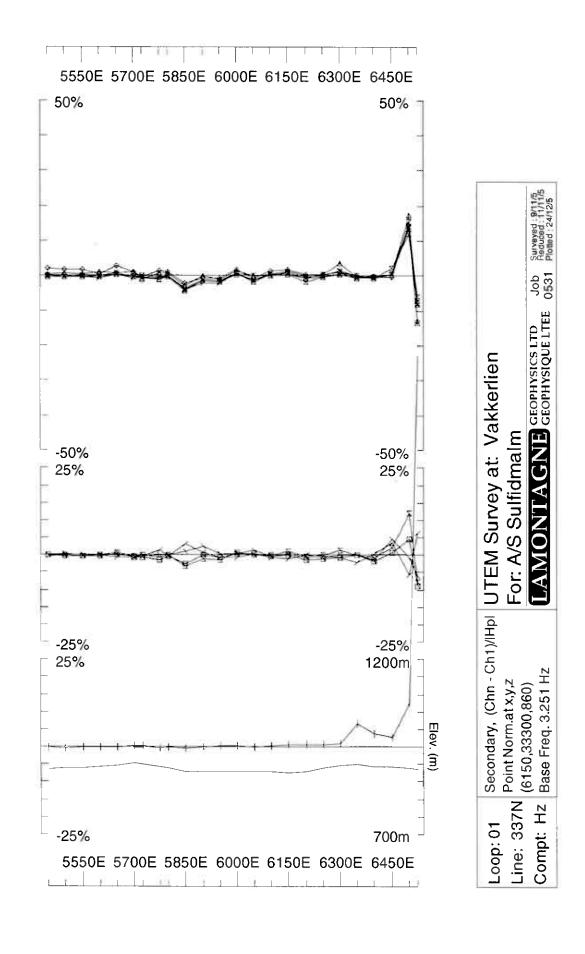




Loop: 01 Secondary, (Chn - Ch1)/IHpl UTE Line: 336N Contin. Norm at depth of 0 m For: Compt: Hz Base Freq. 3.251 Hz

UTEM Survey at: Vakkerlien For: A/S Sulfidmalm

MONTAGNE GEOPHYSIQUELTEE 0531 Plotted 24:25



## Vakkerlien

# Loop 2

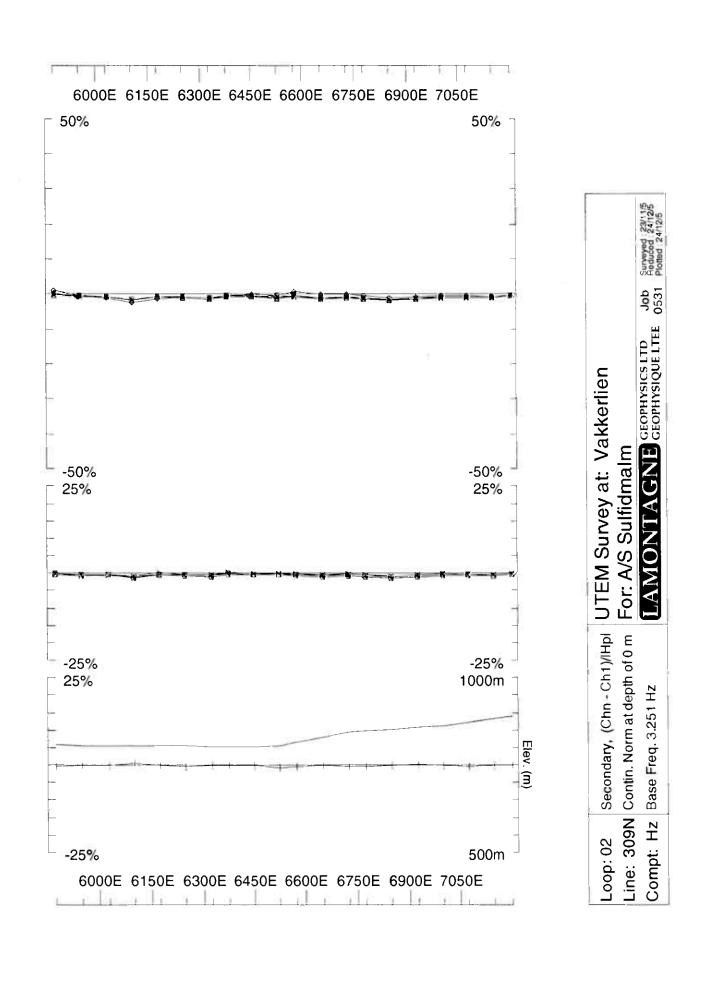
Hz @3.251 Hz frequency

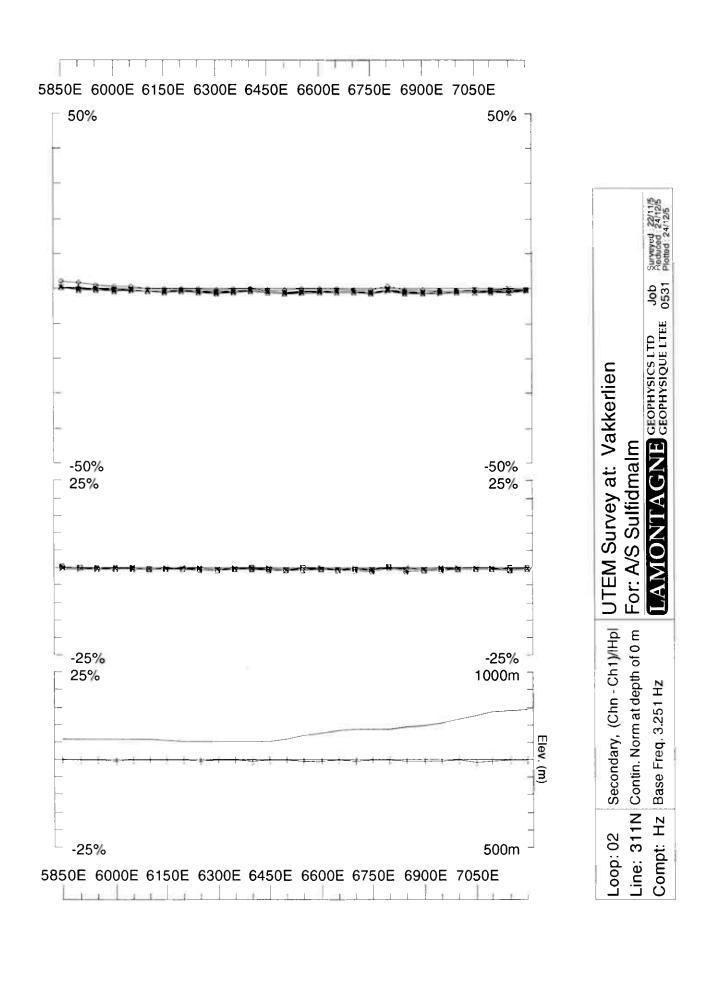
#### continuous norm

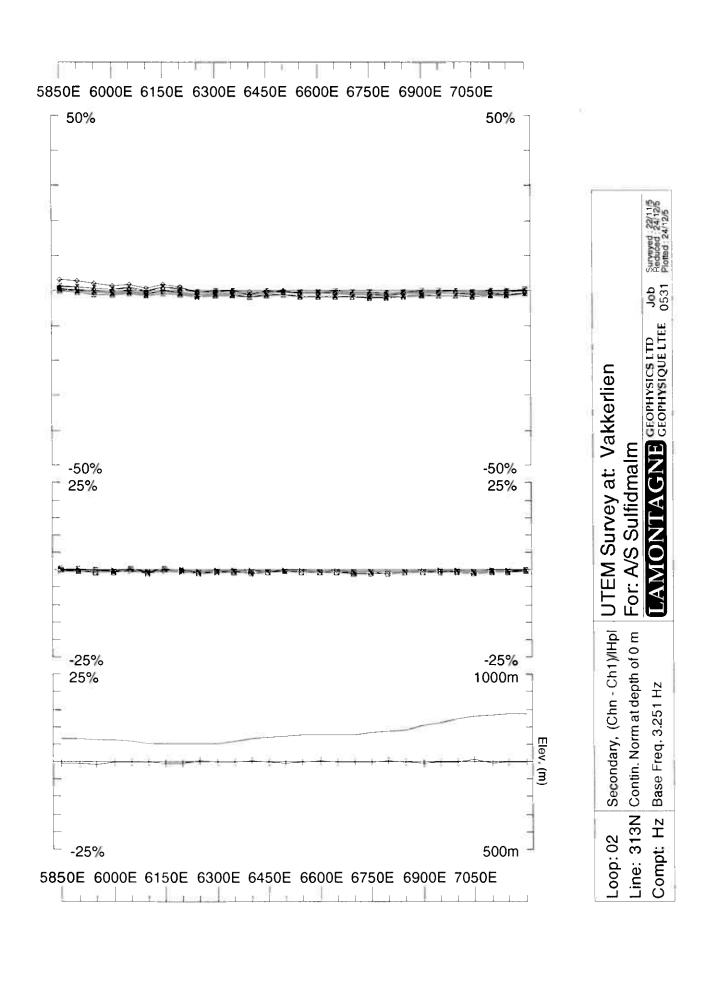
### Ch1 reduced

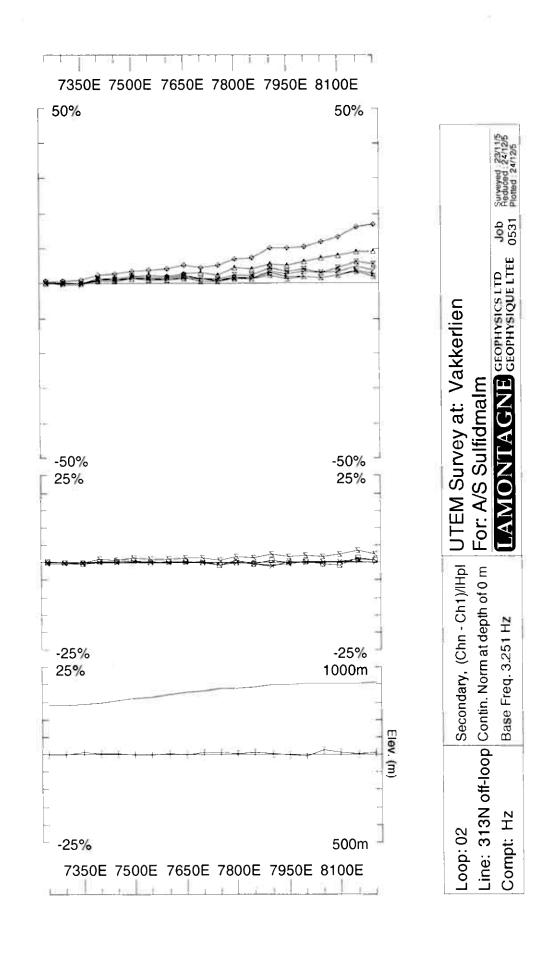
Loop 02	Line 309N	5825N - 7225N	1400m
(E-W)	Line 311N	5825N - 7225N	1400m
	Line 313N	5825N - 7225N	
	off-loop	7225N - 8000N	2175m
	Line 315N	5825N - 7225N	1400m
	Line 317N	5825N - 7225N	1400m
	Line 319N	5825N - 7225N	1400m
(N-S))	Line 663E	700N - 2900N	2200m
	Line 664E	700N - 2900N	2200m
	Line 665E	700N - 2900N	2200m
	Line 666E	700N - 2900N	2200m
	Line 667E	700N - 2900N	2200m
	Line 668E	2100N - 2900N	800m
	Line 669E	2100N - 2900N	800m
	Line 670E	2100N - 3150N	1050m
	Line 671E	2500N - 3150N	650m
	Vakkerlie	en Loop 02 Total	23475m

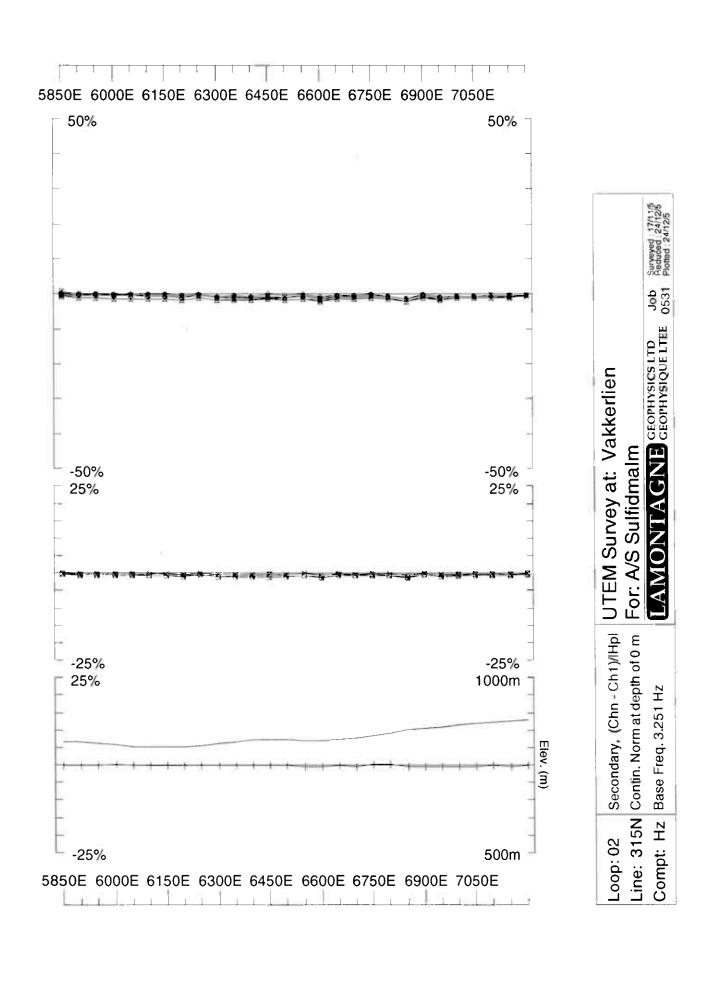
Loop 2 - continuous norm

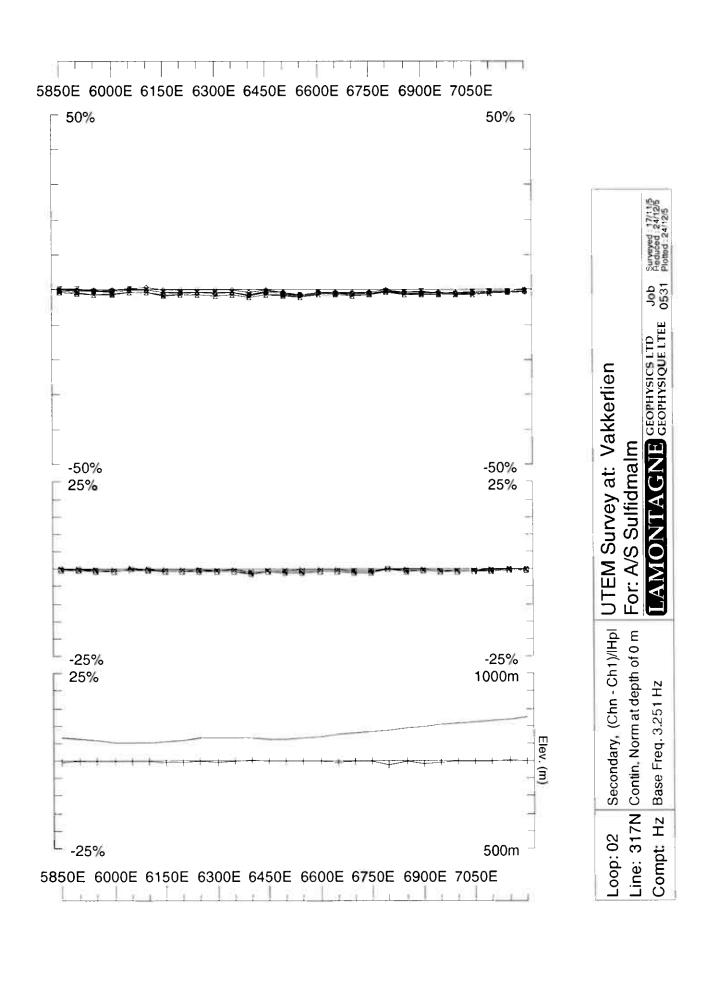


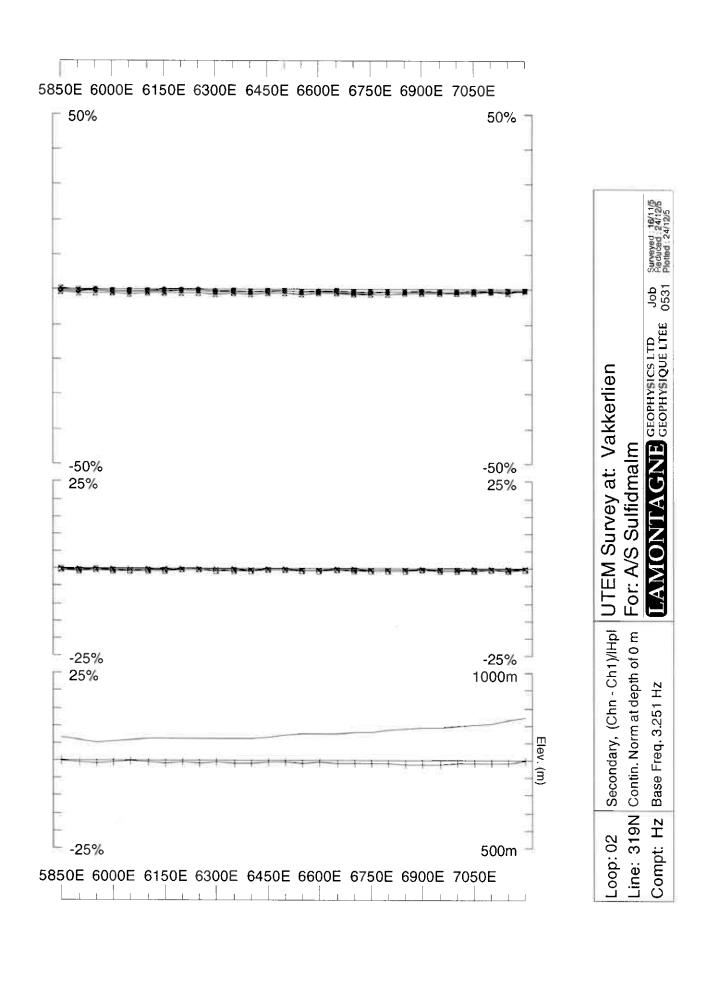


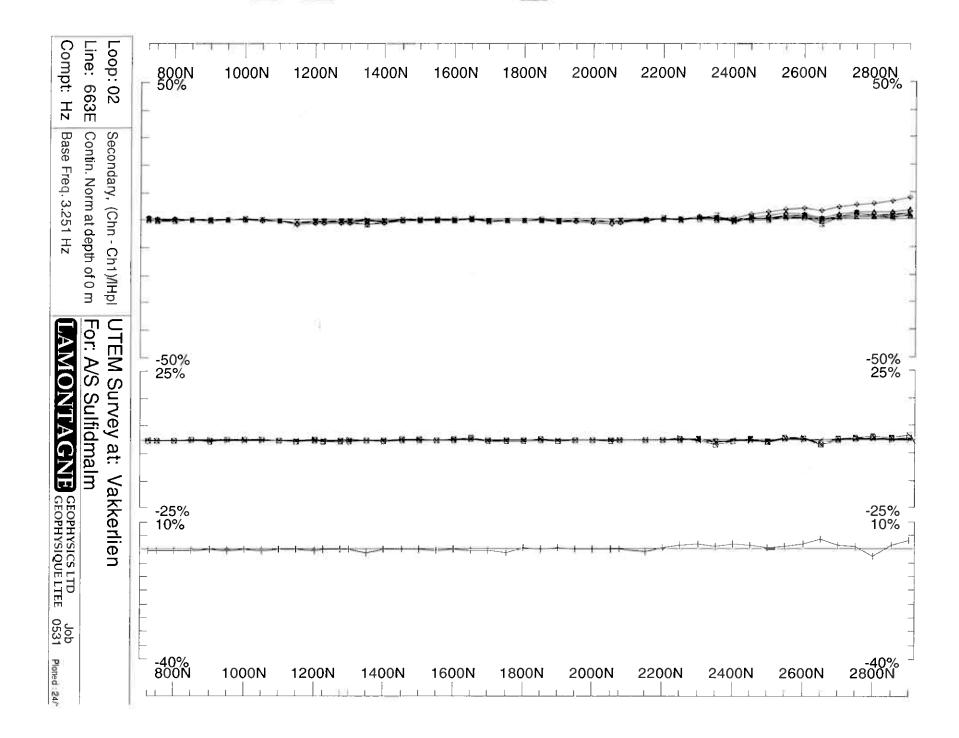


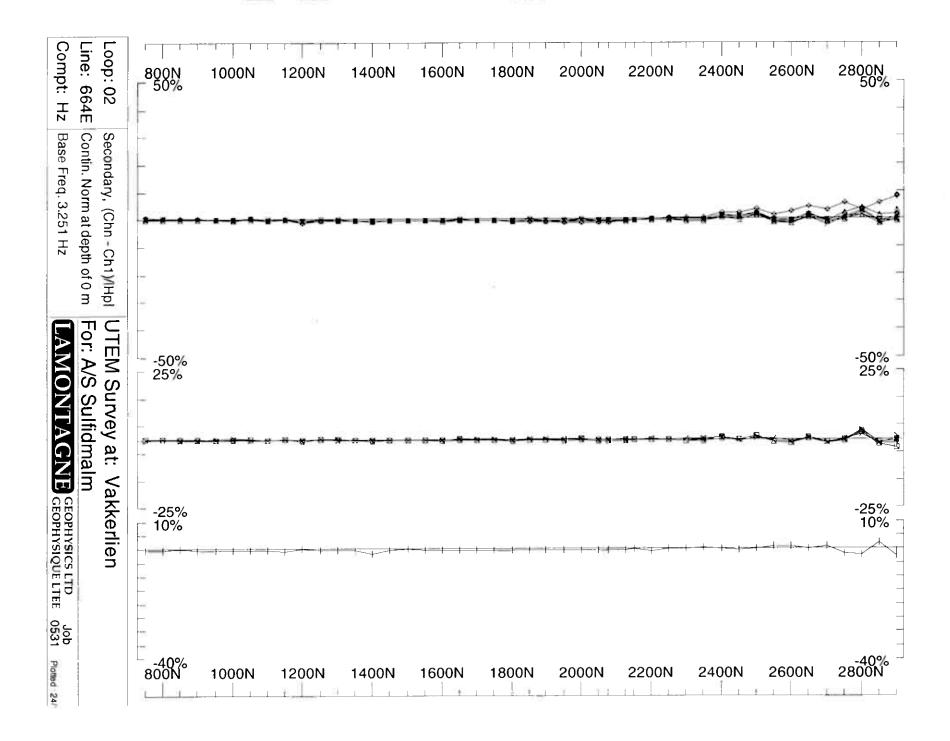


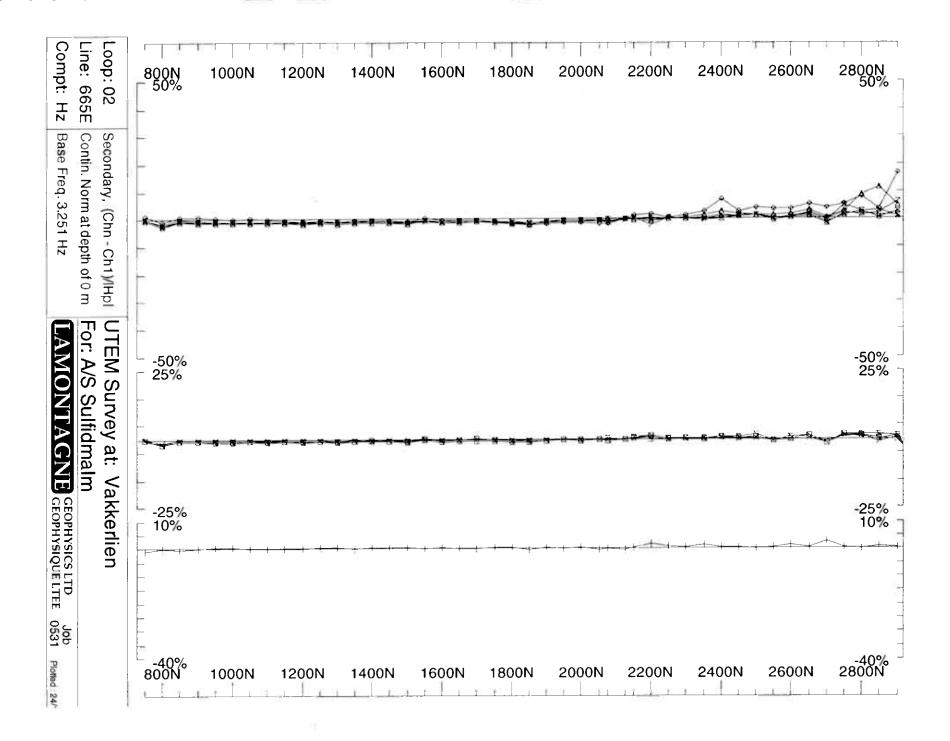


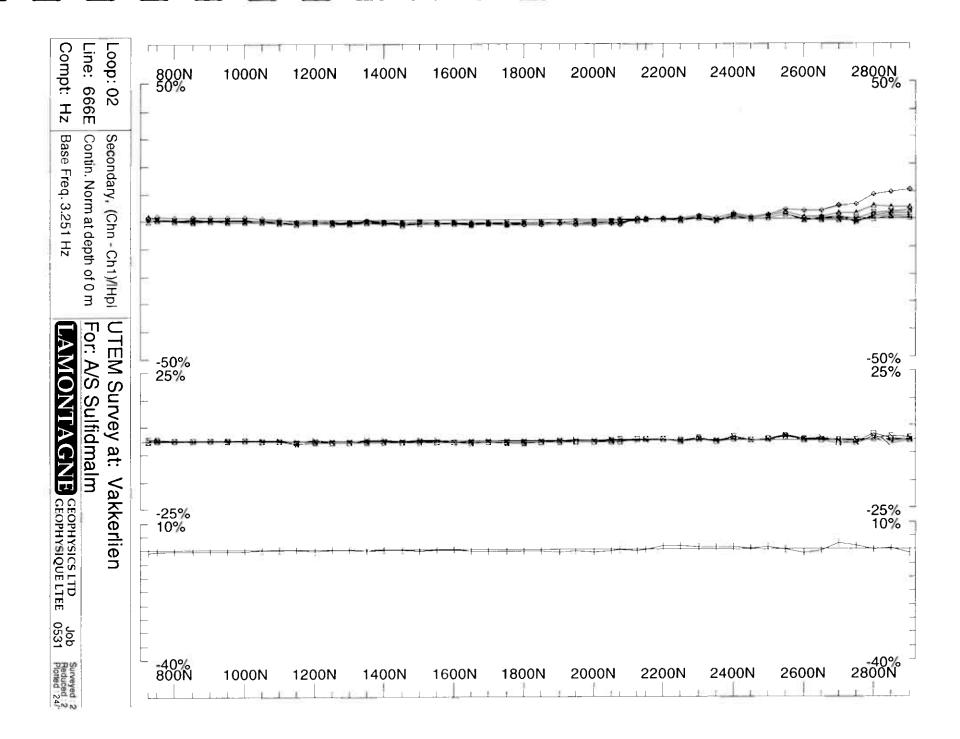


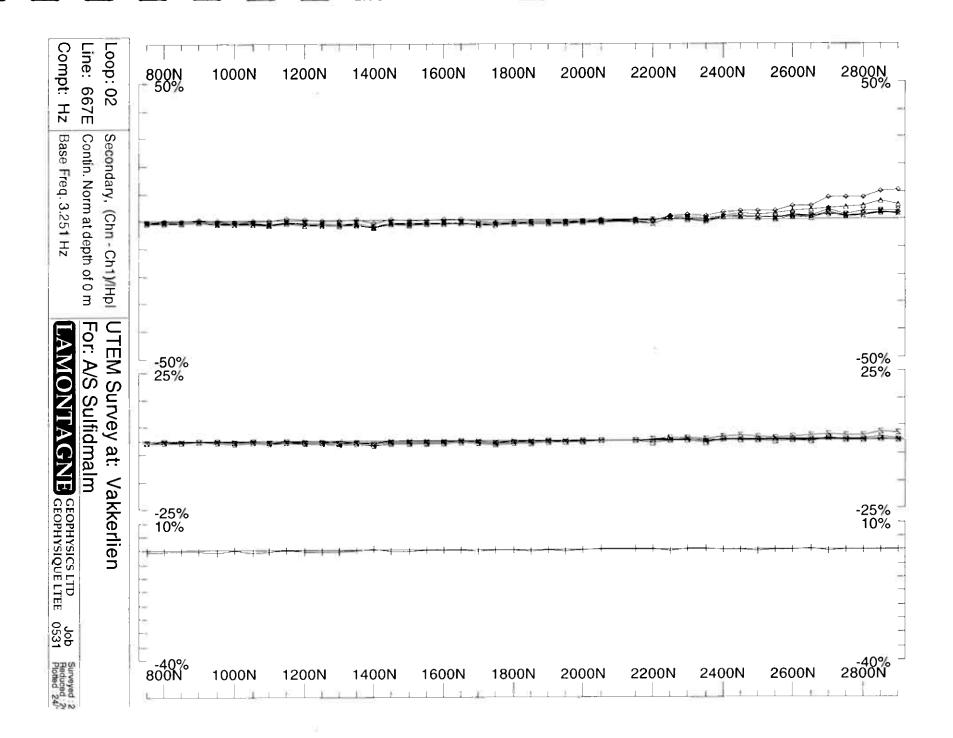


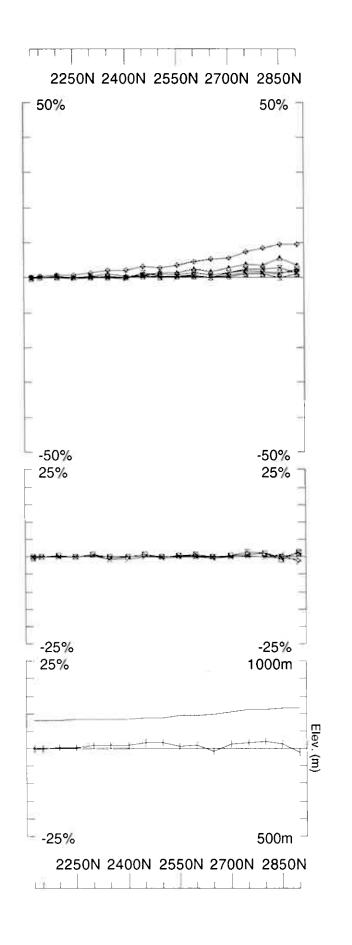






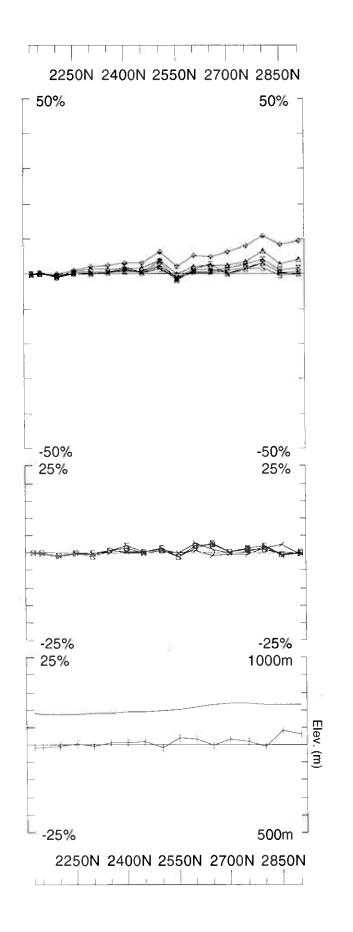




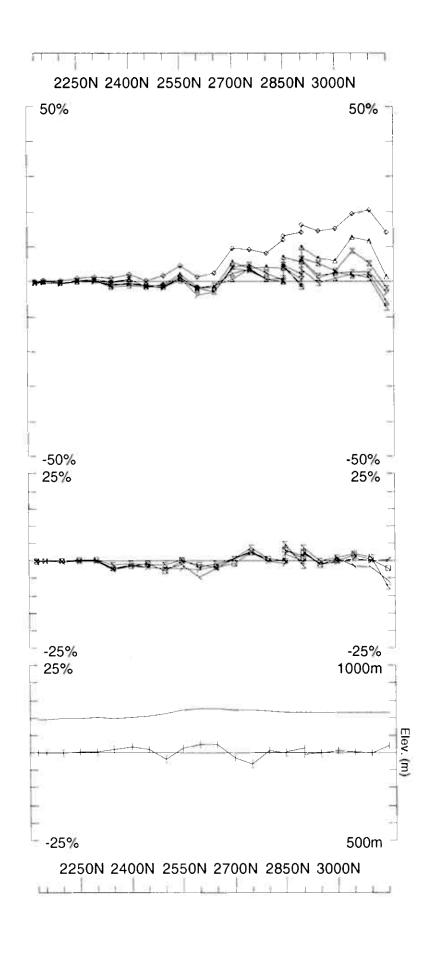


Job Surveyed :18/11/5 Reduced :24/12/5 0531 Plotted : 24/12/5 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE UTEM Survey at: Vakkerlien For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Line: 668E Contin. Norm at depth of 0 m Compt: Hz | Base Freq. 3.251 Hz

Loop: 02



Job 0531 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Contin. Norm at depth of 0 m Compt: Hz | Base Freq. 3.251 Hz Line: 669E Loop: 02



of 0 m For: A/S Sulfidmalm

CAMONTAGNE GEOPHYSICS LTD

Job Surveyed 177115

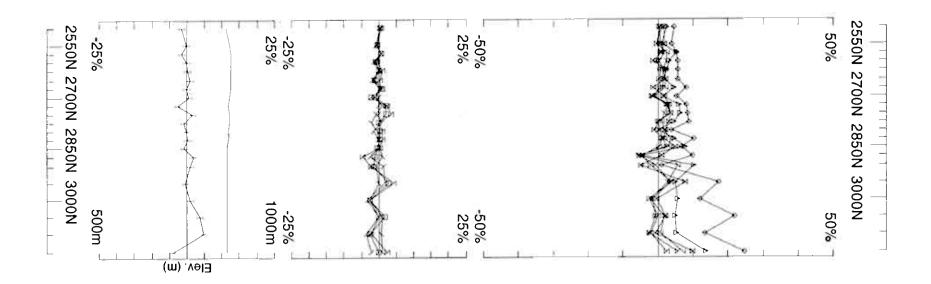
GEOPHYSICS LTD

Job Surveyed 177115

GEOPHYSICS LTD

GEOPHYSIQUE LTEE 0531

Loop: 02 Secondary, (Chn - Ch1)/IHpl U Line: 670E Contin. Norm at depth of 0 m For Compt: Hz Base Freq. 3.251 Hz



Loop: 02

Secondary, (Chn - Ch1)/IHpl

Line: 671E Contin. Norm at depth of 0 m

Compt: Hz Base Freq. 3.251 Hz

UTEM Survey at: Vakkerlien

For: A/S Sulfidmalm

LAMONTAGNE GEOPHYSICS LTD JOB 0531

# Loop 2

Hz @3.251 Hz frequency

point norm

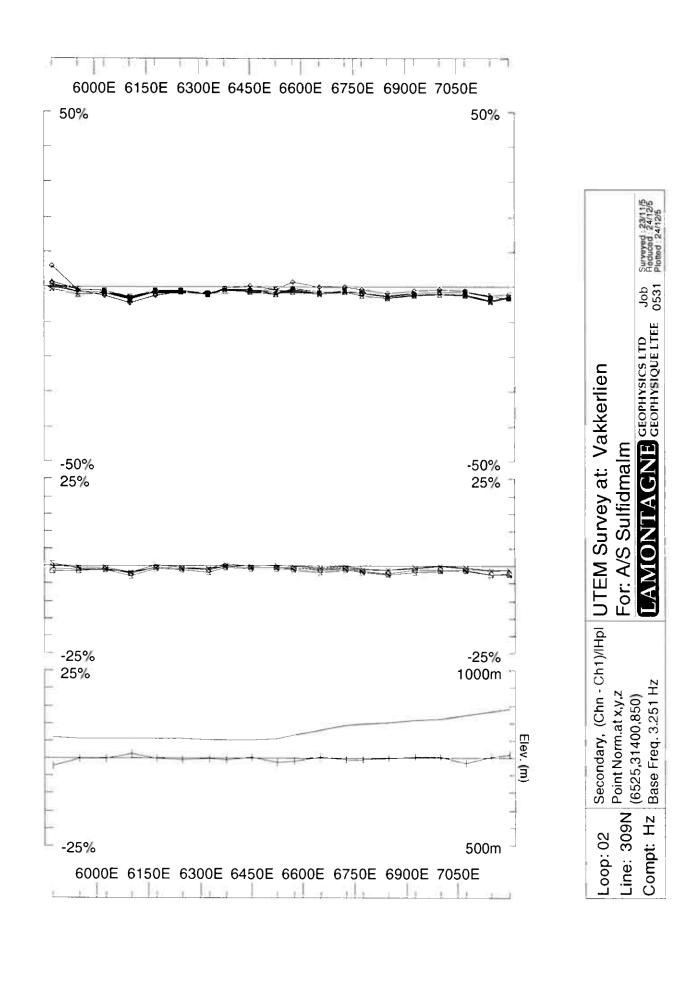
@

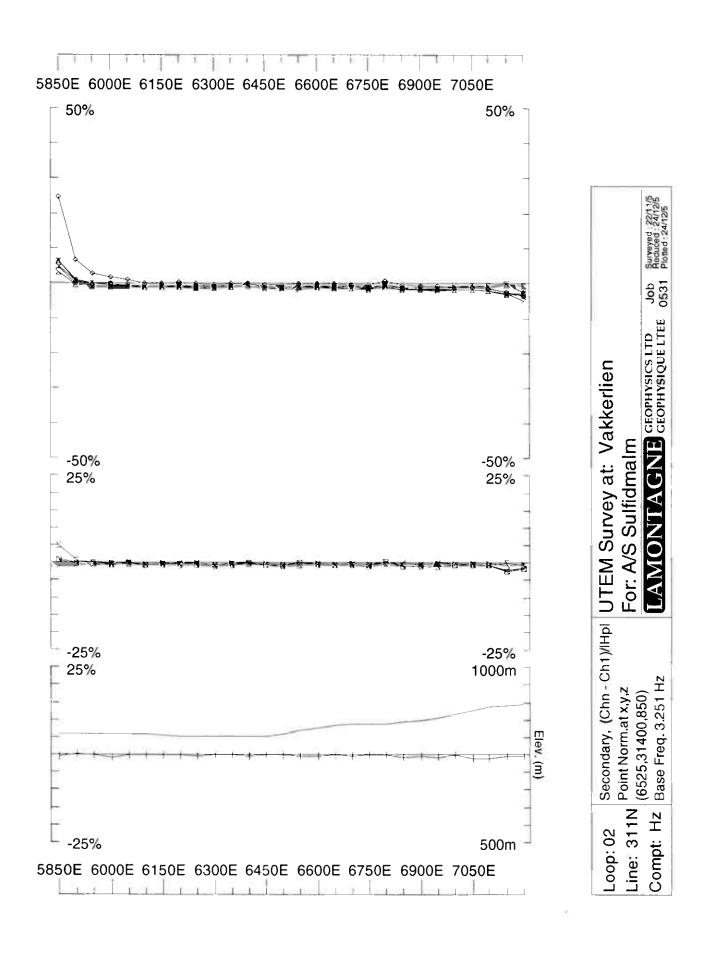
(x,y,z) = (6525E,31400N, 850 m.a.s.l.)

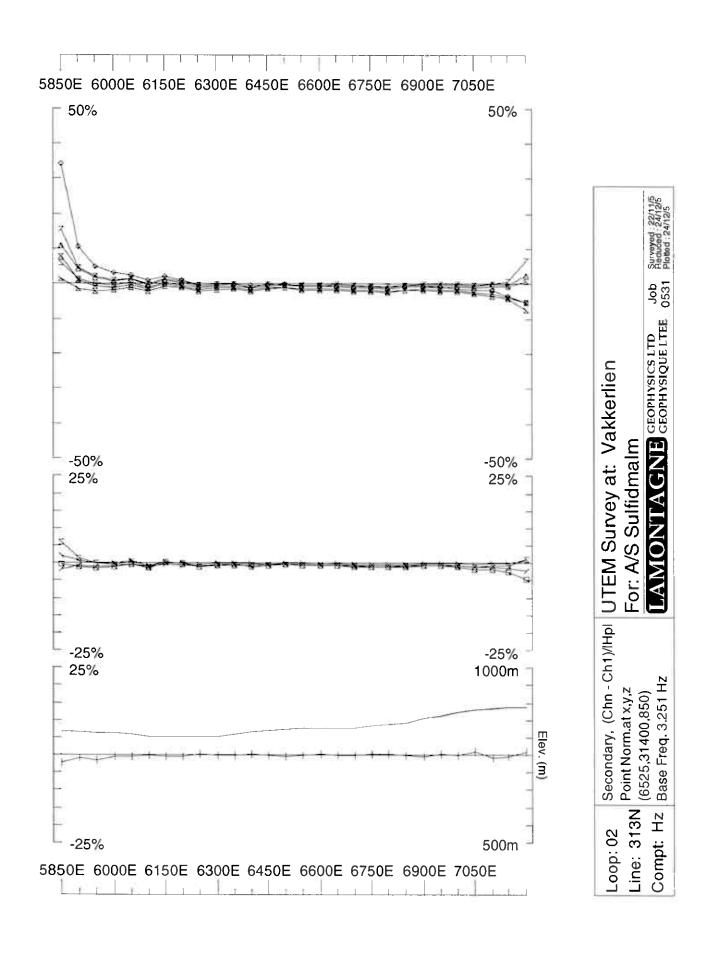
#### Ch1 reduced

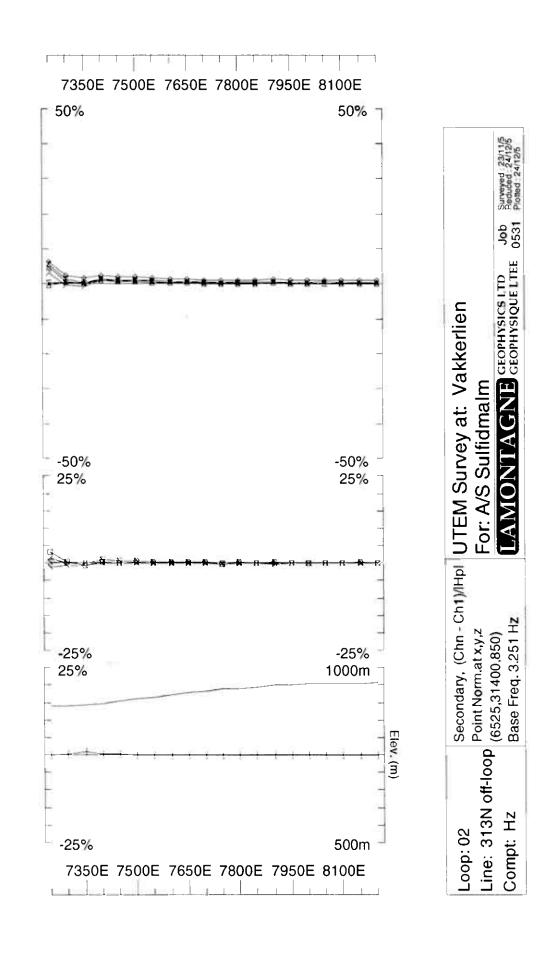
Loop 02	Line 309N	5825N - 7225N	1400m
(E-W)	Line 311N	5825N - 7225N	1400m
	Line 313N	5825N - 8000N	2175m
	Line 315N	5825N - 7225N	1400m
	Line 317N	5825N - 7225N	1400m
	Line 319N	5825N - 7225N	1400m
(N-S))	Line 663E	700N - 2900N	2200m
	Line 664E	700N - 2900N	2200m
	Line 665E	700N - 2900N	2200m
	Line 666E	700N - 2900N	2200m
	Line 667E	700N - 2900N	2200m
	Line 668E	2100N - 2900N	800m
	Line 669E	2100N - 2900N	800m
	Line 670E	2100N - 3150N	1050m
	Line 671E	2500N - 3150N	650m
	Vak	kerlien Loop 02 Total	23475m

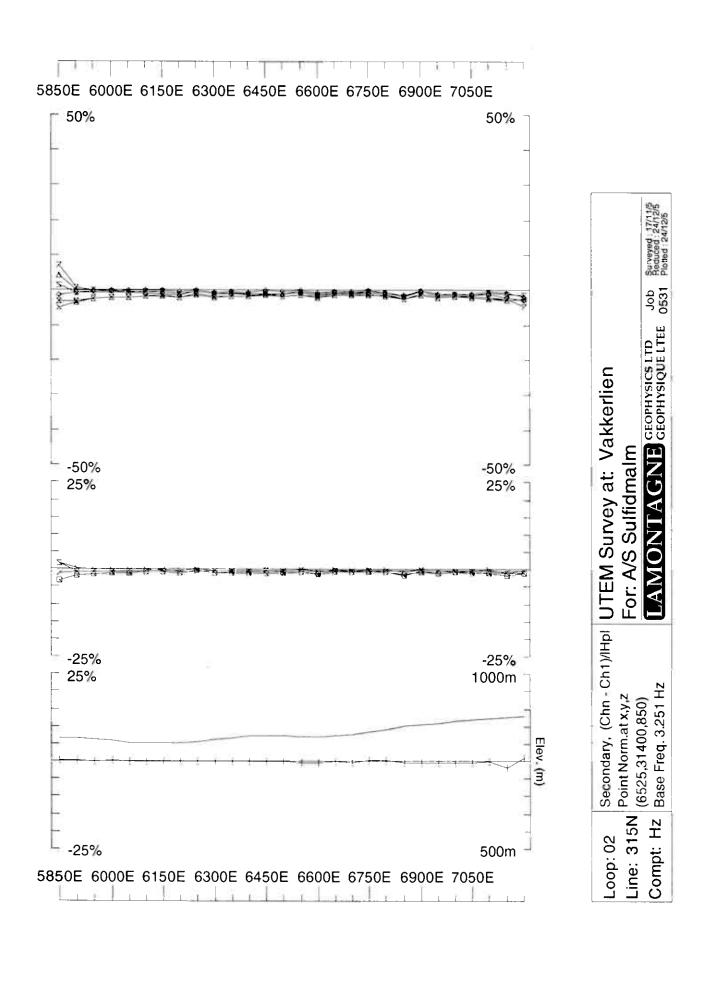
Loop 2 - point norm

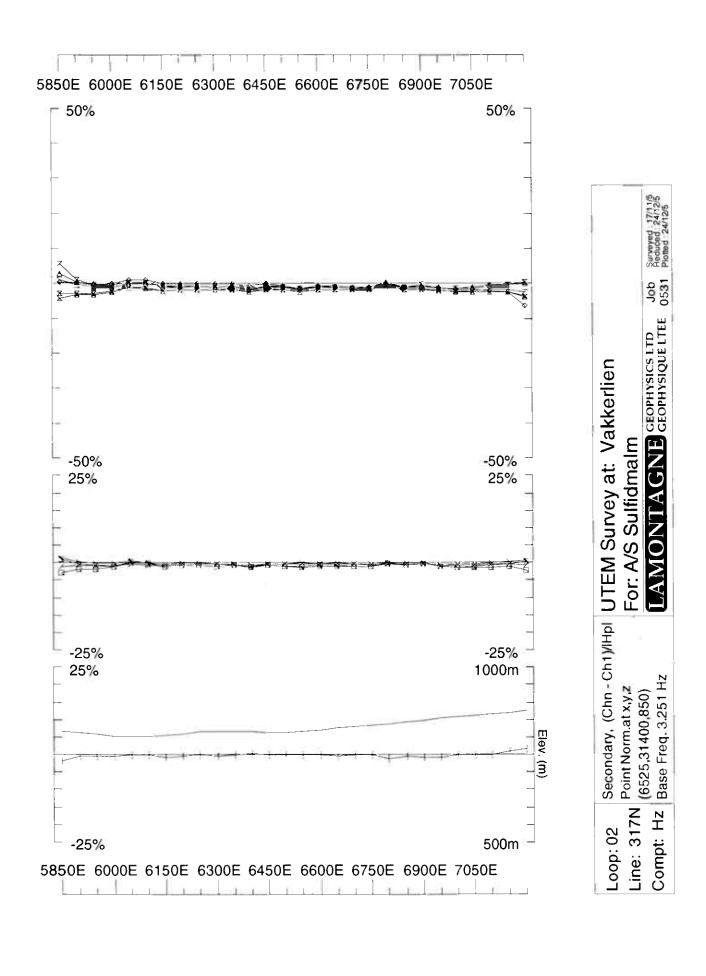


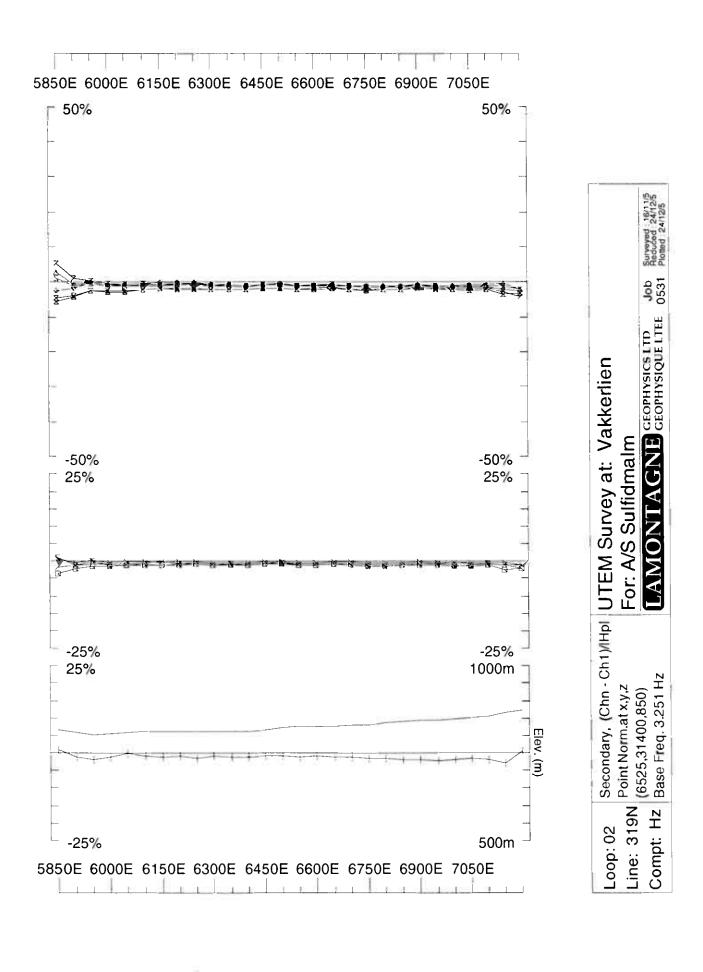


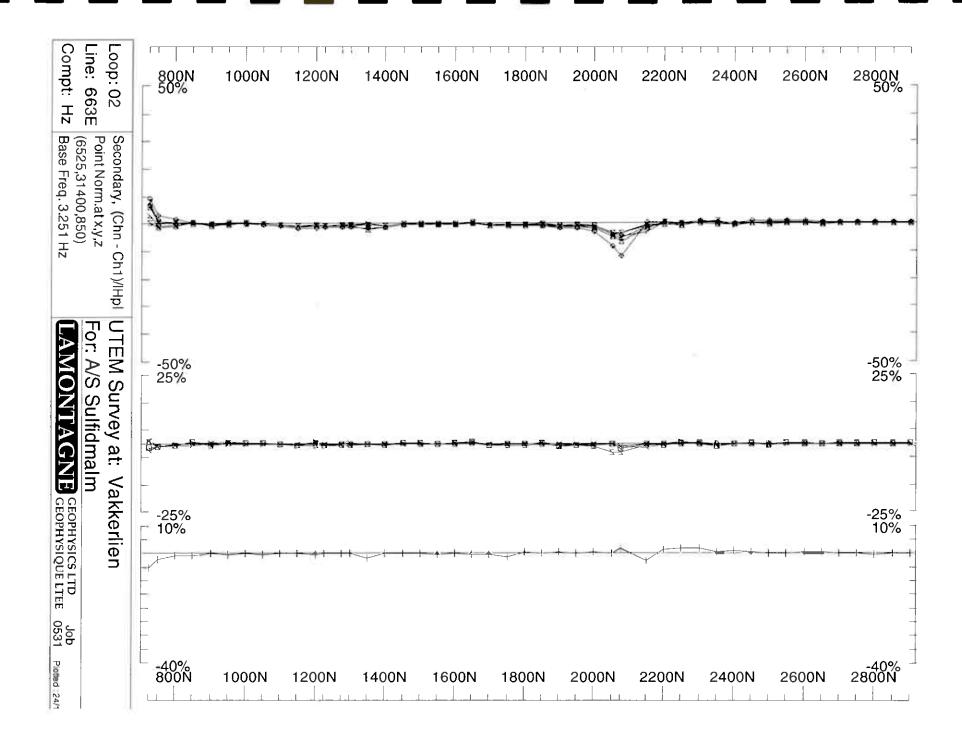


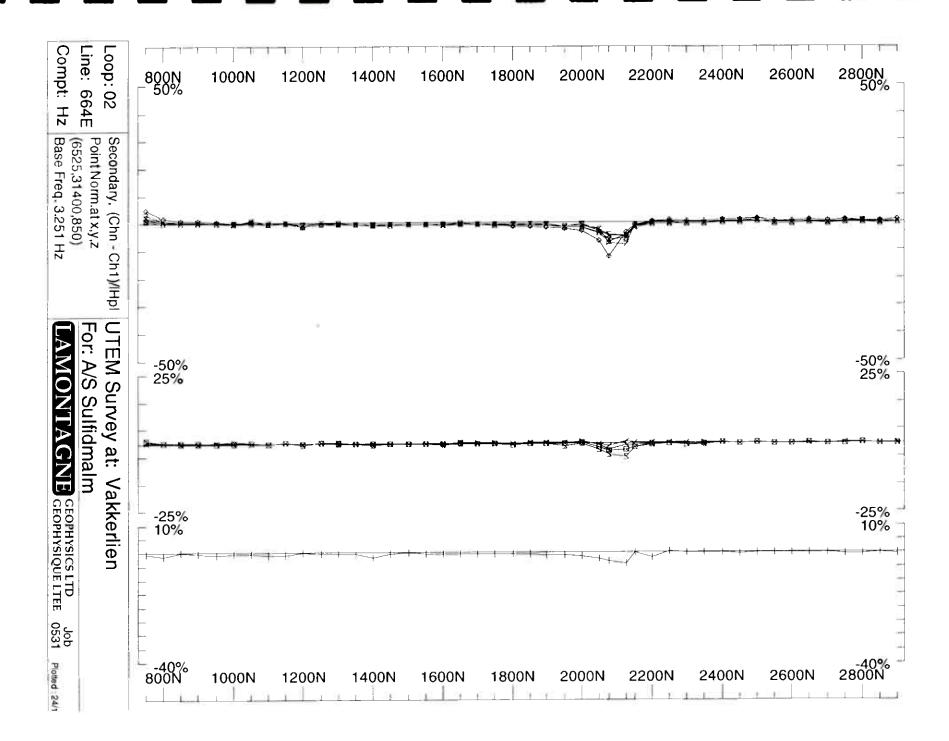


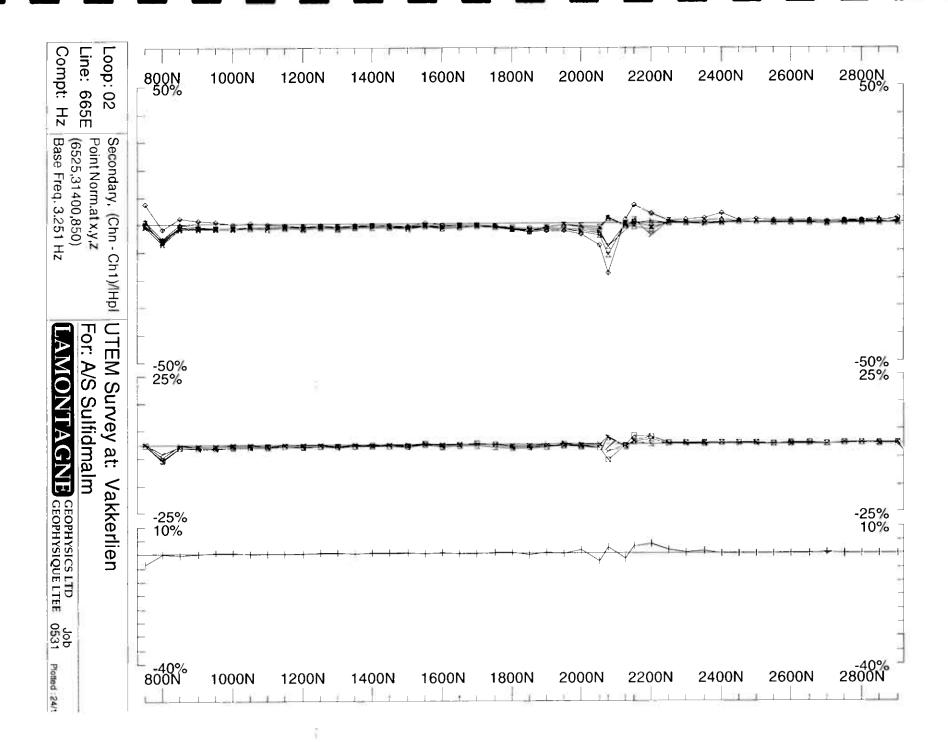


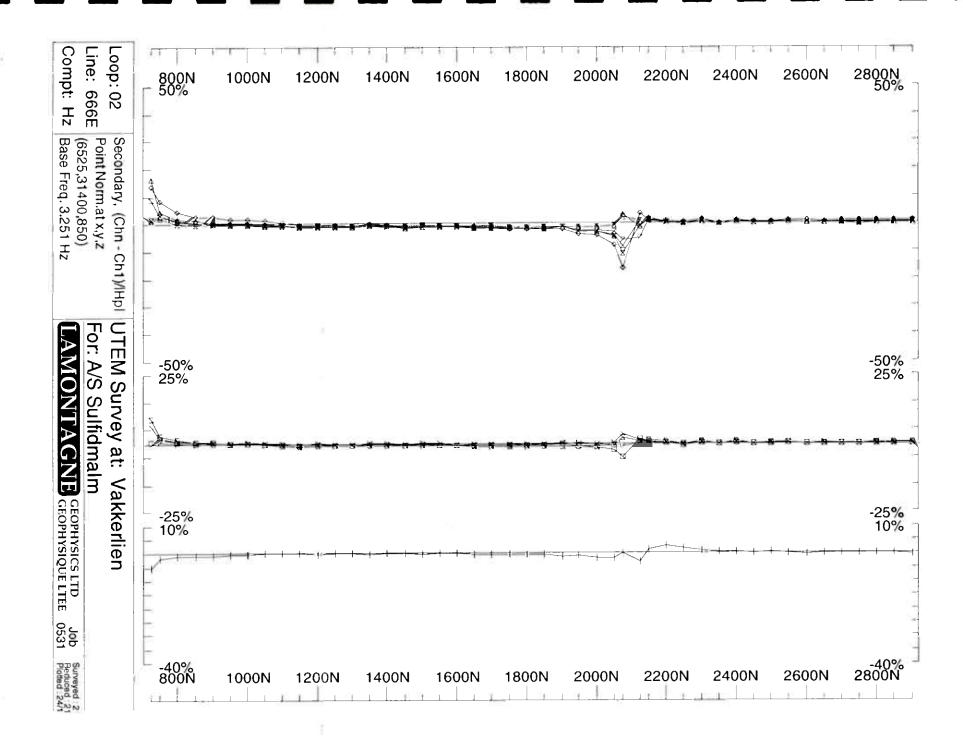


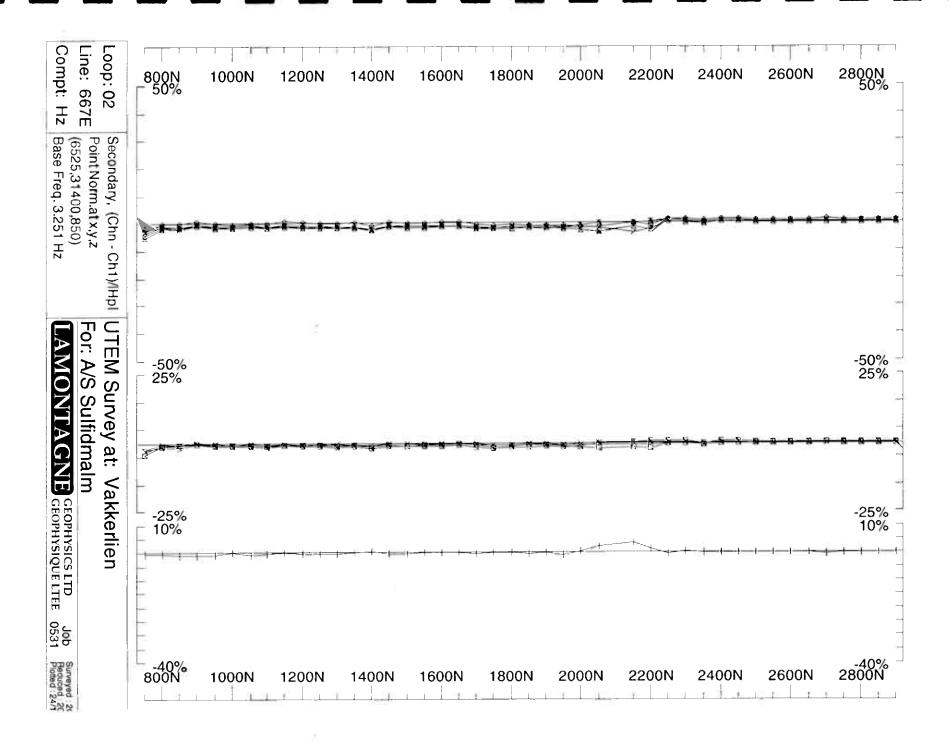


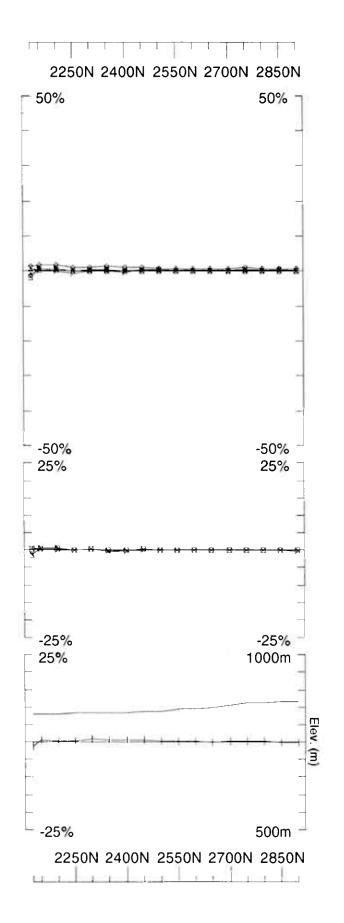




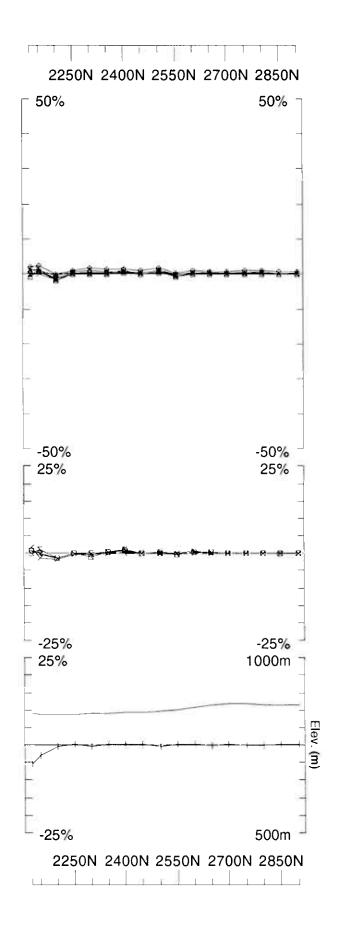






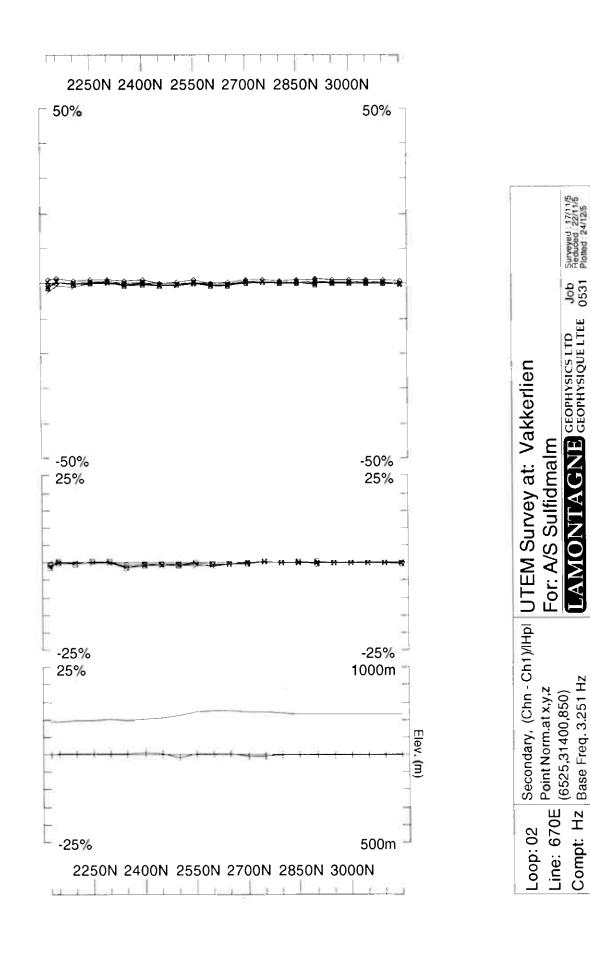


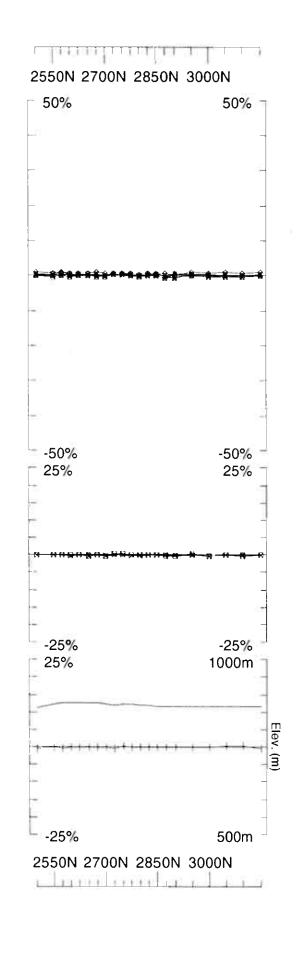
GEOPHYSICS LTD Job Reduced 24/12/5 GEOPHYSIQUE LTEE 0531 Plotted 24/12/5 **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl | Point Norm.at x,y,z | (6525,31400,850) | Base Freq. 3.251 Hz Compt: Hz Line: 668E Loop: 02



Job Surveyed 17/11/5 Reduced 24/12/5 0531 Plotted 24/12/5 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm

Loop: 02 Secondary, (Chn - Ch1)/IHpl L Point Norm.at x,y,z F (6525,31400,850) Compt: Hz Base Freq. 3.251 Hz





Job 0531 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl

(6525,31400,850) Base Freq. 3.251 Hz Point Norm.at x,y,z

Compt: Hz Line: 671E Loop: 02

Loop 2a

Hz @3.251 Hz frequency

continuous norm

Ch1 reduced

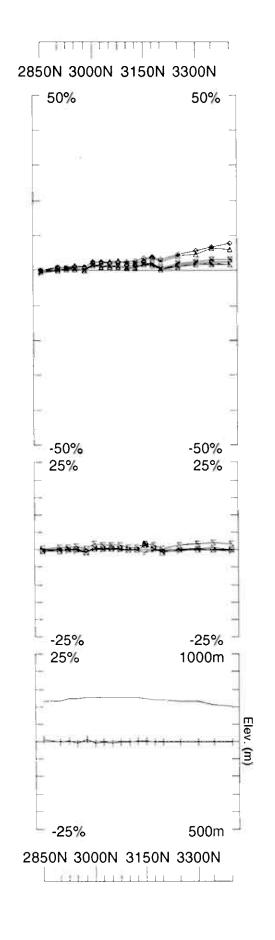
Loop 02a

Line 670E Line 671E 2800N - 3400N 2800N - 3400N 600m 600m

Vakkerlien Loop 02a Total

1200m

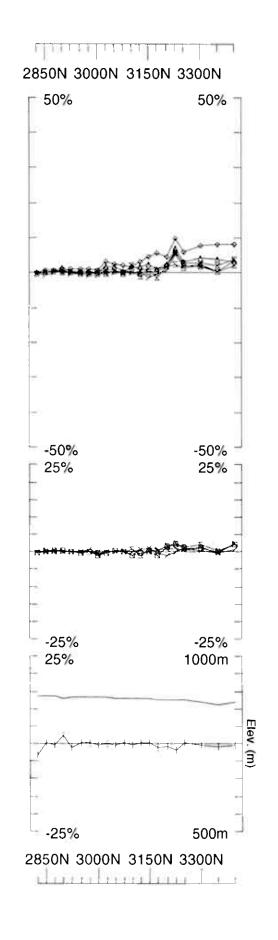
Loop 2a - continuous norm



Job Surveyed 24/11/5 0531 Plotted 24/12/5 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/lHpl Line: 670E Contin. Norm at depth of 0 m Base Freq. 3.251 Hz

Compt: Hz

Loop: 02a



Job 0531 NE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Line: 671E Contin. Norm at depth of 0 m Base Freq. 3.251 Hz Compt: Hz Loop: 02a

## Loop 2a

Hz @3.251 Hz frequency

point norm

@

(x,y,z) = (6600E,31650N,850 m.a.s.l.)

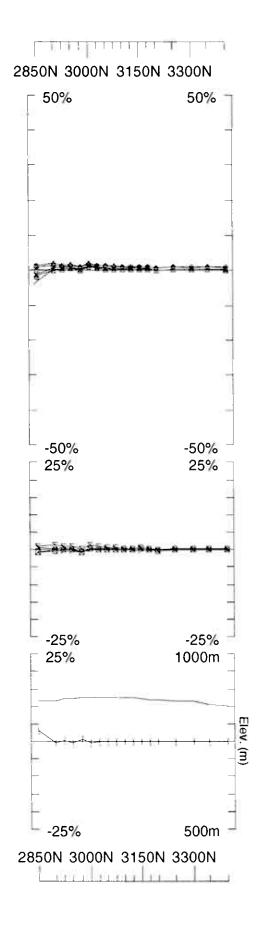
#### Ch1 reduced

Loop 02a

Line 670E Line 671E 2800N - 3400N 2800N - 3400N 600m

Vakkerlien Loop 02a Total

1200m

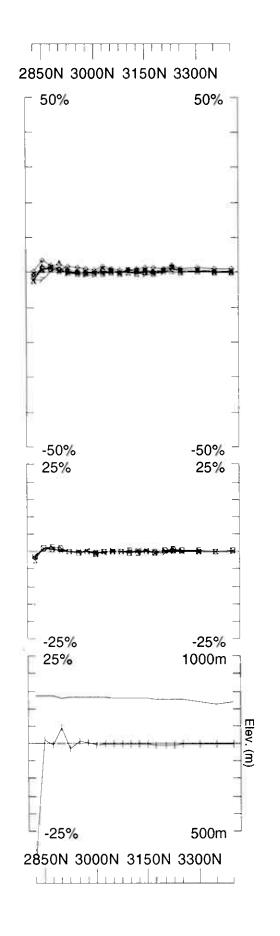


GNE GEOPHYSICS LTD JOB Surveyed 24/11/5 GEOPHYSIQUE LTEE 0531 Ploned 24/125 **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm

Secondary, (Chn - Ch1)/IHpl Line: 670E Loop: 02a

(6600,31650,850) Base Freq. 3.251 Hz Point Normat x,y,z

Compt: Hz



Job 0531 GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl (6600,31650,850) Base Freq. 3.251 Hz Point Norm.at x,y,z Line: 671E Compt: Hz

-oop: 02a

# Loop 3

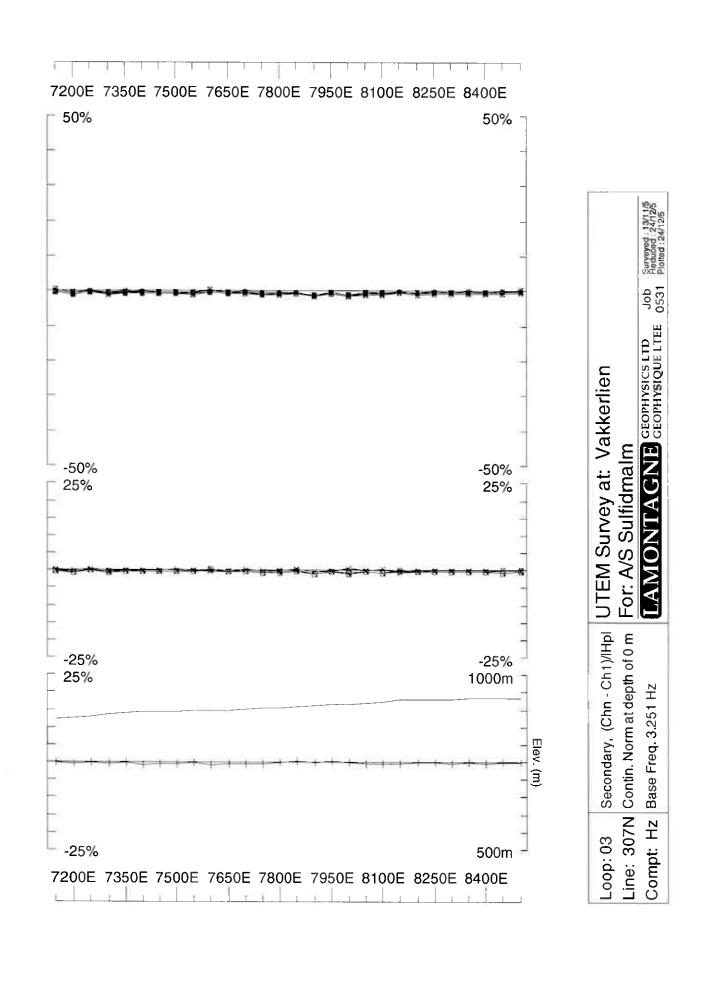
Hz @3.251 Hz frequency

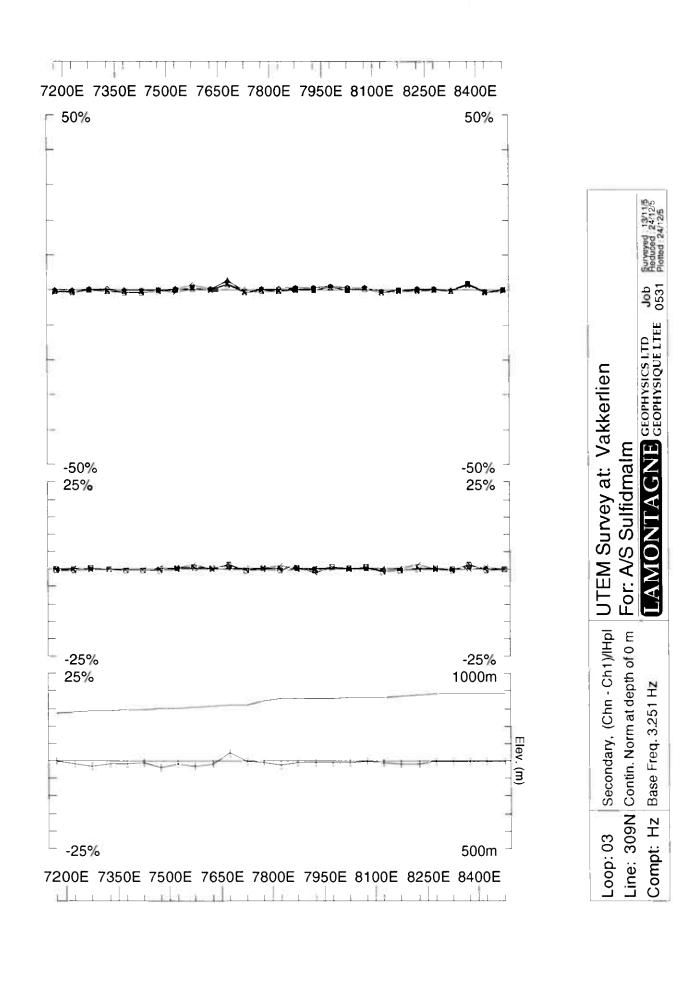
continuous norm

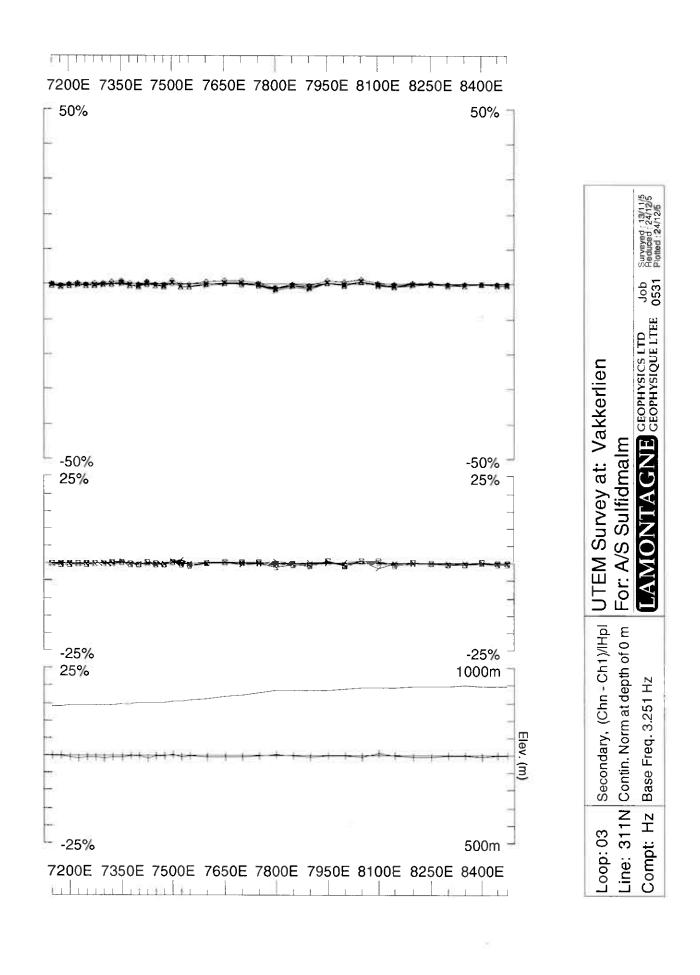
Ch1 reduced

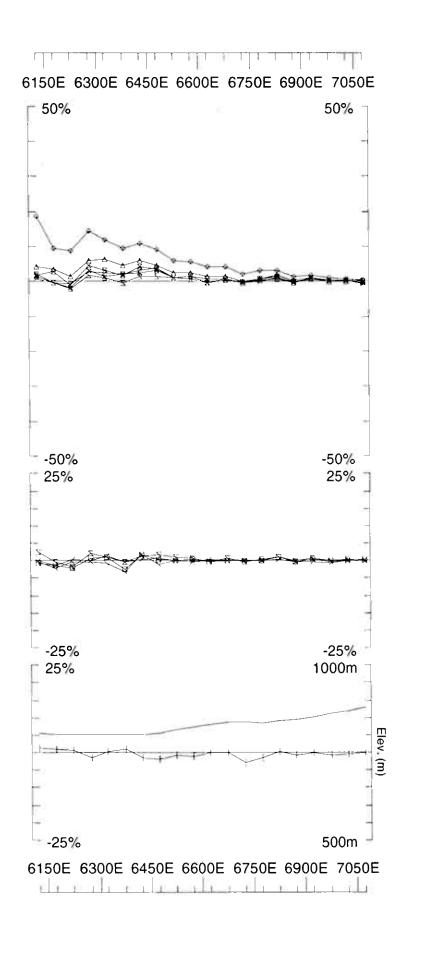
Loop 03	Line 307N	7125N - 8525N	1400m
	Line 309N	7125N - 8525N	1400m
	Line 311N	7125N - 8525N	
	off-loop	6125N - 7125N	2400m
	Line 313N	7125N - 8525N	1400m
	Line 315N	7125N - 8525N	1400m
	Line 317N	7125N - 8525N	
	off-loop	6100N - 7125N	2425m
	Vakkerlie	en Loop 03 Total	10425m

Loop 03 - continuous norm

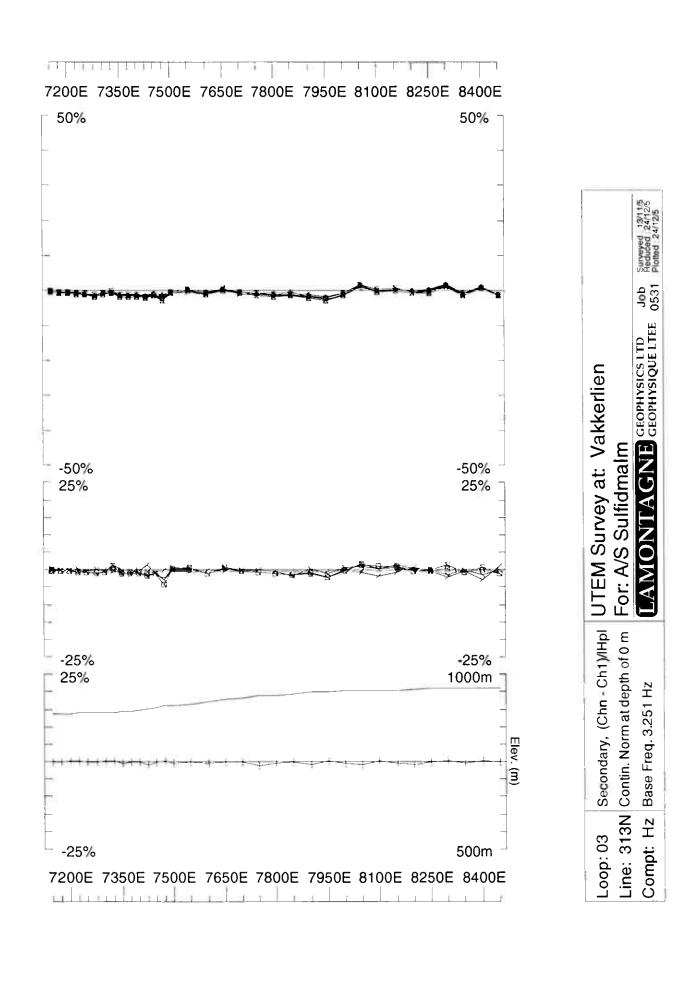


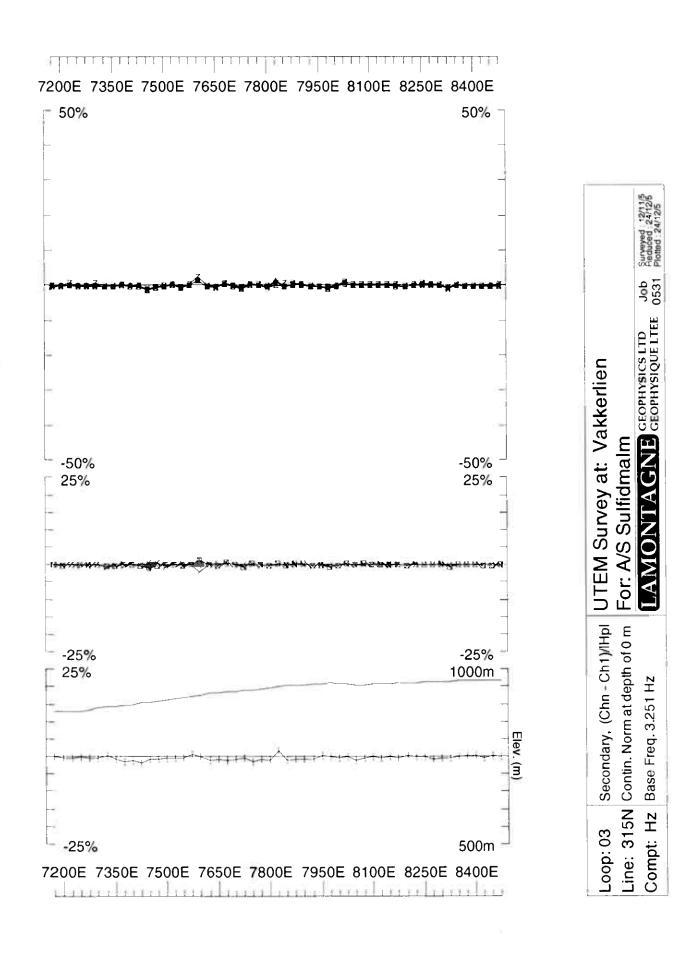


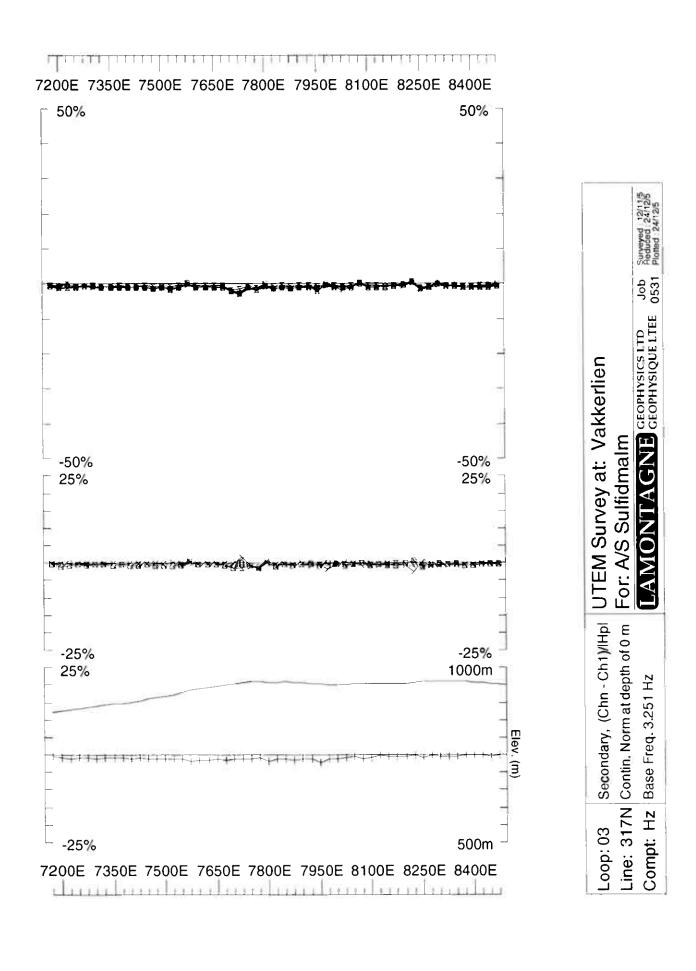


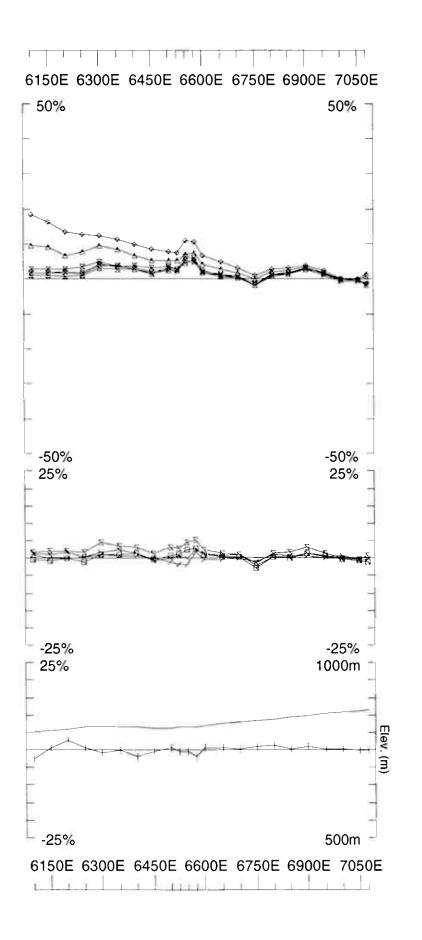


Job Surveyed 14/11/5 0531 Plotted 24/12/5 GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Line: 311N off-loop Contin. Norm at depth of 0 m Base Freq. 3.251 Hz Compt: Hz Loop: 03









GEOPHYSICS LTD GEOPHYSIQUE LTEE For: A/S Sulfidmalm Base Freq. 3.251 Hz

**UTEM Survey at: Vakkerlien** Secondary, (Chn - Ch1)/IHpl Line: 317N off-loop Contin. Norm at depth of 0 m Compt: Hz Loop: 03

## Vakkerlien

# Loop 3

Hz @3.251 Hz frequency

point norm

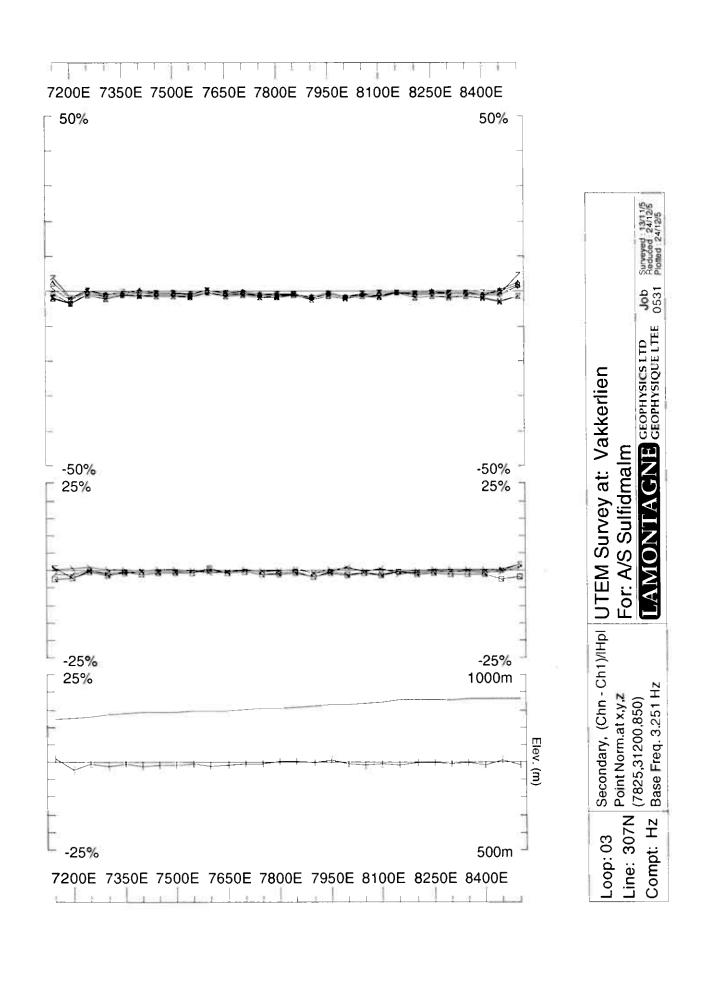
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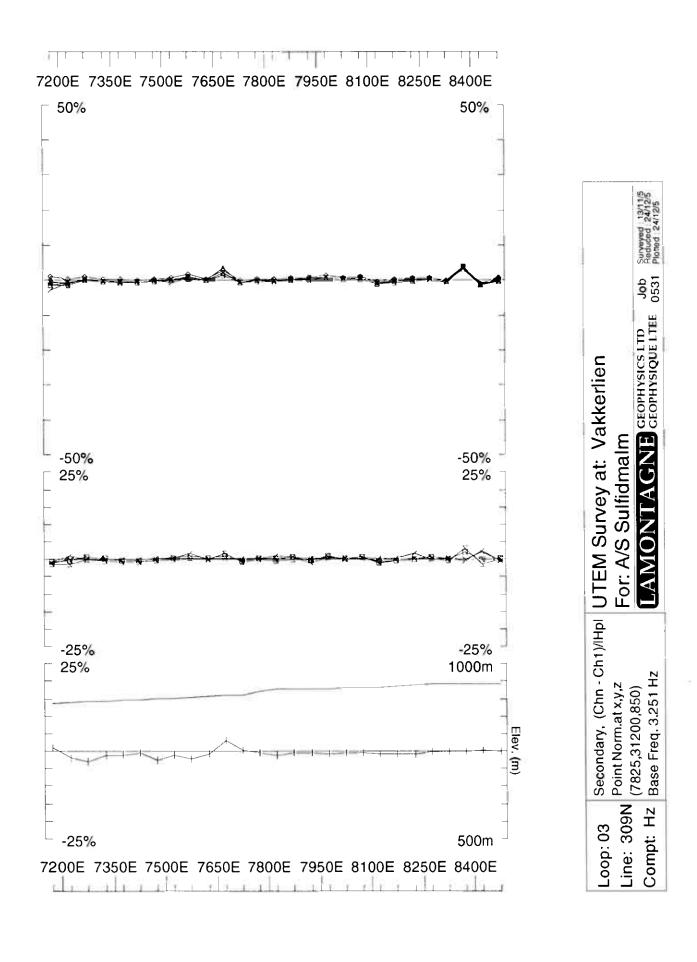
(x,y,z) = (7825E,31200N, 910 m.a.s.l.)

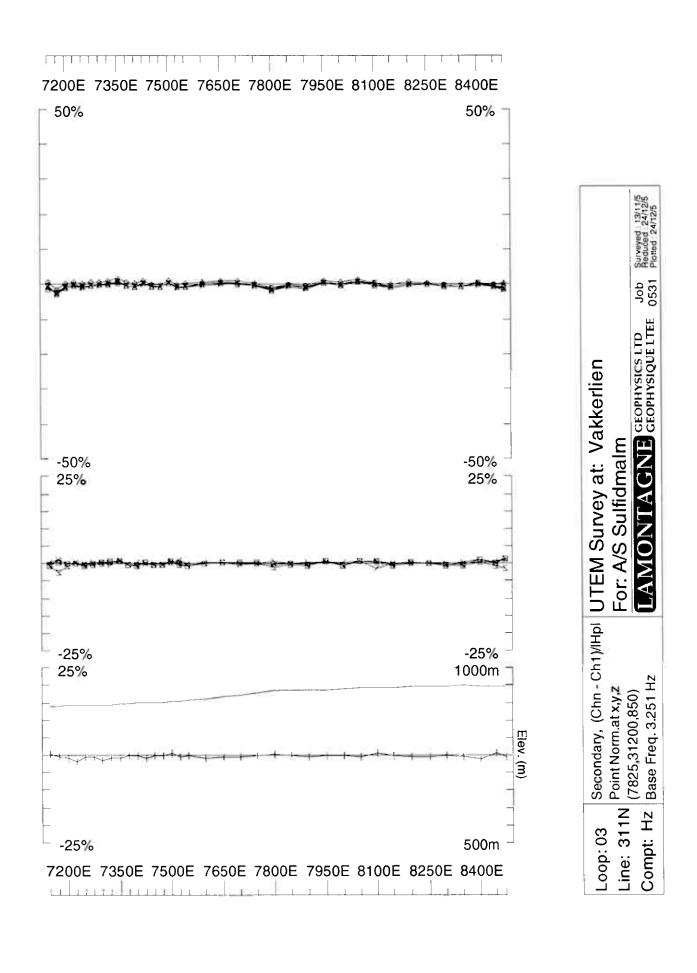
### Ch1 reduced

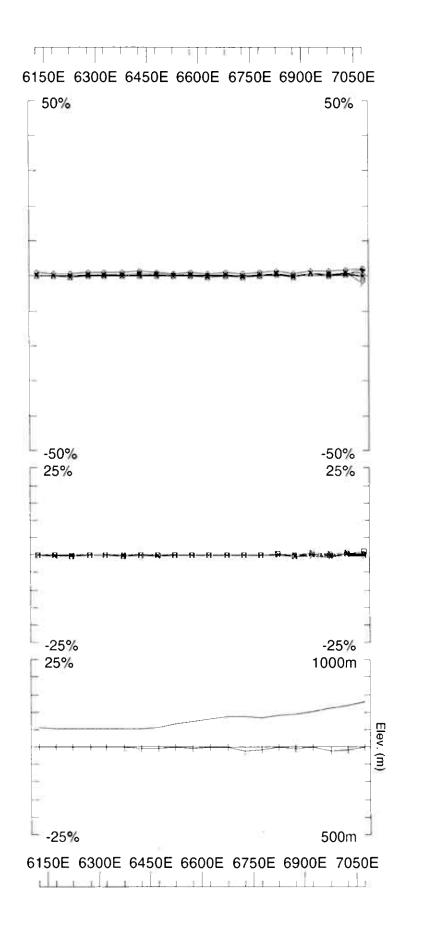
Loop 03	Line 307N	7125N - 8525N	1400m
	Line 309N	7125N - 8525N	1400m
	Line 311N	6125N - 8525N	2400m
	Line 313N	7125N - 8525N	1400m
	Line 315N	7125N - 8525N	1400m
	Line 317N	6100N - 8525N	2425m
	Vakk	erlien Loop 03 Total	10425m

Loop 3 - point norm

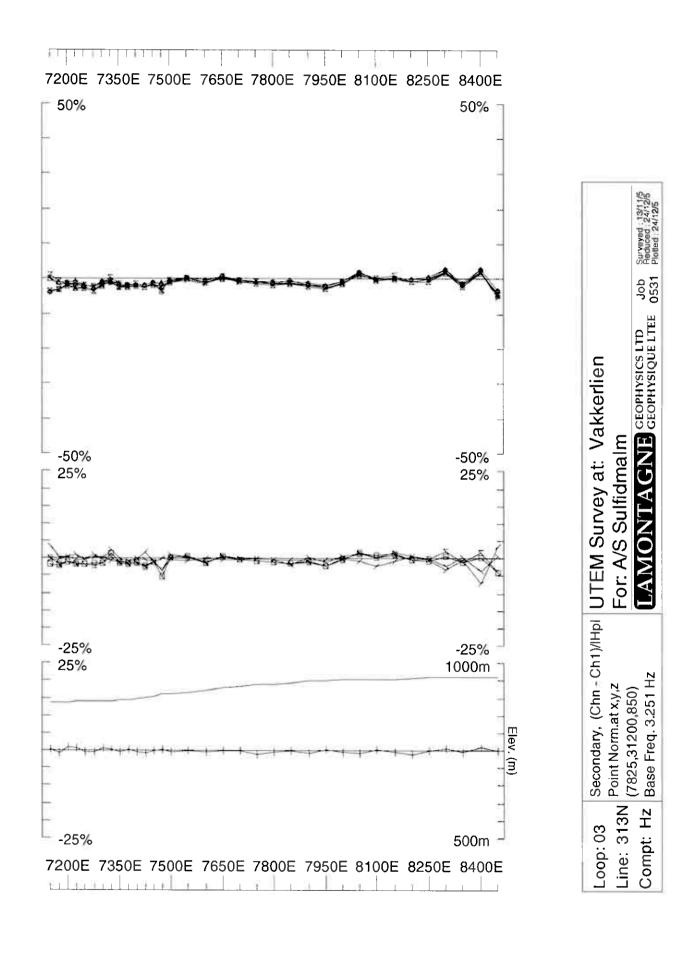


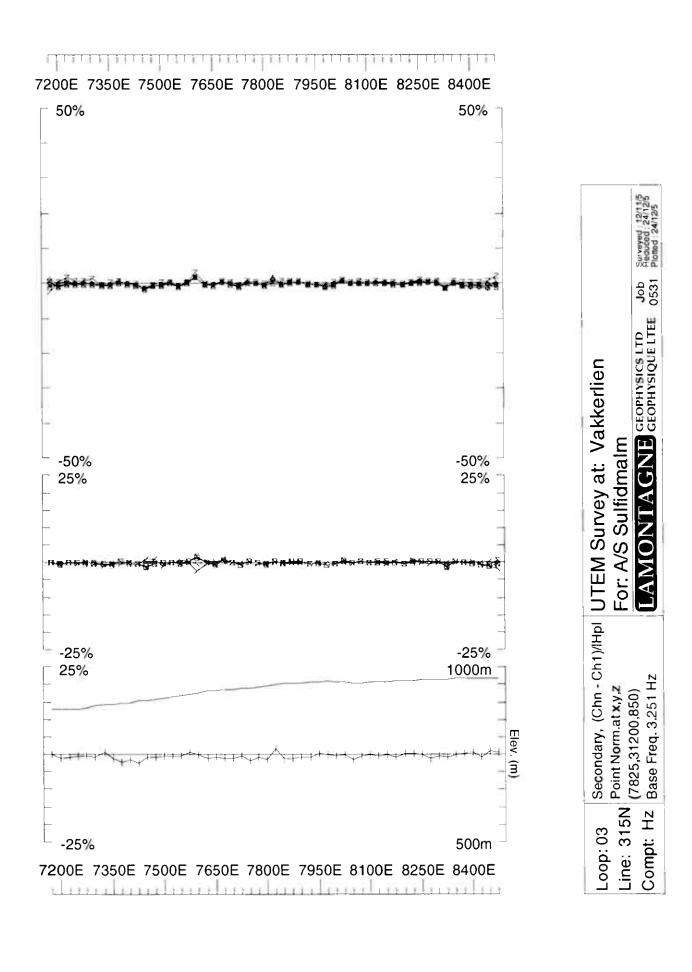


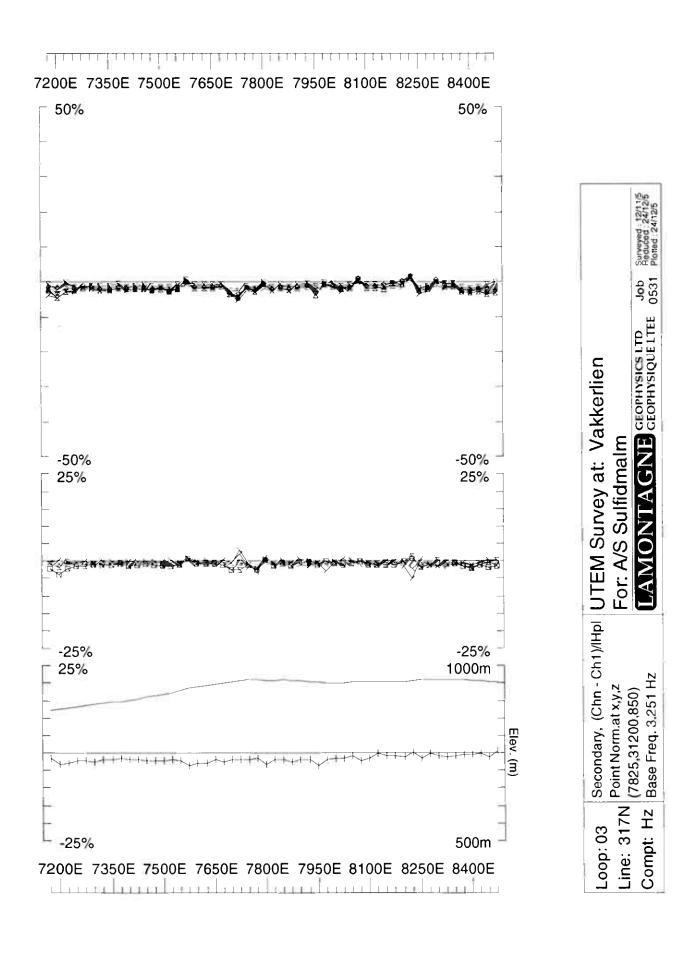


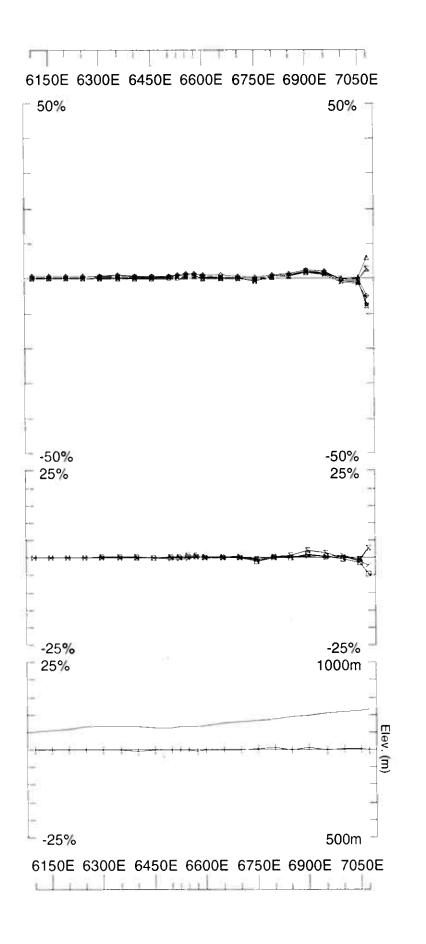


Job Surveyed 14/11/5 Reduced 24/12/5 0531 Plotted 24/12/5 GEOPHYSICS LTD
GEOPHYSIQUE LTEE UTEM Survey at: Vakkerlien For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Point Norm.at x,y,z (7825,31200,850) Base Freq. 3,251 Hz Line: 311N off-loop Compt: Hz Loop: 03









Job Surveyed 14/11/5 Reduced 24/12/5 0531 Proted 24/12/5 GEOPHYSICS LTD GEOPHYSIQUE LTEE **UTEM Survey at: Vakkerlien** For: A/S Sulfidmalm Secondary, (Chn - Ch1)/IHpl Point Norm.at x,y,z (7825,31200,850) Base Freq. 3.251 Hz Line: 317N off-loop

Compt: Hz

Loop: 03

## Vakkerlien

# Loop 4

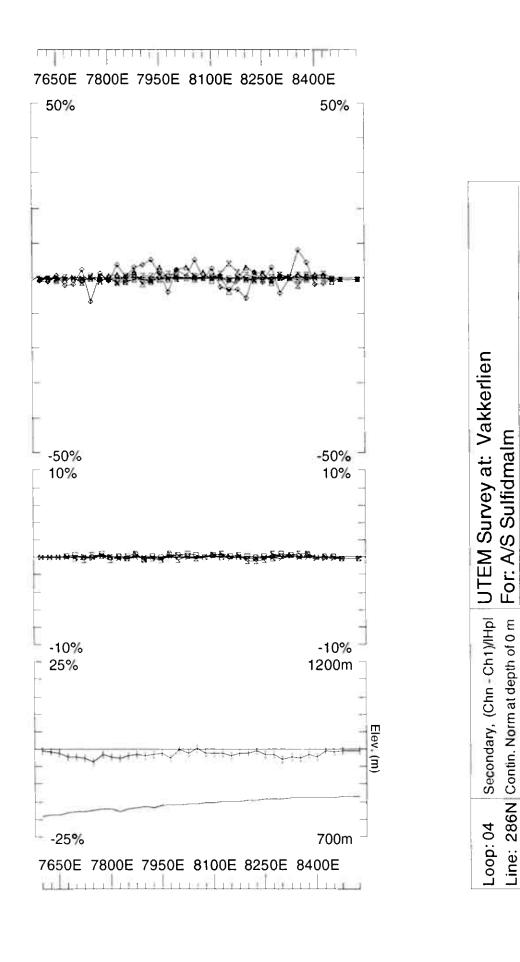
Hz @3.251 Hz frequency

continuous norm

Ch1 reduced

Loop 04	Line 286N	7600N - 8500N	900m
	Line 288N	7400N - 8500N	1100m
	Line 290N	7400N - 8500N	1100m
	Line 292N	7400N - 8500N	1100m
	Line 294N	7400N - 8500N	1100m
	Vakk	terlien Loop 04 Total	5300m

Loop 4 - continuous norm

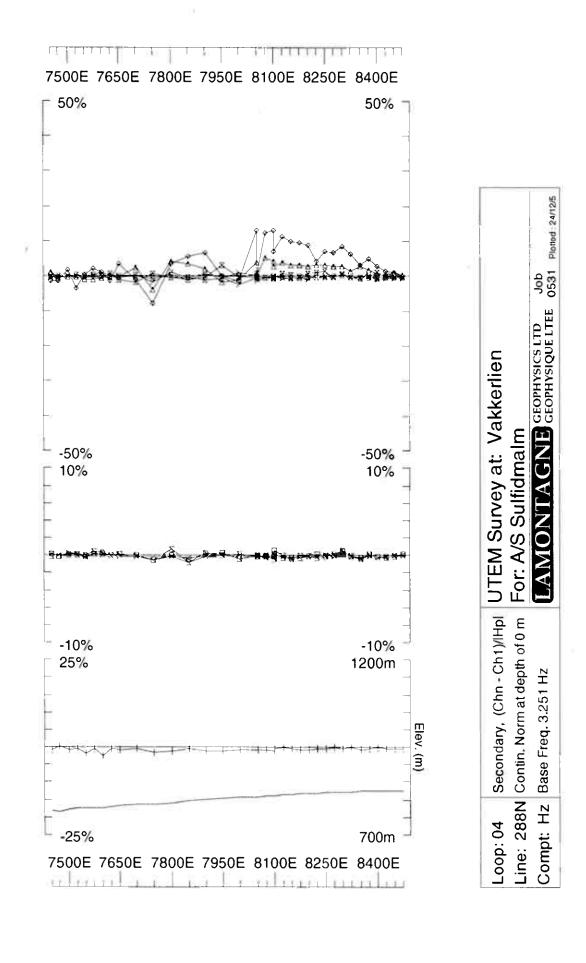


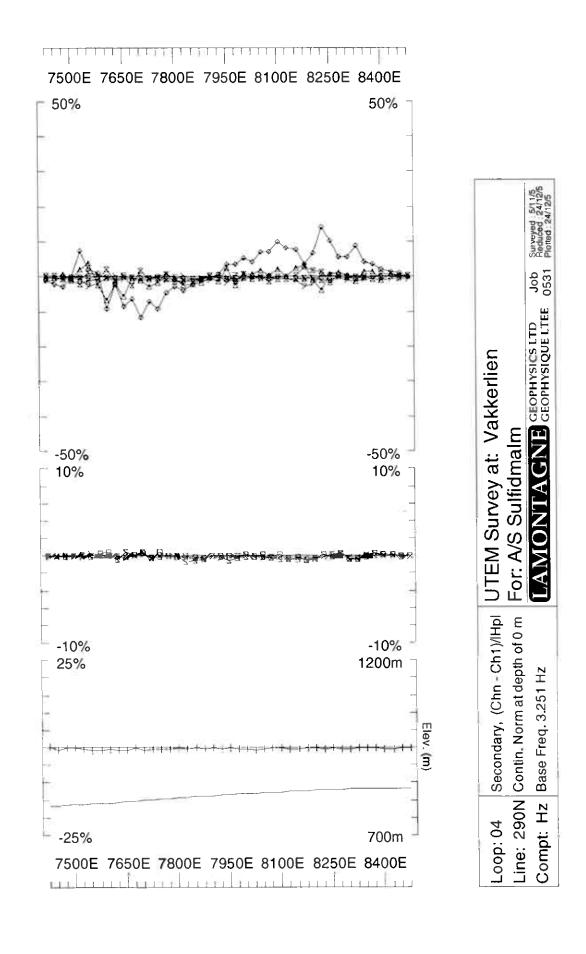
Job Surveyed 4/11/5 Reduced 24/12/5 0531 Plotted 24/12/5

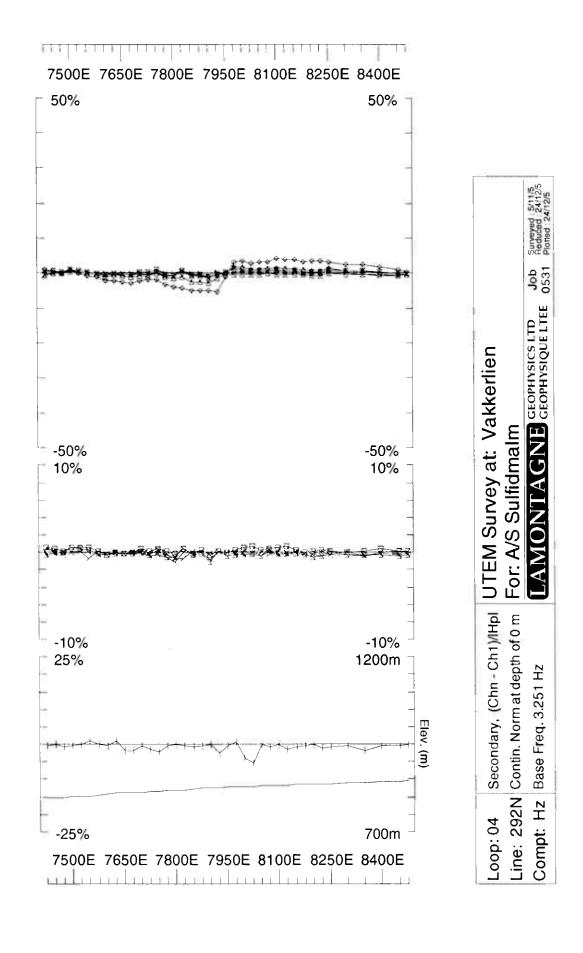
GNE GEOPHYSICS LTD GEOPHYSIQUE LTEE

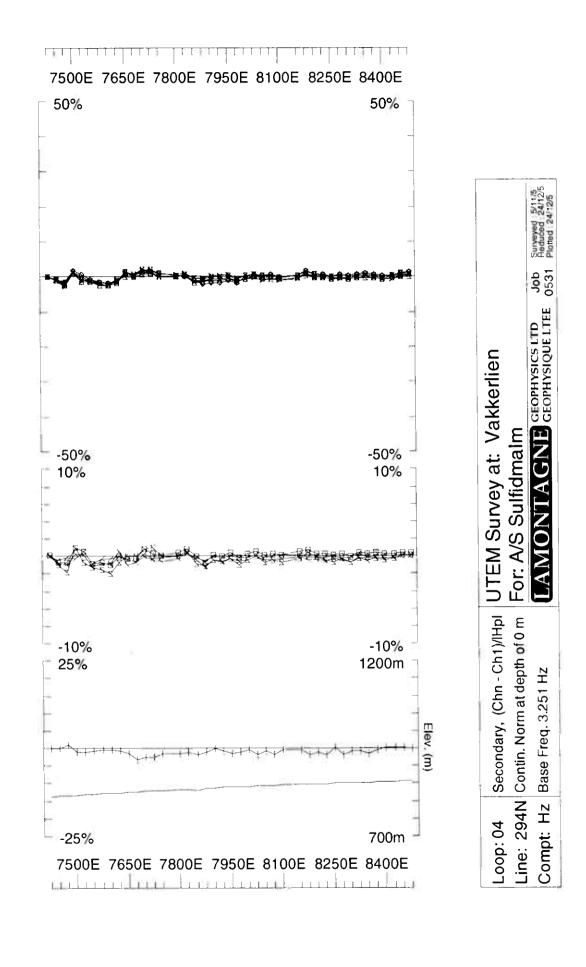
Base Freq. 3.251 Hz

Compt: Hz









## Vakkerlien

# Loop 4

Hz @3.251 Hz frequency

point norm

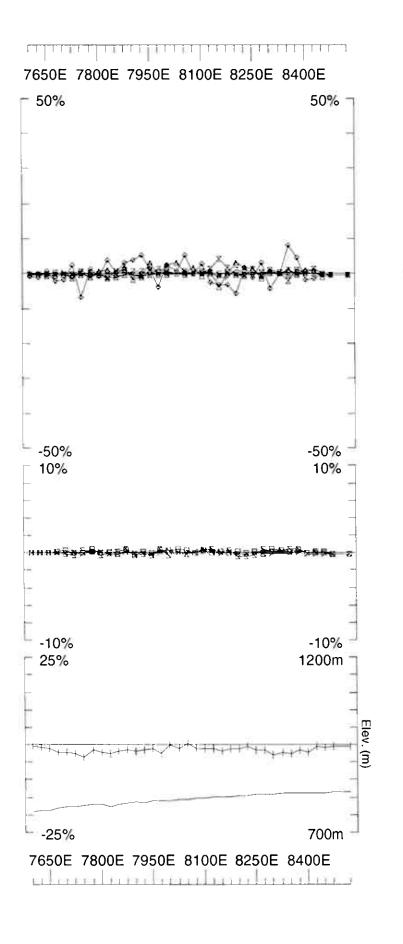
@

(x,y,z) = (8500E,29000N, 800 m.a.s.l.)

### Ch1 reduced

Loop 04	Line 286N	7600N - 8500N	900m
	Line 288N	7400N - 8500N	1100m
	Line 290N	7400N - 8500N	1100m
	Line 292N	7400N - 8500N	1100m
	Line 294N	7400N - 8500N	1100m
	Vakk	erlien Loop 04 Total	5300m

Loop 4 - point norm



Mittpl UTEM Survey at: Vakkerlien

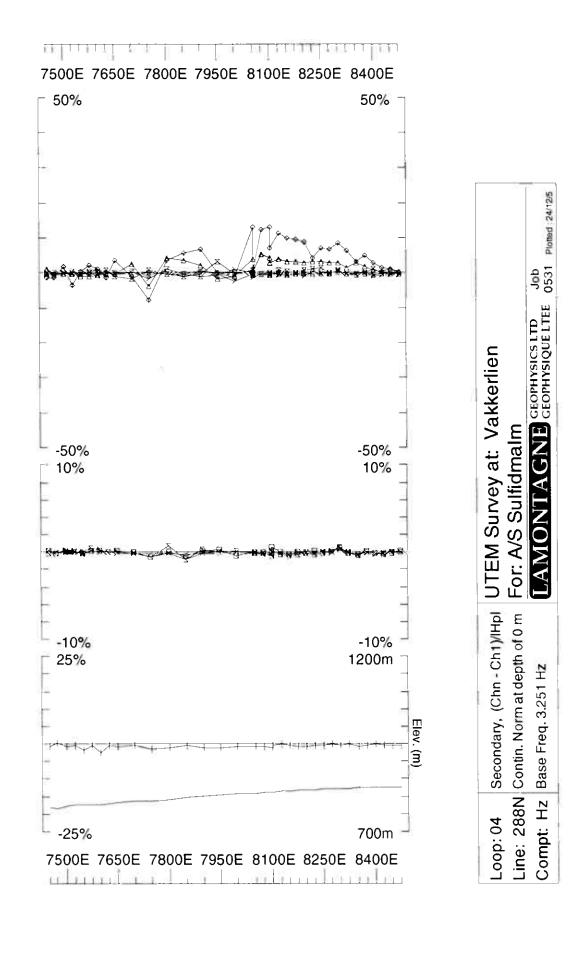
For: A/S Sulfidmalm

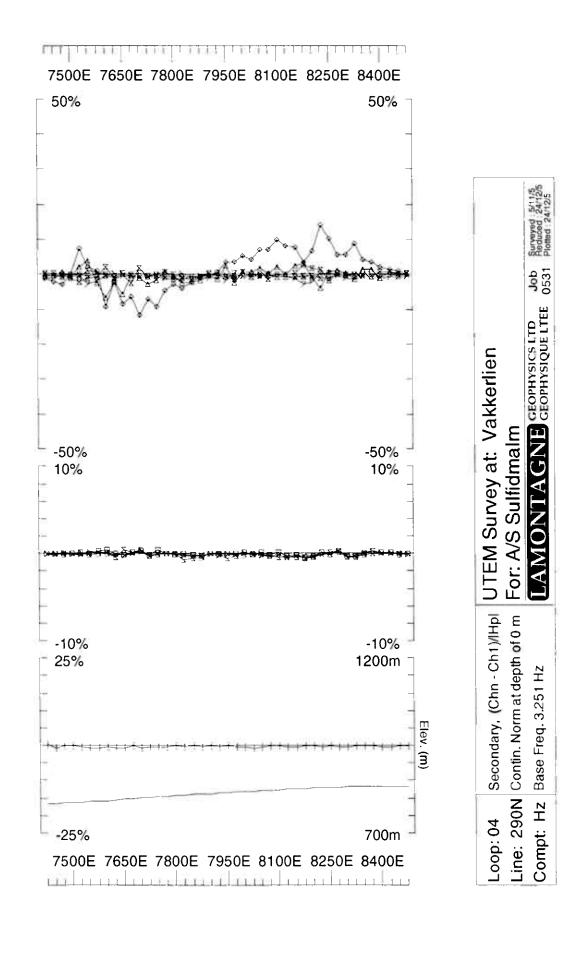
LAMONITAGNE GEOPHYSIQS LTD

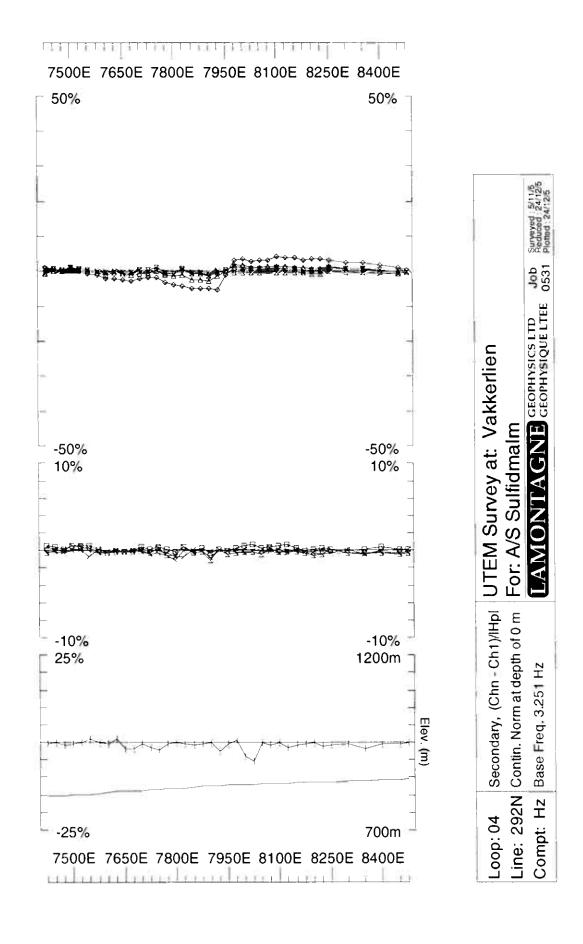
Job Reduced 24/125

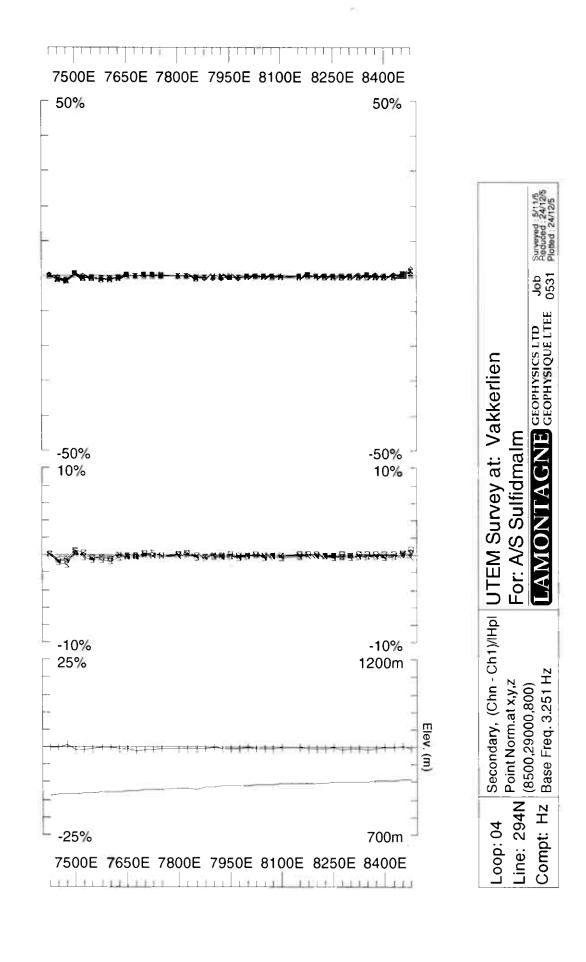
GEOPHYSIQUE LTEE 0531 Plotted 24/125

Loop: 04 Secondary, (Chn - Ch1)/IHpl UTEM Sun Line: 286N Contin. Norm at depth of 0 m Compt: Hz Base Freq. 3.251 Hz









# Appendix B

0531 Production Diary

**UTEM 3 Surface Survey** 

Vakkerlien Grid Norway

for

A/S Sulfidmalm

### Production Log (0531) UTEM Survey - Vakkerlien Norway A/S Sulfidmalm

Data	Pato	Draduation	Comments
<u>Date</u>		Production	
up to October 24		-	Discussions, signing of the contract, assembly of crew and equipment.
October 24	Mob	(equip)	Equipment packed up and labelled. Picked up from Kingston.
October 30	Mob	-	John Frost of the LGL crew travels from Kingston (YGK)- >Toronto (YYZ)->Frankfurt(FRA)->Oslo (OSL). Crew: J.Frost
October 31	Mob	-	John Frost completes journey ->Oslo (OSL). Meets up with Falconbridge personnel and travels with equipment to Espedalen. Crew: J.Frost
November 01	Mob		John Frost and Falconbridge personnel complete journey to Vakkerlien and unpack. Crew: J.Frost
November 02	Mob+?	-20	The LGL crew -Rob Langridge and Tim Pinkerton start travel from Canada->Frankfurt(FRA)->Oslo (OSL)->Trondheim (TRD).  John unpacks gear while the Falconbridge personnel lay out wire.  Crew: R.Langridge, T.Pinkerton, J.Frost
November 03	Mob+?	-	Rob Langridge and Tim Pinkerton continue traveling and arrive ->Trondheim (TRD). They are met by Lars Weiershaeuser of Falconbridge and drive out to the jobsite arriving ~22:00. Set up for the morning. John Frost and Falconbridge personnel (Doris Fox) lay out wire.  Crew: R.Langridge, T.Pinkerton, J.Frost

Date Rate Production Comments November 04 1/2**L(2)-3** 1600m Get equipment ready. Drive out to site picking up fuel 1/2P(1)-2for the generator enroute. Complete loop, setup and start surveying ~12:00. Survey till dark - just past 16:00. Pack up, dinner in town and then head home. Data from Rx06 will be repeated. Loop 04 Line 286N 7600E - 8500E Ηz Rx05 Line 288N 7400E - 8100E Hz Rx05 Line 288N 7400E - 8500E Hz Rx06 Hz Line 290N 7400E - 8500E Rx06 Total to date: 1.600k Crew: R.Langridge, T.Pinkerton, J.Frost November 05 **P(2)-3** 3700m Get equipment ready. Setup, connect loop and start surveying. Survey till 16:00. Pack up and head home. Loop 04 Line 288N 8100E - 8500E Hz Rx06 Line 290N 7400E - 8500E Hz Rx06 7400E - 8500E Line 292N Hz Rx04 Line 294N 7400E - 8500E Hz Rx04 Total to date: 5.300k Crew: R.Langridge, T.Pinkerton, J.Frost November 06 1/2L(2)-3Get equipment ready. Drive out to Loop 01 site via the 1/2**P(2)-3** 1825m back route. Wheelbarrow in the generator and some gear, carry in some gear and setup while the loop is completed. Some of the pickets near the access path have been moved or removed. Loop is completed ~11:00 and surveying starts ~12:00. Missing pickets slow surveying and the area seems quite noisy - production will go slowly. Late in the afternoon (15:00) Rx05 develops a problem. Survey with one Rx till 16:00 - pack up and head home. Overhaul Rx05 and 06 in the evening. Loop 01 Line 329N 5500E - 6550E Rx06 Hг Line 330N 5775E - 6550E Hz Rx05 Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 7.125k November 07 **P(2)-3** Out to Loop 01 - use Tx06 to test if the Tx is related to the 2200m noisy data. Survey till 16:15 and head home. Loop 01 Line 332N 5450E - 6550E Hz Rx05 Line 333N 5450E - 6550E Hz Rx04

Crew: R.Langridge, T.Pinkerton, J.Frost

Total to date: 9.325k

Date Rate Production Comments November 08 **P(2)-3** 2200m Out to Loop 01. Survey till 16:15. Pack up/head home. Sunrise/sunset: 08:12-15:52 Loop 01 Line 334N 5450E - 6550E Hz Rx05 Line 335N 5450E - 6550E Hz Rx04 Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 11.525k November 09 **P(2)-3** 2200m Out to Loop 01. Survey till 16:10. Pack/head home. Sunrise/sunset: 08:15-15:49 Loop 01 Line 336N 5450E - 6550E Hz Rx05 Line 337N 5450E - 6550E Hz Rx06 Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 13.725k November 10 **P(2)-3** 1775m Out to Loop 01. Survey till 15:50. Pack/head home. Sunrise / sunset: 08:18-15:47 Loop 01 Line 329N 5700E - 5975E Hz Rx06 Line 330N Hz 5450E - 5900E Rx06 Line 331N 5450E - 6550E Hz Rx05 Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 15.500k November 11 **P(2)-3** 950m Out to Loop 01 to re-read in detail a section of Line 331N. Survey till 13:15. Pack and shift the generator by wheelbarrow across the swamp. - this takes ~90 minutes. Move the tx, transformer and battery as far as we can before dark. Walk out and head home very tired. Sunrise/sunset: 08:21-15:44 Loop 01 Line 331N 5450E - 6300E Hz Rx5/6Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 16.450k November 12 **P(2)-3** 2800m Out to Loop 03. Finish moving the Tx in the last few hundred metres and set up. Read till ~13:45 when a moose is spotted. Loop is broken soon after and the search for the break completes the day. Walk out - back at the truck @15:40. Sunrise/sunset: 08:24-15:41 Loop 03 Line 317N 7125E - 8525E Hz Rx06 Line 315N 7125E - 8525E Hz Rx05 Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 19.250k

<u>Date</u>	<u>Rate</u>	<b>Production</b>	<u>Comments</u>		
November 13		5600m v: R.Langridg	Out to Loop 03. Set up Evidence of the moos turned out to be an o down as it has occasi Turned It back on an Sunrise/sunset: 08:27 Loop 03 Line 307N Line 309N Line 311N Line 313N ge,T.Pinkerton,J.Frost	se and the Tx shut old friend - the Tx ha onally on all the job d surveyed all day. 7-15:39 7125E - 8525E 7125E - 8525E 7125E - 8525E 7125E - 8525E	down. It d simply shut
November 14		2025m	Out to Loop 03. Set u Stationed Tim at the number of times dur ~14:30 and picked up sides. Out to the true Sunrise/sunset: 08:29 Loop 03 Line 311N Line 317N	transmitter and it sling the day. Finished for pulled wire on the cks by 16:20. 9-15:36 6125E - 7125E 6100E - 7125E	nut down a d reading e north and west  Hz Rx05 Hz Rx06
	Crev	v: R.Langrid	ge,T.Pinkerton,J.Frost	Tota	al to date: 26.875k
November 15	L(2)-3		Up to a world covered road but it appeared at the road we have I for a few hours to che the snow-scooter per hardware to modify there was none local and laid out wire in	to be stengt - closed been using and decide eck on the lower roatmit. Shopped - look the snow shoes for r ly. Headed out ~11: windy, snowy condi	. Took a look ded to back off d status and ted for some nuskeg but 00. Walked out tions - snowier
	ñg	a Palant	than expected. Mana (double wire) in poo extended into the ear the trucks by 16:45.	r conditions. The w rly evening but we v	alk out vere all back at
	Cre	y: R.Langrid	ge,T.Pinkerton,J.Frost		al to date: 26.8 <b>7</b> 5k
November 16	P(2)-3	2200m	Out to Loop 02. Com generator. Set up an the trucks by 16:30. arrived - Finn to the	id go to work in ligh The gate was locked	t snow. Out to

Crew: R.Langridge, T.Pinkerton, J.Frost Total to date: 29.075k UTEM Survey 0531 - A/S Sulfidmalm Vakkerlien, Norway Appendix B pg B4

5825E - 7225E

2100N - 2900N

Hz

Hz

Rx06

Rx05

Sunrise/sunset: 08:35-15:31

Loop 02

Line 319N

Line 663E

<u>Date</u>	Rate	Production	<u>Comments</u>				
November 17	P(2)-3	4400m	Out to Loop 02. Set up Out to the trucks by 1 we can use the snosco protected area. Sunrise/sunset: 08:38 Loop 02 Line 315N Line 317N Line 669E Line 670E	16:40. Fi poters of 3-15:28 5825E 5825E 2100N	nd out in the	evenir	ig that
	Crev	v: R.Langridg	ge,T.Pinkerton,J.Frost		Total	to date	e: 33.475k
November 18	P(2)-3	2200m	Out to Loop 02. Trailed Loop was broken - in where it crosses a rive few days (a metre or out a section - rough! With the double loop patched. started read Getting the snoscooted Sunrise/sunset: 08:47 Loop 02  Line 667E  Line 668E	a a numb er - the s so) back ly as far there is ding ~12 er trailer I-15:25	er of places beteady snowford up the rive from the Tx at wire availabetes and read out proved at 2100N	out mai all of the er and is possi le so it one lin	nly ne past took ble. was e each. difficult.
	Crev	v: R.Langrid	<b>Line 668</b> E ge,T.Pinkerton,J.Frost	2100IN			<b>Rx05</b> e: 35.675k
November 19	n/c		Day off. Picked up to Sunrise/sunset: 08:44		and supplies	in Tyns	set.
November 20		Out to Loop 02. The loop was good but the negative lead had broken off the back up battery and the Tx was off. Decided to get the other Tx. Back to Hogstad to pick-up the Tx and gas etc. On the way back the truck went into the ditch. Pulled it out with the tow rope. Out to the transmitter site again. The backup Tx would not put out as much current @ pre-whitening level 4 - and blew a fuse. Used the same Tx again. Read one line each. Sunrise/sunset: 08:47-15:21					
		D.I	Loop 02 Line 666E Line 667E	2100N 2100N		Hz Hz	Rx05 Rx06

Crew: R.Langridge, T.Pinkerton, J.Frost

Total to date: 37.275k

<u>Date</u>	Rate	Production	Comments				
November 21	P(2)-3	4400m	Out to Loop 02. The leach. Sunrise/sunset: 08:49 Loop 02 Line 664E Line 665E Line 666E	9-15:19 2100N 2100N 700N	- 2900N - 2900N - 2100N - 2100N	Hz Hz Hz Hz	Rx05 Rx05 Rx06 Rx06
	Crev	v: R.Langridg	ge,T.Pinkerton,J.Frost		Total	to date	2: 41.675k
November 22	P(2)-3	5600m	Out to Loop 02. The lines each. Everybook creek crossings. Sunrise/sunset: 08:5 Loop 02 Line 311N Line 313N Line 663E	dy was a 2-15:16 5825E 5825E			
	Cros	w R Langride	Line 664E ge,T.Pinkerton,J.Frost	700N	- 2100N	Hz to date	<b>Rx05</b> e: 47.275k
November 23		3275m	Out to Loop 02. The lines including exter Tim Pinkerton to Tro Sunrise/sunset: 08:5 Loop 02 Line 309N Line 313N Line 670E Line 671E	nded sectiondheim 2-15:16 5825E 7225E 2900N	ions of Lines in the evenin - 7225E - 8200E - 3150N - 3150N	670E a g. Hz Hz Hz Hz Hz	Rx06 Rx06 Rx05 Rx05
	Cre	w: R.Langrid	ge,T.Pinkerton,J.Frost		Total	to date	e: 50.550k
November 24 <b>P(2)-2</b> 1200m demob (Tim)  Out to Loop 02. The loop was good. Modified the loop to read sections of Lines 670 and 671E. Finished @ dark. Back to the trucks @ 16:50. Tim Pinkerton flies home. Sunrise/sunset: 08:55-15:14 <b>Loop 02a</b>							
			Line 670E Line 671E	2800N 2800N	- 3400N - 3400N	Hz Hz	Rx05 Rx06
	Cre	w: <b>R.Langrid</b>	ge, J.Frost, T.Pinkerton				e: 51.750k
November 25		w: R.Langrid	Out to pick up Loop dark. Back to the tr Sunrise/sunset: 09:0 ge, J.Frost	ucks @ 16		ed till a	ıfter

Date Rate Production Comments

November 26 L(2)-2 Out to pick up the remainder of Loop 02. and pickets

Worked till ~noon. Drove snoscooters down to the road. One truck went in the ditch on the way down. Pulled it out with the snoscooter. Brought trailers back and loaded the snoscooters. Packed gear for transport

to Espedalen/Gardemoen. Sunrise/sunset: 09:02-15:08

Crew: R.Langridge, J.Frost

November 27 **demob** Loaded gear for transport to Gardemoen in the morning.

Drove south to Vinstra. Left the gear with Falconbridge personnel and continued on to Gardemoen. Arrived ~18:30. Went to sort out our tickets and had some trouble with John Frost's ticket. This was finally

resolved to some satisfaction at 23:00.

Crew: R.Langridge, J.Frost

November 28 **demob** Gear and crew to Gardemoen. Gear taken to shipper by

Falconbridge personnel.

Crew to Canada.

November 29 equipment - Equipment in transit.

->December 10

December 11 Equipment arrives in Kingston.

**LEGEND** 

P(n)-x Surface Production (# of receivers) - # of personnel

L(n)-x Looping (# of receivers) - # of personnel S(n)-x Standby (# of receivers) - # of personnel Down (# of receivers) - # of personnel

# Appendix C

## The UTEM SYSTEM

The UTEM System

UTEM Data Reduction and Plotting Conventions

Data Presentation

#### The UTEM SYSTEM

UTEM uses a large, fixed, horizontal transmitter loop as its source. Loops range in size from 300m x 300m up to as large as 4km x 4km. Smaller loops are generally used over conductive terrain or for shallow sounding work. The larger loops are only used over resistive terrain. The UTEM receiver is typically syncronized with the transmitter at the beginning of a survey day and operates remotely after that point. The clocks employed - one in each of the receiver and transmitter - are sufficiently accurate to maintain synchronisation.

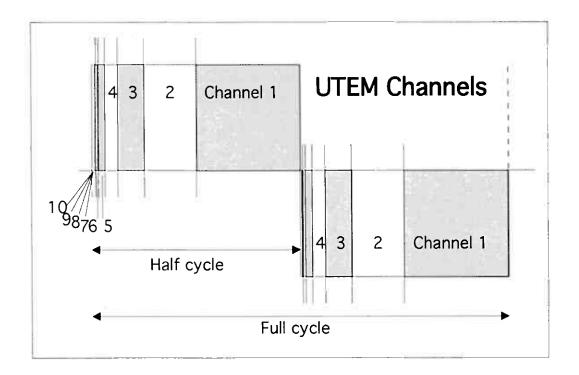
Measurements are routinely taken to a distance of 1.5 to twice the loop dimensions, depending on the local noise levels, and can be continued further. Lines are typically surveyed out from the edge of the loop but may also be read across the loop wire and through the centre of the loop, a configuration used mainly to detect horizontal conductors. BHUTEM - the borehole version of UTEM -surveys have been carried out to depths up to 3000+ metres.

#### System Waveform

The UTEM transmitter passes a low-frequency (4 Hz to 90 Hz) current of a precisely regulated triangular waveform through the transmitter loop. The frequency can be set to any value within the operating range of the transmitter, however, it is usually set at 31 Hz to minimise power line (60 Hz in North America) effects. Since a receiver coil responds to the time derivative of the magnetic field, the UTEM system really "sees" the step response of the ground. UTEM is the only time domain system which measures the step response of the ground. All other T.D.E.M. systems to date transmit a modified step current and "see" the (im)pulse response of the ground at the receiver. In practice, the transmitted UTEM waveform is tailored to optimize signal-to-noise. Deconvolution techniques are employed within the system to produce an equivalent to the conceptual "step response" at the receiver.

#### System Sampling

The UTEM receiver measures the time variation of the magnetic field in the direction of the receiver coil at 10 delay times (channels). UTEM channels are spaced in a binary, geometric progression across each half-cycle of the received waveform. Channel 10 is the earliest channel and it is  $1/2^{10}$  of the half-cycle wide. Channel 1, the latest channel, is  $1/2^{1}$  of the half-cycle wide (see Figure below). The measurements obtained for each of 10 channels are accumulated over many half-cycles. Each final channel value, as stored, is the average of the measurements for that time channel. The number of half-cycles averaged generally ranges between 2048 (1024 full-cycles - 1K in UTEM jargon) to 32768 (16K) depending on the level of ambient noise and the signal strength.



#### System Configurations

For surface work the receiver coil is mounted on a portable tripod and oriented. During a surface UTEM survey the vertical component of the magnetic field (Hz) of the transmitter loop is always measured. Horizontal inline (Hx) and cross-line (Hy) components are also measured if more detailed information is required. The UTEM System is also capable of measuring the two horizontal components of the electric field, Ex and Ey. A dipole sensor comprised of two electrodes is used to measure the electric field components. This is generally used for outlining resistive features to which the magnetic field is not very sensitive.

BHUTEM surveys employ a receiver coil that is smaller in diameter than the surface coil. The borehole receiver coil forms part of a down-hole receiver package used to measure the axial (along-borehole) component of the magnetic field of the transmitter loop. Due to the distance between coil and receiver in borehole surveys the signal must be transmitted up to the receiver. In BHUTEM the signal is transmitted to surface digitally using a kevlar-reinforced fibre-optic cable as a data link. Using a fibre-optic link avoids signal degradation problems and allows surveying of boreholes to 3000+m. The cable is also very light - the specific gravity is nearly 1.0 - making the cable handling hardware quite portable.

#### The EM Induction Process

Any time-varying transmitted ("primary") field induces current flow in conductive regions of the ground below and around the transmitter loop (i.e. in the earth or "half-space"). This current flow produces a measurable EM field, the secondary field, which has an inherent "inertia" that resists the change in primary field direction. This "inertial" effect is called self-inductance; it limits the rate at which current can change and is only dependent on the shape and size of a conductive path.

It takes a certain amount of time for the transmitted current flow to be redirected (reversed) and reestablished to full amplitude after the rate-of-change of the primary field reverses direction. This measurable reversal time is characteristic for a given conductor. In general, for a good conductor this time is greater than that of a poor conductor. This is because in a good conductor the terminal current level is greater, whereas its rate of change is limited by the inductance of the current path. The time-varying current causes an Emf in the sensor proportional to the time derivative of the current. This Emf decays with time - it vanishes when the reversal is complete - and the characteristic time of the Emf decay as measured by the sensor is referred to as the **decay time** of the conductor.

The large-scale current which is induced in the half-space by the primary field produces the half-space response as seen in typical UTEM profiles. This background response is influenced by the finite conductivity of the surrounding rock. Other currents may be induced in locally more conductive zones (conductors) that have longer decay times than the half-space response. The responses of these conductors are superimposed upon the background response. The result is that the UTEM receiver detects:

- the primary field waveform, a square-wave
- the half-space (background) response of the surrounding rock
- a slight-to-large response due to any conductors present.

The result is that in the presence of conductors the primary field waveform is substantially (and anomalously) distorted.

#### UTEM DATA REDUCTION and PLOTTING CONVENTIONS

The UTEM data as it appears in the data files is in total field, continuously normalized form. In this form, the magnetic field data collected by the receiver is expressed as a % of the calculated primary magnetic field vector magnitude at the station. These are total field values - the UTEM system measures during the "on-time" and as such samples both the primary and secondary fields.

For plotting purposes, the reduced magnetic field data (as it appears in the data file) are transformed to other formats as required. The following is provided as a description of the various plotting formats used for the display of UTEM data. A plotting format is defined by the choice of the *normalization* and *field type* parameters selected for display.

#### **NORMALIZATION**

UTEM results are always expressed as a % of a normalizing field at some point in space.

In **continuously normalized** form the normalizing factor (the denominator) is the magnitude of the computed local primary field vector. As the primary exciting field magnitude diminishes with increasing distance from the transmitter loop the response is continuously amplified as a function of offset from the loop. Although this type of normalization considerably distorts the response shape, it permits anomalies to be easily identified at a wide range of distances from the loop.

Note: An optional form of continuous normalization permits the interpreter to normalize the response to the magnitude of the primary field vector at a fixed depth below each station. This is useful for surface profiles which come very close to the loop. Without this adjustment option, the normalizing field is so strong near the loop that the secondary effects become too small in the presence of such a large primary component. In such circumstances interpretation is difficult, however; by "normalizing at some depth" the size of the normalizing field, near the loop in particular, is reduced and the resulting profile can be more effectively interpreted to a very close distance from the transmitter wire. The usual choice for the depth is the estimated target depth is used.

In **point normalized form** the normalizing factor is the magnitude of the computed primary field vector at a single point in space. When data is presented in this form, the point of normalization is displayed in the title block of the plot. Point normalized profiles show the non-distorted shape of the field profiles. Unfortunately, the very large range in magnitude of anomalies both near and far from the loop means that small anomalies, particularly those far from the loop, may be overlooked on this type of plot in favor of presenting larger amplitude anomalies.

Note: Selecting the correct plot scales is critical to the recognition of conductors over the entire length of a point normalized profile. Point normalized data is often used for interpretation where an analysis of the shape of a specific anomaly is required. Point normalized profiles are therefore plotted selectively as required during interpretation. An exception to this procedure occurs where surface data has been collected entirely inside a transmitter loop. The primary field does not vary greatly inside the loop, therefore, the benefits of continuous normalization are not required in the display of such results. In these cases data is often point normalized to a fixed point near the loop centre.

#### **FIELD TYPE**

The type of field may be either the **Total field** or the **Secondary field**. In general, it is the secondary field that is most useful for the recognition and interpretation of discrete conductors.

### **UTEM Results as Secondary Fields**

Because the UTEM system measures during the transmitter on-time the determination of the secondary field requires that an estimate of the primary signal be subtracted from the observations. Two estimates of the primary signal are available:

#### 1) UTEM Channel 1

One estimate of the primary signal is the value of the latest time channel observed by the UTEM System, channel 1. When Channel 1 is subtracted from the UTEM data the resulting data display is termed *Channel 1 Reduced*. This reduction formula is used in situations where it can be assumed that all responses from any target bodies have decayed away by the latest time channel sampled. The Channel 1 value is then a reasonable estimate of the primary signal present during Channels 2....10.

In practice the *Channel 1 Reduced* form is most useful when the secondary response is very small at the latest delay time. In these cases channel 1 is indeed a good estimate of the primary field and using it avoids problems due to geometric errors or transmitter loop current/system sensitivity errors.

# 2) Calculated primary field

An alternate estimate of the primary field is obtained by computing the primary field from the known locations of the transmitter loop and the receiver stations. When the computed primary field is subtracted from the UTEM data the resulting data display is termed *Primary Field Reduced*.

The calculated primary field will be in error if the geometry is in error mislocation of the survey stations or the loop vertices - or if the transmitter loop current/system sensitivity is in error. Mislocation errors from loop/station geometry may give rise to very large secondary field errors depending on the accuracy of the loop and station location method used. Transmitter loop current/system sensitivity error is rarely greater than 2%. Primary Field Reduced is plotted in situations where a large Channel 1 response is observed. In this case the assumption that the Channel 1 value is a reasonable estimate of the primary field effect is not valid.

Note: When UTEM data is plotted in the *Channel 1 Reduced* form the secondary field data for Channel 1 itself are always presented in *Primary Field Reduced* form and are plotted on a separate axis. This plotting format serves to show any long time-constant responses, magnetostatic anomalies and/or geometric errors present in the data.

#### Mathematical Formulations

In the following expressions:

Rn; is the result plotted for the n<sup>th</sup> UTEM channel,

R1i is the result plotted for the latest-time UTEM channel, channel 1,

Chn; is the raw component sensor value for the nth channel at station j,

Ch1; is the raw component sensor value for channel 1 at station j,

 $H^{\mathbf{p}}_{\mathbf{j}}$  is the computed primary field component in the sensor direction

 $|H^{\mathbf{P}}|$  is the magnitude of the computed primary field at:

- a fixed station for the entire line (point normalized data)

- the local station of observation (continuously normalized data)

- a fixed depth below the station (continuously normalized at a depth).

**Channel 1 Reduced Secondary Fields**: Here, the latest time channel, Channel 1 is used as an "estimate" of the primary signal and channels 2-10 are expressed as:

$$Rn_j = (Chn_j - Ch1_j) / |H^P| x 100\%$$

Channel 1 itself is reduced by subtracting a calculation of the primary field observed in the direction of the coil,  $H^{\mathbf{p}}$  as follows:

$$R1_j = (Ch1_j - H^P_j) / |H^P| x 100\%$$

**Primary Field Reduced Secondary Fields:** In this form all channels are reduced according to the equation used for channel 1 above:

$$Rn_j = (Chn_j - H^P_j) / |H^P| \times 100\%$$

This type of reduction is most often used in cases where very good geometric control is available (leading to low error in the calculated primary field,  $\mathbf{H}^{\mathbf{P}_{\mathbf{j}}}$ ) and where very slowly decaying responses result in significant secondary field effects remaining in channel 1 observations.

#### UTEM Results as a Total Field

In certain cases results are presented as a % of the **Total Field**. This display is particularly useful, in borehole surveys where the probe may actually pass through a very good conductor. In these cases the shielding effect of the conductor will cause the observed (total) field to become very small below the intersection point. This nullification due to shielding effects on the total field is much easier to see on a separate *Total Field* plot. In cases where the amplitude of the anomalies relative to the primary field is small, suggesting the presence of poorly conductive bodies, the *Total Field* plot is less useful.

The data contained in the UTEM reduced data files is in *Total Field*, continuously normalized form if:

$$Rn_j = Chn_j / |H^P| \times 100\%$$

#### **DATA PRESENTATION**

All UTEM survey results are presented as profiles in an Appendix of this report. For BHUTEM surveys the requisite Vectorplots, presented as plan and section views showing the direction and magnitude of the calculated primary field vectors for each transmitter loop, are presented in a separate Appendix.

The symbols used to identify the channels on all plots as well as the mean delay time for each channel is shown in the table below.

<u>UTEM System Mean Delay Times</u> 10 Channel Mode @ 31 hz.(approx.)		
(base freq:	30.974	hertz )
Channel #	Delay time (ms)	Plot Symbol
1	12.11	
2	6.053	
3	3.027	
4	1.513	
5	0.757	
6	0.378	∑ ∠ 7 ×
7	0.189	7
8	0.095	Ý
9	0.047	Â
10	0.024	Δ
		~

# Notes on Standard plotting formats:

<u>10 channel data in *Channel 1 Reduced* form</u> - The data are usually displayed on three separate axes. This permits scale expansion, allowing for accurate determination of signal decay rates. The standard configuration is:

Bottom axis - Channel 1 (latest time) is plotted alone in *Primary Field Reduced* form using the same scale as the center axis.

Center axis - The intermediate to late time channels, ch5 to ch2 are plotted on the center axis using a suitable scale.

Top axis - The early time channels, ch10 to ch6 and a repeat of ch5 for comparison are plotted on the top axis at a reduced scale. The earliest channels, ch8 to ch10, may not be plotted to avoid clutter.

10 channel data in Primary Field Reduced form: The data are displayed using a

single axis plot format. Secondary effects are plotted using a Y axis on each data plot with peak to peak values up to 200%.

BHUTEM data plotted as total field profiles: Data are expressed directly as a percentage of the *Total Field* value. The Y axis on each single axis data plot shows peak values of up to 100%. These departures are always relative to the measured total field value at the observation station.

BHUTEM data plotted as secondary field profiles: Check the title block of the plot to determine if the data is in *Channel 1 Reduced* form or in *Primary Field Reduced* form.

Note that on all BHUTEM plots the ratio between the axial component of the primary field of the loop and the magnitude of the total primary field strength (dc) is plotted as a profile without symbols. In UTEM jargon this is referred to as the "primary field" and it is plotted for use as a polarity reference tool.

# Appendix D

Note on sources of anomalous Ch1

#### Note on sources of anomalous Ch1

This section outlines the possible sources of anomalous channel 1 which is not correlated to the Ch2-10 data plotted on the upper axes of a *channel 1 normalized* plot.

1) Mislocation of the transmitter loop and/or survey stations

Mislocating the transmitter loop and/or the survey stations results in an error in the calculated primary field at the station and appears as an anomalous Ch1 value not correlated to *channel 1 normalized* Ch2-10. The effect is amplified near the loop front. This can be seen in the profiles - the error in Ch1 generally increases approaching the loop. As a rule a 1% error in measurement of the distance from the loop will result in, for outside the loop surveys, an error in Ch1 of:

- 1% near the loop front (long-wire field varies as 1/r)

- 3% at a distance from the loop front (dipolar field varies as  $1/r^3$ )

- 2% at intermediate distances (intermediate field varies as  $\sim 1/r^2$ )

Errors in elevation result in smaller errors but as they often affect the chainage they accumulate along the line.

The in-loop survey configuration generally diminishes geometric error since the field gradients are very low. At the centre of the loop the gradient in the vertical field is essentially zero so it is difficult to introduce geometric anomalies near the loop centre. Near the loop sides and at the closest approach of the lines to the wire mislocation of the loop and the station becomes more critical. Typically loop sides are designed to be >200m from any survey stations.

2) Magnetostatic UTEM responses

Magnetostatic UTEM responses arise over rocks which generate magnetic anomalies. Such magnetic materials will amplify the total (primary + secondary) field of the UTEM transmitter which is sensed by the receiver coil. The secondary field is generated by subtracting a computed primary which does not include magnetic effects. This can give rise to strong and abrupt channel 1 anomalies when the source of the magnetics is at surface. This is the case in a number of places on these grids. UTEM magnetostatic anomalies differ from DC magnetic anomalies in the following three major ways:

1) In the case of DC magnetics the field is dipping N and is very uniform over the scale of the survey area while the UTEM field inside the loop is vertical and it is stronger near the loop edges.

2) Most aeromagnetics are collected as total field while with UTEM we measure a given (in this case generally **z**,**x**) component.

3) DC magnetic instruments observe the total magnetization of the causative body which is due to its susceptibility as well as any remnant magnetization. An AC method such as UTEM will not respond to the remnant portion of the magnetization.

The larger amplitude of the UTEM Ch1 response is explained by the fact that the UTEM primary field is often more favourably coupled (magnetostatically speaking) to

magnetic mineralization as compared to the earths field. Another factor could be the presence of a reverse remnant component to the magnetization. Note that positive magnetic anomalies will cause:

- positive Ch1 anomalies in data collected outside the loop
- negative Ch1 anomalies in data collected inside the loop

#### 3) Extremely good conductors

An extremely good conductor will be characterized by a time constant much longer than the half-period (@ 30Hz >>16ms). This will give rise to an anomalous Ch1 which is not correlated to the Ch2-10 data plotted on the upper axes of a *channel 1 normalized* plot.

# Appendix E

# Note on 4 Hz UTEM data: The effect of the presence of a 60-cycle powerline.

# Note

While this Appendix uses data collected in the presence of a 60Hz powerline the issue dealt with applies equally to UTEM data collected in the presence of a 50Hz powerline.

Note: The standard presentation in Appendix A has Ch2-5 plotted on the middle axis. An alternative presentation - with Ch2 and Ch3 on the middle axis - is sometimes chosen when a powerline cuts through the surveyed area. This Appendix is a brief discussion of why the alternative presentation is chosen.

# Note on 4 Hz UTEM data: The effect of the presence of a 60-cycle powerline.

This appendix outlines and discusses the effect of the presence of a 60-cycle powerline on ~4Hz (3.872Hz) UTEM data. The example data is from Loop 12 Line 280S. This line is from a series of loops with a powerline cutting across the survey area. The Loop 12 Line 280S UTEM data is affected by the presence of the powerline.

#### example data:

Figure E1(a) is the example data as presented in Appendix A - an alternative presentation with Ch2 and Ch3 on the middle axis. The standard presentation is shown in Figure E1(b) - with Ch2-5 plotted on the middle axis. The alternative presentation was chosen for a series of loops (including this loop) with a powerline cutting through the surveyed area. Figure E1(c) shows why - Ch4 and Ch5 show a pattern where when one is up the other is down and vice versa. The amplitude of the pattern decreases with distance away from the powerline. It was felt that this pattern obscured the information in Ch2 and 3 and the alternative presentation was chosen.

#### explanation:

Figure E2a) shows the UTEM waveform at ~4Hz with a 60Hz waveform superimposed on it. Roughly 16 cycles of the 60-cycle waveform fit into the full UTEM waveform. On a channel-by-channel basis:

~4 cycles fit into Ch1

~2 cycles fit into Ch2

~1 cycle fits into Ch3.

The multiple cycles tend to cancel out. Earlier channels are narrower - only part of a cycle wide. In particular Ch4 is ~half a cycle wide and Ch5 falls in the opposite halfcycle. The result is the pattern shown in Figure 1(c): Ch4 and Ch5 tending to diverge from one another - more strongly near the powerline.

# other presentations:

Figures E3(a) and (b) show the example data in two other presentations where several channels are combined to give fewer, cleaner channels:

Figure E3(a): In this presentation Ch4 and 5 are combined to give a combined Ch"4" that is ~1.5 times as wide as the original Ch4. The Ch"4" is cleaner than the original. The original Ch5-10 are shown on the upper axis.

Figure E3(b): In this presentation Ch4-10 are combined to give a combined Ch"4" that is 2x as wide as the original Ch4 (equal in width to the original Ch3). The Ch"4" is as clean as the original Ch3. Note that Ch10 is added in twice to make the 2x factor exact. The original Ch5-10 are shown on the upper axis.

#### Discussion:

Several elements of UTEM survey design and procedure will have an affect on the number of useful channels in the final data set. These would include:

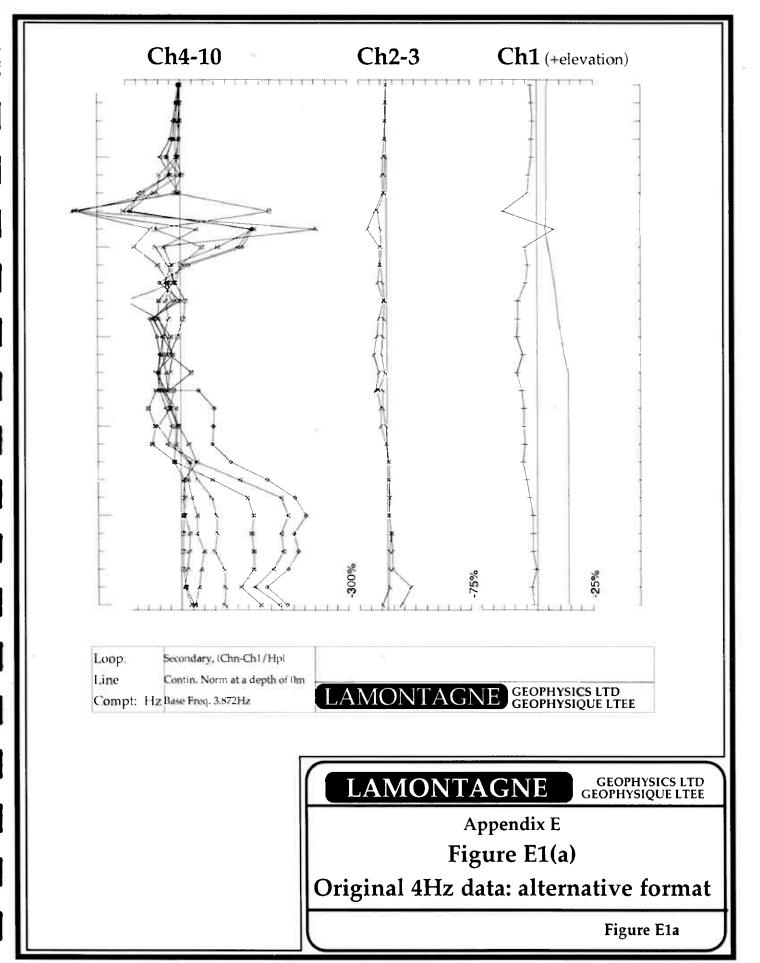
- careful positioning of the transmitter loops relative to the powerline(s)
- increasing the transmitter current (and the signal-to-noise ratio)
- care in the selection of gains during surveying. Near a source of coherent noise (eg powerline) the signal gain should be selected to minimize data rejections.

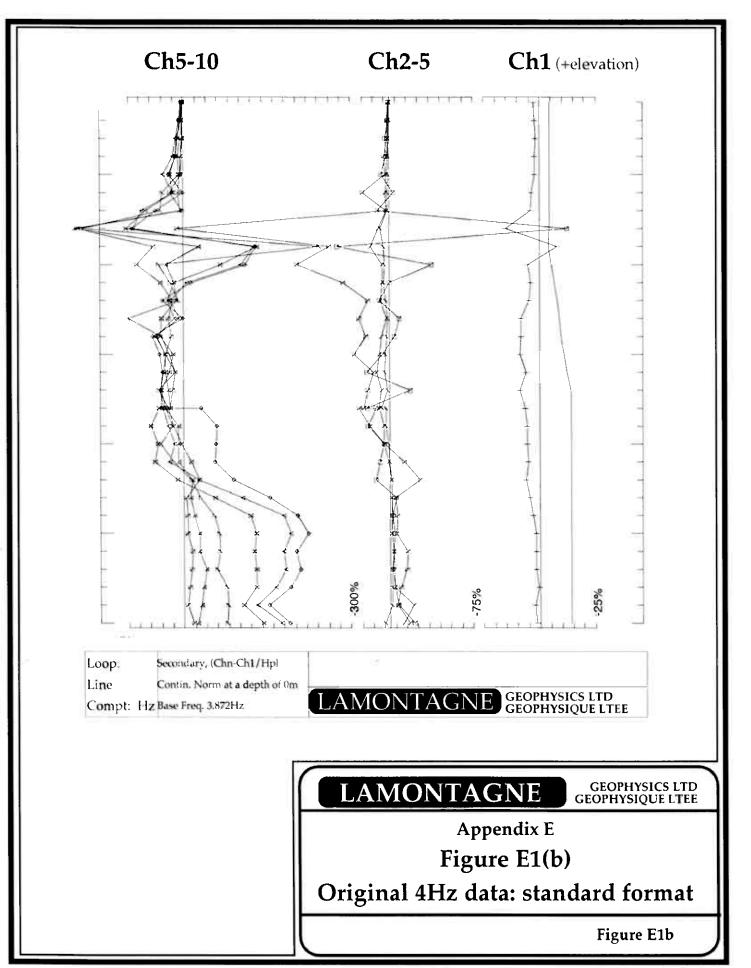
Consideration should also be given to increasing the station spacing in the vicinity of the powerline. This allows additional stacking to be done (at fewer stations) without much of an increase in surveying time.

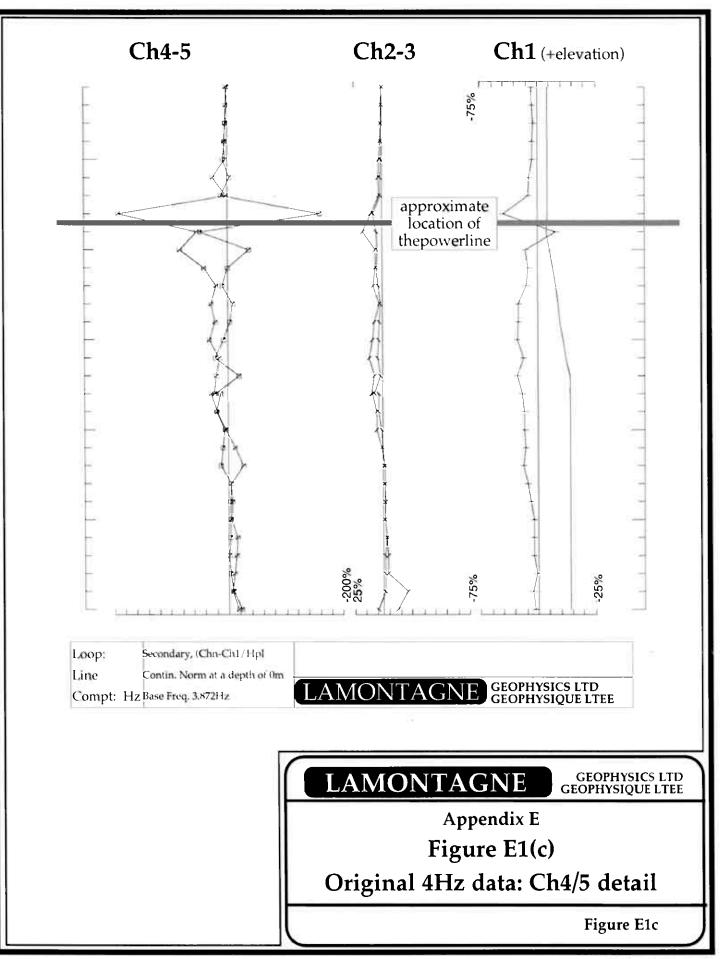
Several other ways to increase the number of channels free of the powerline affects are:

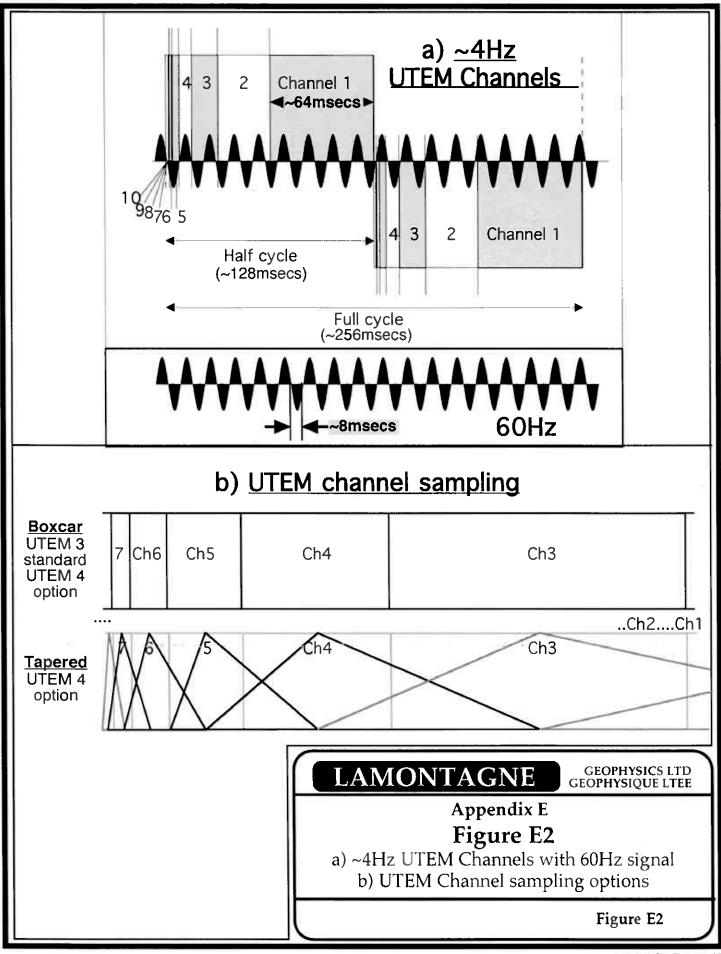
- <u>lowering the frequency</u>: each factor of two lower in frequency would add a channel relatively free of the affects of the powerline. The cost would be increased stacking time at each station.
- <u>taking multiple readings</u>: each reading starts at a different (random) point on the 60-cycle waveform. The sum of several readings will tend to better average out any affect.
- <u>alternative channel sampling</u>: Figure E2b) shows the standard UTEM 3 Boxcar channel sampling. An alternative tapered channel sampling is available (and often used) with UTEM 4. In this case if tapered sampling had been available it would likely have been used. The result would have been:
  - a slightly noisier Ch3
  - a considerably improved Ch4
  - an improved Ch5

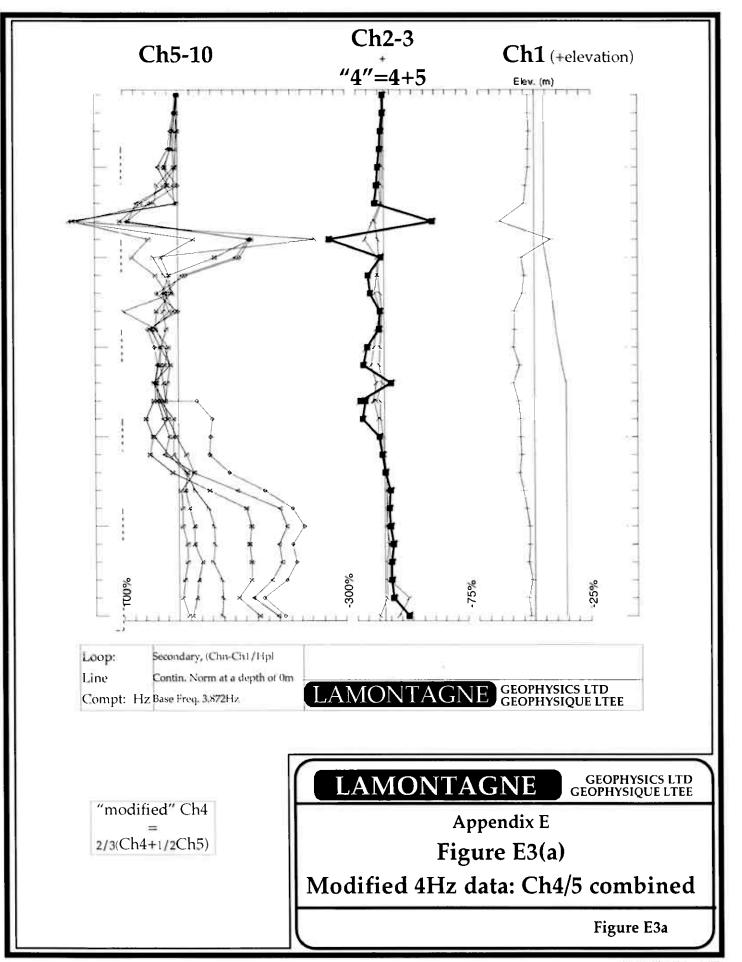
The choice of which sampling to use on a UTEM 4 survey depends on the frequency of the survey, the proximity and the frequency of any local powerline and the type of decay seen.

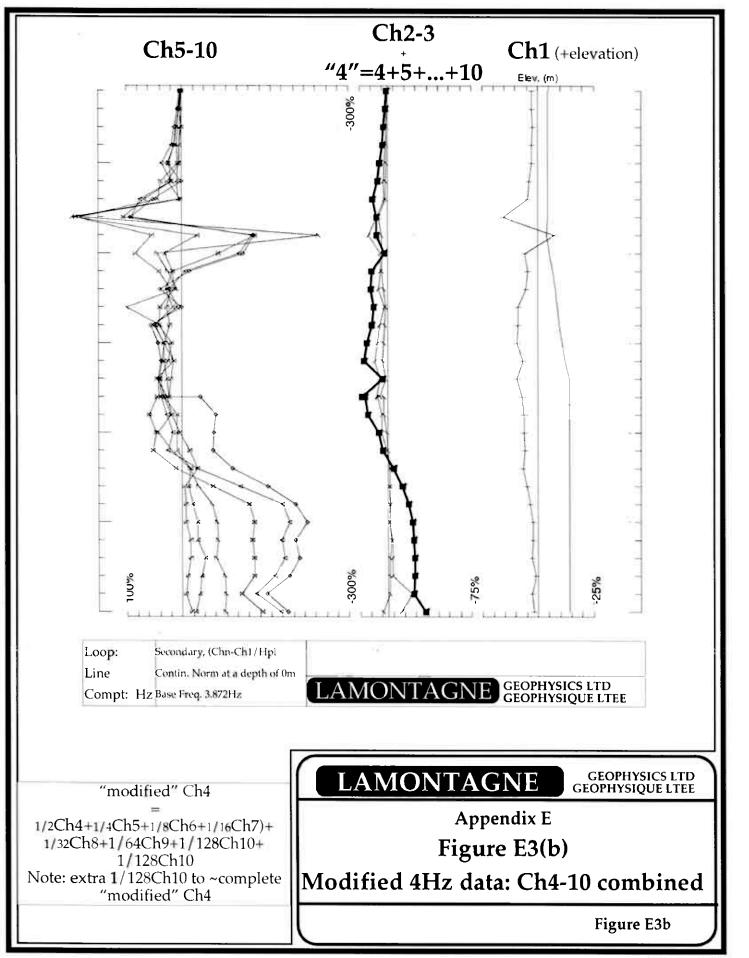












#### APPENDIX D

### In-house UTEM Maxwell Modeling

Vakkerlien Project, Hedemark Province, Norway

Anthony Watts, Falconbridge Ltd for Sulfidmalm A/S

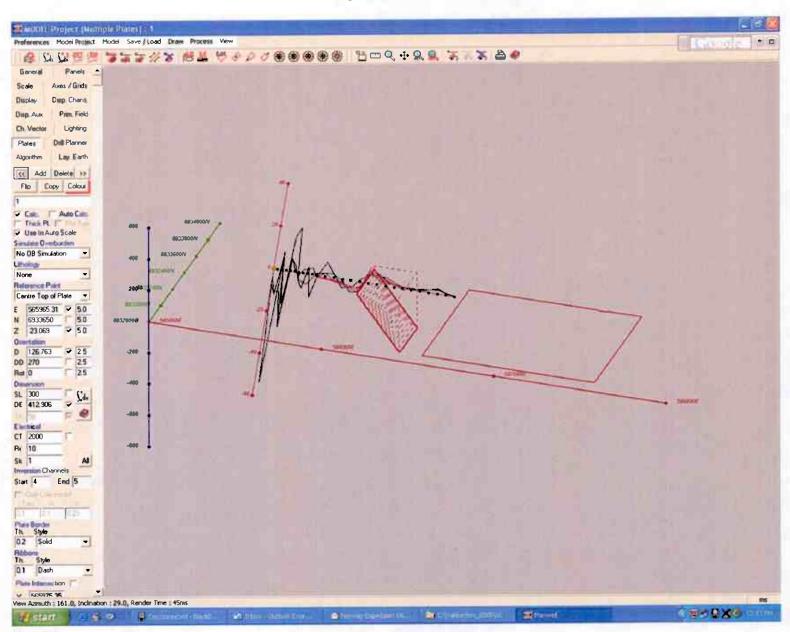
Model 1: Loop 1, L336N - Isometric View

Model 2: Loop 1, L336N - Plan View

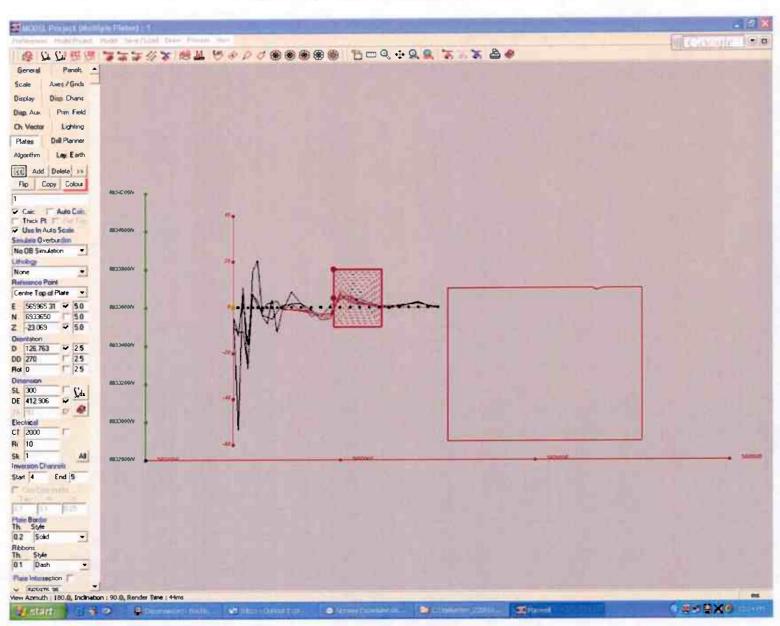
Model 3: Loop 1, L336N – Sectional View Looking North

Model 4: Loop 1, L336N - Longitudinal View

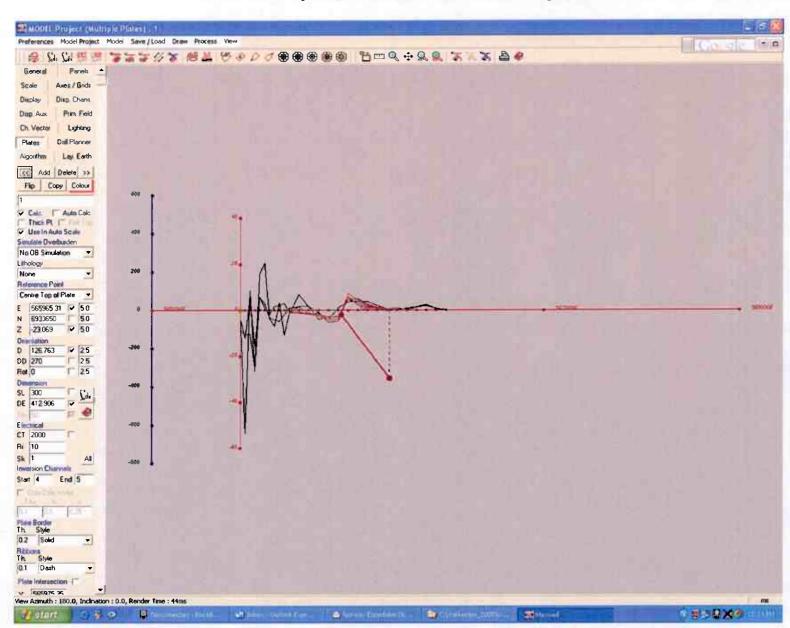
Model 1: Loop 1, L336N - Isometric View



Model 2: Loop 1, L336N – Plan View



Model 3: Loop 1, L336N – Sectional View Looking North



Model 4: Loop 1, L336N – Longitudinal View

